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Radio polarization maps of shell-type SNRs – II. Sedov models with evolution of turbulent magnetic field

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ABSTRACT

Polarized radio emission has been mapped with great detail in several Galactic supernova remnants (SNRs), but has not yet been exploited to the extent it deserves. We have developed a method to model maps of the Stokes parameters for shell-like SNRs during their Sedov evolution phase. At first, three-dimensional structure of an SNR has been computed, by modelling the distribution of the magnetohydrodynamic parameters and of the accelerated particles. The generation and dissipation of the turbulent component of magnetic field everywhere in SNR are also considered taking into account its interaction with accelerated particles. Then, in order to model the emission, we have used a generalization of the classical synchrotron theory, valid for the case in which the magnetic field has ordered and disordered components. Finally, two-dimensional projected maps have been derived, for different orientations of SNR and of interstellar magnetic field with respect to the observer. An important effect to consider is the Faraday rotation of the polarization planes inside the SNR interior. In this paper, we present details of the model, and describe general properties of the images.

Key words: acceleration of particles – radiation mechanisms: non-thermal – shock waves – cosmic rays – ISM: supernova remnants.

1 INTRODUCTION

Supernova remnants (SNRs) are very important objects for high-energy astrophysics. They provide experimental information, in particular, on the processes related to magnetic turbulence, cosmic rays (CRs), their interactions and influence on the fluid dynamics and the shock properties. Interstellar magnetic field (ISMF, of the order of few μG) considerably affects the propagation of all CRs with energies $\leq 3 \times 10^{15}$ eV deviating them from their original directions. Therefore, the only possibility to study these cosmic accelerators individually is to consider different kinds of emission resulted from interactions of accelerated particles with magnetic fields (MFs), with photons or with other particles.

SNRs are observed in all electromagnetic domains, from radio waves to TeV gamma-rays. There is a wealth of information produced by many experiments but only a fraction of it has been exploited.

Fluxes and spectra, both integrated and spatially resolved, are widely used. In some cases, fine details of the SNR surface brightness distribution have been deeply investigated. For instance, the

radial thickness of the X-ray SNR rim is associated with the strength of the MF behind the shock front (Vink & Laming 2003) if the dominant factor of the fading process is the density decrease and the energy downgrading (and/or diffusion) of the emitting particles (Berezhko, Ksenofontov & Völk 2003; Berezhko & Völk 2004; Bamba et al. 2005; Völk, Berezhko & Ksenofontov 2005; Warren et al. 2005). Alternatively, it may indicate the length-scale of the MF damping downstream (Pohl, Yan & Lazarian 2005; Ressler et al. 2014; Pohl, Wilhelm & Telezhinsky 2015; Tran et al. 2015). Additional constraints on models come from the energy dependence of the rim thickness (Ressler et al. 2014). The presence (or absence) of the X-ray emission in the precursor gives hints on the particle acceleration properties (Long et al. 2003; Morlino et al. 2010; Winkler et al. 2014). The azimuthal variation of the radio brightness depends on the obliquity dependence of the injection efficiency (Fulbright & Reynolds 1990; Petruk et al. 2009a) while the X-ray azimuthal profile might help in determining whether the maximum particle momentum is time or loss limited (Petruk et al. 2011a). High spatial resolution observations may reveal the distance between the shock and the contact discontinuity (e.g. Miceli et al. 2009). A considerably reduced distance can be effect of particle acceleration with an efficient backreaction on the flow (Warren et al. 2005) or otherwise of protrusions of ejecta beyond the forward shock (Rakowski et al.

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2011). Similar effects may be due to the ejecta clumping (Orlando et al. 2012). Rapidly varying spots in the SNR shell might be a sign of the presence of either a highly amplified MF and ongoing acceleration (e.g. Uchiyama et al. 2007) or of the plasma waves and steady electron distributions (Bykov, Uvarov & Ellison 2008; Bykov et al. 2009). The ordered stripes observed in Tycho SNR not far from the shell (Eriksen et al. 2011) are a challenge for models of plasma microphysics (Bykov et al. 2011; Malkov, Sagdeev & Diamond 2012; Laming 2015).

In contrast to the widespread analysis of spectra and local spatial characteristics of the non-thermal emission from SNRs in different spectral ranges, the maps of the surface brightness and of the polarized synchrotron emission – which are known for many SNRs – are lacking an adequate analysis. Such situation should be changed by developing new analysis methods. In general, there are two ways to deal with SNR images: to analyse observed maps with minimal assumptions or to model maps starting from basic theoretical principles.

Using the properties of the emission processes and the observed maps in different bands, it is possible, for example, to separate the thermal and non-thermal X-ray images out of the mixed observed one (Miceli et al. 2009), to predict a gamma-ray image of SNR (Petruk et al. 2009c) or to determine the MF strength in the limbs of SNR (Petruk, Kuzyo & Bocchino 2012).

As to the latter strategy to explore SNR images, a method to model the synchrotron radio and X-ray images of Sedov SNRs (that is the shell-like adiabatic remnant of a spherical explosion in a uniform medium) was developed by Fulbright & Reynolds (1990) and Reynolds (1998), who also analysed the main features of these maps. The method was adapted to the gamma-ray SNR images due to the inverse-Compton emission (Petruk et al. 2009b, 2011b) and to those due to the hadronic interactions with protons inside SNR (Beshley & Petruk 2012). The method was generalized to the case of an SNR evolving in an interstellar medium (ISM) with non-uniform distributions of density and/or MF: the resulting asymmetries on the radio maps have been studied by Orlando et al. (2007) and in X-rays and gamma-rays by Orlando et al. (2011).

The SNR morphologies shown by their maps have the potential for understanding the plasma microphysics (Reynolds 2004) and determining the properties of the SNR and its environment. In particular, they allow for determination of the three-dimensional orientation of ISMF and even its gradient around SN 1006 (Petruk et al. 2009a; Bocchino et al. 2011) or, by analysing a sample of SNRs, to reveal properties of the Galactic MF (West et al. 2016). By modelling the surface brightness maps, it was shown that a certain class of SNRs, namely the thermal X-ray composites (or mixed-morphology SNRs, i.e. remnants with a thermal X-ray peak within the radio shell), might be explained as a projection effect of SNR evolving in essentially non-uniform environment (Petruk 2001).

The work of Bandiera & Petruk (2016, hereafter *Paper I*) and the present paper continue a series of papers devoted to development of methods to model SNR images. Namely, we are interested in maps of the surface distribution of the polarized radio emission that could also be important to test theories. It is known that random MF generally reduces the polarization of the synchrotron emitting sources (e.g. Stroman & Pohl 2009), but it is able also to produce stochastic small-scale patchy structures, like spots and filaments, with high polarization fraction in synchrotron X-rays (Bykov et al. 2008; Bykov et al. 2009). Recently, Schneiter et al. (2015) have considered a task to simulate polarization images of SNR as a whole under two simplifications: the authors neglected the turbulent

component of MF and assumed the (variable) Faraday effect in the SNR interior to be minor comparing to the (uniform) Faraday rotation of the polarization planes outside. In our model, we consider both these components and demonstrate that they might essentially modify polarization images comparing to the cases with vanishing turbulent MF and internal Faraday rotation.

With *Paper I*, we have essentially reached two main achievements. First, we have developed a method to evaluate the synchrotron polarized emission in the case in which the MF is the composition of a uniform plus a random component, and we have computed exact analytic formulae for all Stokes parameters in some particular cases, the most useful probably being that of a power-law particle energy distribution and a Gaussian isotropic MF random component: the resulting formulae show strong similarities with those for the classical case (i.e. of a homogeneous MF), and are in fact a generalization of them. Then, using a thin-shell approximation, we have simulated the observed maps of the total radio intensity and of the Stokes parameters for a wide number of cases. In spite of the simplification used, we have been able to tackle in detail a number of effects, like for instance the effectiveness of the internal Faraday rotation in distorting the polarization pattern as well as in affecting the observed polarization fraction, and the partial depolarization also due to projection effects and to the random MF component. Another advantage of that approach is that it is computationally rather light.

In the present paper, we present instead a more detailed model; namely, we consider the distribution of polarized synchrotron emission not only in the thin shell but everywhere inside a shell-like SNR. In this way, more reliable maps can be obtained, which may be used in particular to test various effects as well as to verify how accurate the simplified models of *Paper I* can be, under typical conditions.

2 POLARIZATION IN ADIABATIC SNR

In the present paper, aimed at modelling the radio emission from shell-type SNRs, we have improved the treatment presented in *Paper I*, by implementing a detailed and self-consistent treatment of SNRs in the adiabatic regime, valid for objects old enough to have swept up from the ambient medium a mass much larger than the original mass of the supernova ejecta, but that are still evolving adiabatically, i.e. the radiative losses and the backreaction of accelerated particles are inefficient (in fact, the SNR statistics is consistent with their radio emission to be strongly reduced about the end of the adiabatic phase; Bandiera & Petruk 2010). The approach we present here (Sections 2.2, 2.3, 2.4, 3) is general, in the sense that it may be used with the numerical 3D magnetohydrodynamic (MHD) simulations of an adiabatic remnant of an asymmetric supernova explosion in a medium with non-uniform distributions of density and/or MF. However, in order to simplify the analysis, to make conclusions clearer and to have a basic reference model, in the present paper, we apply our model to the so-called Sedov SNR, i.e. the remnant of a spherical point-like explosion in the uniform medium (Section 2.1). Polarization maps of SNRs from fully numerical 3D MHD simulations with asymmetric ejecta and/or expansion in a non-uniform environment are in preparation.

2.1 MHD and relativistic electrons in Sedov SNRs

Before calculations of the polarization maps, one has to simulate the 3D MHD structure of an SNR.

In the simulations reported in the present paper, we assume a strong unmodified shock (with $\gamma = 5/3$), adiabatically expanding in a uniform medium, after a spherical point-like explosion. This problem admits an analytic solution (Sedov 1959), which is self-similar: namely, the spatial and temporal variation of parameters inside the SNR, for example the flow velocity $u(r, t)$, can be written in the form

$$u(r, t) = u_s(t) \bar{u}(\bar{r}), \quad \bar{r} = r/R(t), \quad (1)$$

where the index ‘s’ corresponds to the immediately post-shock position and the profile $\bar{u}(\bar{r})$ does not explicitly depend on time. In other words, it is sufficient to calculate once the normalized profile $\bar{u}(\bar{r})$, to obtain (just by scaling) the profile at any given time. The scaling properties of the Sedov solution reduce the number of free parameters in simulations and reveal how the supernova and the environment characteristics combine.¹ Accurate approximations of the Sedov solution have been proposed for calculations, either in the Eulerian coordinate r (Cox & Franko 1981) or in the Lagrangian coordinate a (section 4.5 in Petruk 2000).²

The model assumes that the MF is a composition of an ordered (B) and a disordered (δB) component. The distribution of B inside the SNR may be calculated following Chevalier (1974): the MF in each point may be treated as the sum of a radial and a tangential component, which evolve in different ways (for detailed references and expressions, see section 2.2 in Petruk, Kuzyo & Beshley 2016). In a Sedov SNR, like for the other hydrodynamic parameters, also the spatial profiles of these two quantities might be expressed with self-similar functions of the normalized coordinates $\bar{r}$ or $\bar{a} = a/R$. The MF experiences a compression at the shock, with the compression factor $\sigma_B = B_s/B_o$ that depends on the shock obliquity angle Θ_o (the angle between the ambient MF and the shock normal) according to the law:

$$\sigma_B = (\cos^2 \Theta_o + \sigma^2 \sin^2 \Theta_o)^{1/2}, \quad (2)$$

where the index ‘o’ refers to the pre-shock position, and $\sigma = \rho_s/\rho_o$ is the (density) shock compression factor. Consistently with our assumptions, we will use $\sigma = 4$ in our calculations. Therefore, σ_B runs from 1, for a parallel shock ($\Theta_o = 0^\circ$), to 4, for a perpendicular shock ($\Theta_o = 90^\circ$). Instead, the model for evolution of the disordered MF component will be presented in Section 3.

In order to synthesize the SNR synchrotron maps, one has to know also the spectral and spatial distributions of relativistic electrons. We assume the power-law spectrum of emitting particles with the index $s = 2$ and the injection efficiency (defined as the fraction of accelerated particles) independent of the shock obliquity (unless otherwise stated). The evolution of the relativistic electron population downstream of the shock is also self-similar; we model it following Reynolds (1998); details are presented in Petruk et al. (2011b, appendix A).

¹ The Sedov solution describes the remnant of a point-like explosion and therefore neglects the structure of ejecta that may give some effect in the polarization maps at the early stages of SNR evolution.

² The Lagrangian approach is useful if one needs to trace the evolution of parameters inside a given fluid parcel. r is the common spatial coordinate, while a is like a number attached to a fluid element. It is defined as the radial coordinate of the element before the shock crosses this element and remains unchanged later, i.e. $a \equiv R(t_i)$, where t_i is the time when the fluid element a was shocked. There is a possibility to convert a to r if one knows the hydrodynamical structure downstream. Such conversion is a way to find a spatial distribution of parameters.

2.2 Polarized emission

Once the distributions of MF and emitting particles have been evaluated for all locations within the SNR, we can compute the local Stokes parameters, $\mathcal{I}$, $\mathcal{Q}$ and $\mathcal{U}$, which contain full information on the (linearly) polarized synchrotron emission per unit path, while $\mathcal{V}$, the parameter associated with circular polarization, vanishes. We can then integrate them along the line of sight, to get the observed Stokes parameters.

For a general orientation x - y of the projected axes (z is the line-of-sight coordinate with the positive direction towards the observer), the standard formulae give $\mathcal{Q} = \langle E_x E_x^* \rangle - \langle E_y E_y^* \rangle$ and $\mathcal{U} = \langle E_x E_y^* \rangle + \langle E_y E_x^* \rangle$. If we choose the special orientation (x' - y'), such that the E' vector is directed towards the unit vector $\hat{x}'$ (namely the B' vector is directed towards the unit vector $\hat{y}'$), we readily derive $\mathcal{Q}' \geq 0$ and $\mathcal{U}' = 0$.

Let $P_\perp$ and $P_\parallel$ be, respectively, the synchrotron power per unit frequency ν polarized perpendicular and parallel to the projected MF direction, then $\mathcal{I}' = (P_\perp + P_\parallel)/4\pi$ and $\mathcal{Q}' = (P_\perp - P_\parallel)/4\pi$. For an arbitrary orientation, the Stokes parameters can be derived using the standard rotation laws:

$$\begin{cases} \mathcal{I} = \mathcal{I}' \\ \mathcal{Q} = \mathcal{Q}' \cos 2\chi - \mathcal{U}' \sin 2\chi = \mathcal{Q}' \cos 2\chi \\ \mathcal{U} = \mathcal{Q}' \sin 2\chi + \mathcal{U}' \cos 2\chi = \mathcal{Q}' \sin 2\chi \\ \mathcal{V} = \mathcal{V}' = 0 \end{cases}, \quad (3)$$

where χ is an angle between the x -axis and the local polarization measured anticlockwise, from the observer point of view. This is the same as an angle between the y and the local vector $\mathbf{B}_{xy}$ (a component of the ordered MF $\mathbf{B}$ in the plane orthogonal to the line of sight³).

In terms of the components B_x and B_y of the ordered projected MF, we get $\cos \chi = B_y/B_{xy}$, $\sin \chi = -B_x/B_{xy}$, where $B_{xy}^2 = B_x^2 + B_y^2$ (see Appendix A). Therefore,

$$\begin{cases} \cos 2\chi = \frac{B_y^2 - B_x^2}{B_x^2 + B_y^2}, \\ \sin 2\chi = -\frac{2B_x B_y}{B_x^2 + B_y^2}. \end{cases} \quad (4)$$

Before integrating the Stokes local values along the line of sight, to obtain observed Stokes parameters, we must account also for the rotation of the polarization plane inside the SNR due to Faraday effect (called ‘internal Faraday rotation’ throughout this paper):

$$\beta(l, z_1) = \text{RM}(l, z_1) \lambda^2, \quad (5)$$

where β is the angle of rotation of the polarization plane during propagation from the emission site l inside the SNR to z_1 , namely where the line of sight crosses the edge of the SNR near to the observer (see Fig. 1), measured in the same direction as χ (i.e. anticlockwise from the observer point of view); λ is the wavelength of emission, and $\text{RM}(l, z_1)$ is the rotation measure, defined as

$$\text{RM}(l, z_1) = \frac{e^3}{2\pi m_e^2 c^4} \int_l^{z_1} n_e B_z dz. \quad (6)$$

³ In the present paper, χ is the rotation angle of the MF vector while in Paper I it was the rotation angle of the coordinate system. The sign in this definition is opposite to that in Paper I, and now gives an orientation consistent with the angle β , for the Faraday rotation. It also applies to equation (7), cf. equations 10 and 69 in Paper I (see Fig. 1). On the other hand, this change of definition does not affect the results.

2.4 Stokes parameters. Ordered plus disordered MF

If a model considers the only ordered MF, then it results in the high fraction of the polarized emission. Observations reveal rather small Π in SNRs, around 15 per cent. Therefore, a model of polarized synchrotron emission should also include the disordered component of MF inside SNR.

At this point, we face the two problems.

First, the classic theory of synchrotron emission is developed for MF that is uniform on the length-scale much greater than the gyroradius of the emitting electron; in other words, it may be used with the ordered MF only. Thus, the theory of synchrotron emission should be generalized to the cases when the random MF δB is not negligible comparing to the ordered MF B . We have developed such generalization in [Paper I](#). Namely, if the particles with the power-law momentum distribution emit in MF that has ordered component of the strength B and the random component represented by the spherical Gaussian⁵ with the standard deviation δB , then the Stokes parameters are (for details see section 2.2 in [Paper I](#))

$$\mathcal{I}' = \mathcal{I}'_0 \left\{ 2^{(s+1)/4} \Gamma \left(\frac{s+5}{4} \right) \times \left(\frac{\delta B}{B} \right)^{(s+1)/2} {}_1F_1 \left(-\frac{1+s}{4}, 1, -\frac{1}{2} \left(\frac{\delta B}{B} \right)^{-2} \right) \right\}; \quad (19)$$

$$\mathcal{Q}' = \mathcal{Q}'_0 \left\{ 2^{(s-7)/4} \Gamma \left(\frac{s+9}{4} \right) \times \left(\frac{\delta B}{B} \right)^{(s-3)/2} {}_1F_1 \left(\frac{3-s}{4}, 3, -\frac{1}{2} \left(\frac{\delta B}{B} \right)^{-2} \right) \right\}, \quad (20)$$

where ${}_1F_1(a, b, z)$ is the Kummer confluent hypergeometric function, $\mathcal{I}'_0$ and $\mathcal{Q}'_0$ are respective Stokes parameters for the case of the ordered MF [i.e. given by equations (15) and (16)]. The polarization fraction is

$$\Pi = \Pi_{\max} \left\{ \frac{s+5}{16} \left(\frac{\delta B}{B} \right)^{-2} \times \frac{{}_1F_1((3-s)/4, 3, -(\delta B/B)^{-2}/2)}{{}_1F_1(-(1+s)/4, 1, -(\delta B/B)^{-2}/2)} \right\}. \quad (21)$$

The terms in braces $\{\dots\} \rightarrow 1$ for $\delta B/B \rightarrow 0$ and the results of the classic synchrotron emission theory are recovered for a vanishing random component of MF. Fig. 2 demonstrates the dependence of $\mathcal{I}'$, $\mathcal{Q}'$ and Π on the strength of the disordered MF. Note that $\mathcal{I}'$ increases with $\delta B/B$; this is of importance for fitting of the observed synchrotron spectra. In particular, if one assumes $\delta B/B \sim 1$, then the flux is twice the flux given by the classic synchrotron theory. Similar effect, namely, that the turbulent MF is able to enhance the synchrotron emission, is noticed also by Bykov et al. (2008).

The second problem is that we have to know the value of δB everywhere inside SNR. An approach to model the evolution of the disordered component of MF on the shock and in the SNR interior is one of the main goals of the present paper. It is developed in Section 3 where the equation for the evolution of waves is considered. Solutions of this equation are analysed in Section 4. In our approach,

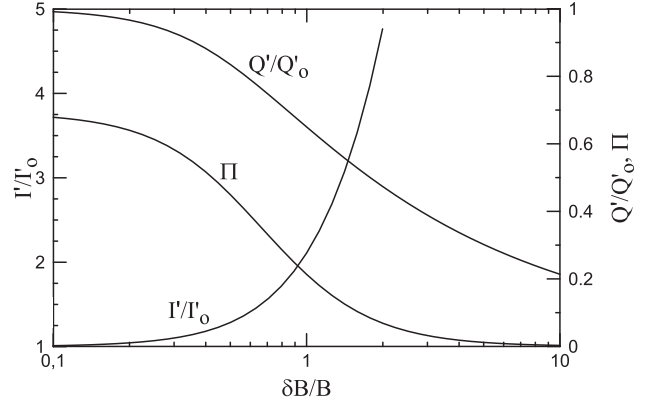


Figure 2. Dependence of the Stokes parameters $\mathcal{I}'/\mathcal{I}'_0$ and $\mathcal{Q}'/\mathcal{Q}'_0$ as well as the polarization fraction Π on the ratio of strengths of the disordered and ordered components of MF $\delta B/B$, for the power-law index of the electron spectrum $s = 2$ (Π is almost insensitive to s ; for the $\mathcal{I}'(s)$, $\mathcal{Q}'(s)$ dependence, see fig. 1 in [Paper I](#)).

the wave properties are related to properties of CRs accelerated on the forward shock and evolved downstream.

Once B and δB are known in each point of SNR, the projected Stokes parameters may be calculated by equation (7) with $\mathcal{I}'$ and $\mathcal{Q}'$ given by equations (19) and (20). Note that in our approach to the synchrotron emission theory (where the random MF is represented by the spherical Gaussian) neither χ (spatial structure of MF) nor β (internal Faraday rotation) is affected by the disordered MF.

Results of simulations of the polarized emission from the Sedov SNR including disordered MF are presented in Section 5.2.

3 MODELLING DISORDERED COMPONENT OF MF IN SNR

One of the basic ingredients needed to calculate detailed synchrotron polarization maps of SNRs is the spatial distribution of the MF disordered component, everywhere inside the SNR. In this section, we present a description of the evolution of this MF component: this treatment is rather general, in the sense that it may be applied to a shock moving in a medium with non-uniform distribution of density and/or MF; however, for the calculation of the numerical models presented in this paper, we will apply it only to the cases of an SNR Sedov expansion. The present treatment is based on the following main assumptions: (i) the disordered MF is essentially the effect of the composition of Alfvén waves and we are limited therefore to small values of the ratio $\delta B/B$; (ii) these waves, as well as the CRs, behave like ‘test particles’, i.e. they are developed atop of an MHD structure, which is unaffected by them; (iii) MHD instabilities are not taken into consideration once we consider the Sedov SNR; (iv) waves and CRs interact with each other through resonant interactions only; (v) the wave damping is described by a non-linear Landau approach.

More sophisticated descriptions of the random MF component are present in the literature (e.g. Bell 2004; Balsara & Kim 2005; Giacalone & Jokipii 2007; Mizuno et al. 2011; Guo et al. 2012; Fraschetti 2013, and others) and should be considered in the future studies. In the present paper, we adopt instead a rather standard and ‘simple’ prescription for the wave evolution. This allows us to reveal the basic trends caused by the disordered MF, as well as the complexity that arises when taking into consideration the random MF. Also the choice of modelling a Sedov SNR in the present paper

⁵ A possible realization of a turbulent MF by a spherical Gaussian, which preserves the zero divergence of MF, by an ensemble of Alfvén waves, is given by Bykov et al. (2008).

is in order to provide some basic ‘reference’ results, for a typical evolutionary phase.

We leave to future simulations the task of revealing effects of other, more complex, elements (like MHD instabilities, non-uniform ISM or ISMF, non-adiabatic or CR-modified shocks, other types of waves) in the modelling of polarized synchrotron emission from SNRs.

3.1 Equation for the downstream evolution of δB

The equation that describes the evolution of waves downstream of the shock is (McKenzie & Völk 1982)

$$\frac{\partial E_w}{\partial t} + \frac{\partial F_w}{\partial r} = u \frac{\partial P_w}{\partial r} + \sigma_w P_w - \Gamma_w P_w, \quad (22)$$

where u is the flow velocity with respect to the shock reference frame, $E_w = \delta B^2/4\pi$ is the wave (magnetic and kinetic) energy density, $P_w = \delta B^2/8\pi$ is the pressure of waves, $\sigma_w P_w$ and $\Gamma_w P_w$ are the growth and damping rates for waves, respectively. Note that the quantities in this equation are not functions of the wavenumber, but are the integrated ones. Let us assume that the energy flux F_w is dominated by Alfvén waves, so that

$$F_w = \frac{\delta B^2}{4\pi} u + \frac{\delta B^2}{8\pi} u. \quad (23)$$

It accounts for the purely magnetic (the first term to the right) and kinetic (the second term) contributions (McKenzie & Völk 1982); v_A is the Alfvén velocity

$$v_A = \frac{B}{\sqrt{4\pi\rho}}. \quad (24)$$

Therefore, behind the shock, $E_w = 2P_w$, $F_w = 3uP_w$ and equation for P_w becomes

$$\frac{\partial P_w}{\partial t} + u \frac{\partial P_w}{\partial r} + P_w \frac{3}{2} \frac{\partial u}{\partial r} = \frac{1}{2} (\sigma_w P_w - \Gamma_w P_w). \quad (25)$$

Alfvén waves interact resonantly with Larmor radius of accelerated protons: $k \propto 1/p$, where k is the wavenumber. The growth rate is derived by Skilling (1975b):

$$\sigma_w(k) = \frac{4\pi}{3} \frac{v_A |\hat{b} \cdot \hat{n}|}{k W(k)} p^4 v \frac{\partial f}{\partial r}, \quad (26)$$

where $W(k)$ is the spectrum of the wave energy density, $\hat{b}$ is the unit vector in the direction of MF (Skilling 1975a) and $\hat{n}$ is the unit vector outwards along the radius. These unit vectors are defined in such a way in order their dot product to be $\hat{b} \cdot \hat{n} = \cos \Theta$, where Θ is a ‘local’ obliquity angle (between MF and the radial direction). The absolute value of the dot product is taken because the growth rate is positive while the dot product may be negative depending on the local orientations of these vectors. The growth term in equation (22) is

$$\sigma_w P_w = \int \sigma_w(k) W(k) dk. \quad (27)$$

We therefore integrate equation (26) using the property $dk/k = -dp/p$ and the definition of the CR pressure

$$P_c = \frac{4\pi}{3} \int p^4 v f \frac{dp}{p}, \quad (28)$$

and derive that

$$\sigma_w P_w = v_A \cos \Theta \frac{\partial P_c}{\partial r}. \quad (29)$$

The damping term consists of the linear and non-linear contributions (e.g. Ptuskin & Zirakashvili 2003): $\Gamma_w = \Gamma_L + \Gamma_{NL}$. The first one is due to collisions of protons with neutral hydrogen of the density n_H (e.g. Kulsrud & Cesarsky 1971). It is taken as $\Gamma_L \propto n_H = 0$ assuming that no neutral survive after passage across the shock front. There is no commonly accepted approach to the description of the non-linear damping (see e.g. Ptuskin & Zirakashvili 2003, and references therein). We take the expression for the rate of non-linear Landau damping from Ptuskin & Zirakashvili (2003), namely from their equation 12:

$$\Gamma_{NL}(k) W(k) = c_K v_A k \frac{E_w(>k)}{B^2/4\pi} W(k), \quad (30)$$

where $c_K = (2C_K)^{-3/2}$, $C_K \approx 3.6$ being the quantity introduced by Ptuskin & Zirakashvili (2003), and $E_w(>k)$ the energy density of waves with wavenumbers larger than k . Note that there is no explicit obliquity dependence in this term because the waves interact with themselves and this process does not depend on the shock obliquity. Equation (30) can be integrated over k , giving

$$\int \Gamma_{NL}(k) W(k) dk = \frac{c_K v_A}{B^2/4\pi} \int k E_w(>k) W(k) dk. \quad (31)$$

Multiplying this expression by unity

$$1 \equiv E_w \left(\int W(k) dk \right)^{-1}, \quad (32)$$

and noting that the average $\langle k E_w(>k) \rangle$ is dominated by the lowest wavenumber in the spectrum ($k_{\min}$): $\langle k E_w(>k) \rangle \simeq k_{\min} E_w$, where $E_w(>k_{\min}) = E_w$, we have the damping term in equation (22) of the form

$$\Gamma_{NL} P_w = \frac{2c_K v_A}{B^2/8\pi} k_{\min} P_w^2. \quad (33)$$

Thus, equation (22) is now

$$\begin{aligned} \frac{\partial P_w}{\partial t} + u \frac{\partial P_w}{\partial r} + P_w \frac{3}{2} \frac{\partial u}{\partial r} \\ = \frac{v_A \cos \Theta}{2} \frac{\partial P_c}{\partial r} - \frac{c_K v_A}{B^2/8\pi} k_{\min} P_w^2. \end{aligned} \quad (34)$$

In order to follow more easily the evolution of waves in a given fluid element, we use the Lagrangian coordinate a and the relations

$$\left(\frac{\partial}{\partial t} + u \frac{\partial}{\partial r} \right)_E = \left(\frac{d}{dt} \right)_L, \quad \left(\frac{\partial}{\partial r} \right)_E = \frac{\rho(a) r(a)^2}{\rho_0(a) a^2} \left(\frac{\partial}{\partial a} \right)_L, \quad (35)$$

where ‘E’ and ‘L’ denote Eulerian and Lagrangian derivatives, respectively, and the latter relation directly follows from mass conservation ($\rho r^2 dr = \rho_0 a^2 da$). In terms of a , equation (34) has the form

$$\frac{dP_w(a, t)}{dt} + q_1(a, t) P_w(a, t) + q_2(a, t) P_w(a, t)^2 = q_0(a, t), \quad (36)$$

with

$$q_0 = \frac{v_A \cos \Theta \rho r^2}{2\rho_0 a^2} \frac{\partial P_c}{\partial a}, \quad (37)$$

$$q_1 = \frac{3\rho r^2}{2\rho_0 a^2} \frac{\partial u}{\partial a}, \quad (38)$$

$$q_2 = \frac{c_K v_A k_{\min}}{B^2/8\pi}. \quad (39)$$

Equation (36) is the Riccati differential equation and may be solved numerically. Solutions of equation (36) are considered in

detail in Section 4. In the rest of this section, we describe how to model different properties of waves that are needed to solve this equation.

The solution $P_w(a, t)$, with known $r(a, t)$, $\rho(a, t)$, $u(a, t)$, $B(a, t)$, $P_c(a, t)$, describes the wave pressure. The evolution of δB downstream is given by

$$\delta B(a, t) = \sqrt{8\pi P_w(a, t)}. \quad (40)$$

This dependence on a may be converted to the spatial dependence on r with the use of the relation $r(a, t)$ that is known explicitly from the hydrodynamic solution.

3.2 Shock compression factor for waves

Let us define the ‘shock compression factor’ for the wave pressure as the ratio of pressures immediately downstream P_{ws} and upstream P_{wo} :

$$\sigma_{Pw} = P_{ws}/P_{wo}. \quad (41)$$

This ratio may be calculated from the stationary form ($\partial P_w/\partial t = 0$) of equation (25) written as

$$\frac{1}{P_w} \frac{\partial P_w}{\partial r} + \frac{3}{2} \frac{1}{u} \frac{\partial u}{\partial r} = \frac{1}{2} (\sigma_w - \Gamma_w) \frac{dt}{dr}. \quad (42)$$

By integrating this equation across the shock, we get

$$\ln \frac{P_{ws}}{P_{wo}} + \frac{3}{2} \ln \frac{u_s}{u_o} = \frac{\Delta t}{4\tau_{\sigma s}} + \frac{\Delta t}{4\tau_{\sigma o}} - \frac{\Delta t}{4\tau_{\Gamma s}} - \frac{\Delta t}{4\tau_{\Gamma o}}, \quad (43)$$

where $\tau_\sigma = \sigma_w^{-1}$ and $\tau_\Gamma = \Gamma_w^{-1}$ are the time-scales for the wave growth and damping. In order to come to this equation, we estimated the functions σ_w and Γ_w with their average: $(\sigma_{ws} + \sigma_{wo})/2$ and $(\Gamma_{ws} + \Gamma_{wo})/2$.

If the time-scale Δt for the shock to cross the fluid element is much smaller than all $\tau_{\sigma s}$, $\tau_{\sigma o}$, $\tau_{\Gamma s}$ and $\tau_{\Gamma o}$, then the right-hand side in equation (43) vanishes and then

$$\sigma_{Pw} = \sigma^{3/2}, \quad (44)$$

where we have used the relation $u_o = \sigma u_s$. An important result is that, since σ is constant for strong shocks, the factor σ_{Pw} neither depends on time nor on the shock obliquity. The shock jump in δB is then simply

$$\frac{\delta B_s}{\delta B_o} = \left(\frac{P_{ws}}{P_{wo}} \right)^{1/2} = \sigma^{3/4}. \quad (45)$$

3.3 Model for the wave pressure on the shock P_{ws}

The energy density of waves is assumed to reach the saturation level before the shock front. Its value P_{wo} is given by the stationary form (Amato & Blasi 2006) of equation (25) written in the upstream region:

$$-2u \frac{\partial P_w}{\partial r} = \sigma_w P_w - \Gamma_w P_w. \quad (46)$$

Let us introduce two parameters

$$\xi = \left(\frac{\sigma_w P_w}{\Gamma_w P_w} \right)^{1/2} \frac{P_w}{P_{co}}, \quad (47)$$

$$\lambda = \frac{u P_w}{(\sigma_w P_w + \Gamma_w P_w)^{1/2}}. \quad (48)$$

Note from equations (29) and (33) that ξ and λ are independent of P_w . Equation (46) becomes, after multiplication by $\lambda \xi / (u P_{co})$,

$$-2\lambda \xi \frac{\partial}{\partial r} \left(\frac{P_w}{P_{co}} \right) = \xi^2 - \left(\frac{P_w}{P_{co}} \right)^2. \quad (49)$$

The solution of equation (49) may be derived by separation of variables, assuming $\xi = \xi_o$ and $\lambda = \lambda_o$ constant on the scale of the precursor, i.e. from the shock to distance x_o upstream of the shock. Thus, immediately upstream

$$P_{wo} = P_{co} \xi_o \frac{\exp(\Omega_o) - 1}{\exp(\Omega_o) + 1}, \quad (50)$$

where $\Omega_o = x_o/\lambda_o$. The CR and wave pressures are set to zero beyond the distance x_o because our model does not consider seed CRs and waves (note that $0 \leq P_{wo}/(P_{co} \xi_o) \leq 1$).

In order to see the meaning of the parameters ξ_o and Ω_o , we use equations (29) and (33), written for the upstream region and use some simplifications. For instance, the minimum wavevector $k_{\min}$ (whose modulus appears in equation 33) is set to $k_o \simeq b_o r_{Lo}^{-1}$, where $r_{Lo} = p_{\max} c / (e B_o)$ is the Larmor radius of protons with maximum momentum in the field B_o . The value of the CR pressure gradient in the shock precursor may be estimated as $\partial P_c / \partial r \simeq P_{co} / x_o$, where x_o is the distance the same protons are able to diffuse off the shock (the size of the CR precursor); it is directed opposite to $\hat{n}_o$. The unit vectors $\hat{b}_o$ and $\hat{n}_o$ are in the directions of the upstream MF and of the normal to the shock, respectively; their dot product is $\hat{b}_o \cdot \hat{n}_o = \cos \Theta_o$. The distance $x_o \simeq D(p_{\max}) / u_o$ (Amato & Blasi 2005), where $D(p_{\max}) = r_{Lo} c / 3$ is the Bohm diffusion coefficient. So,

$$\xi_o \simeq \left(\frac{\cos \Theta_o}{2c_K} \frac{3u_o}{c} \frac{P_{Bo}}{P_{co}} \right)^{1/2}, \quad (51)$$

$$\Omega_o \simeq \frac{v_{Ao} \cos \Theta_o}{u_o \xi_o} = \frac{\cos \Theta_o}{M_{Ao} \xi_o}, \quad (52)$$

where $2c_K \simeq 0.1$, and $M_{Ao} = u_o / v_{Ao}$ is the Alfvén Mach number of the shock.

Now, the post-shock pressure of waves is given by

$$P_{ws} \simeq \sigma_{Pw} P_{co} \xi_o \frac{\exp(\Omega_o) - 1}{\exp(\Omega_o) + 1}. \quad (53)$$

3.3.1 Limit cases of the wave evolution

Let us introduce the variable α as the ratio of the wave growth to damping rates

$$\alpha = \frac{\sigma_w P_w}{\Gamma_w P_w}. \quad (54)$$

Following definition (47), immediately before the shock

$$\xi_o = \alpha_o^{1/2} P_{wo} / P_{co}. \quad (55)$$

Comparing this relation with the solution (50), we see that the ratio between the two rates is related to the ratio of the exponents:

$$\alpha_o = \left(\frac{\exp(\Omega_o) + 1}{\exp(\Omega_o) - 1} \right)^2. \quad (56)$$

The plot $\alpha_o(\Omega_o)$ is shown in Fig. 3. The two limiting regimes of the wave evolution are evident from this plot: the limit A of the small damping rate at the shock [$\alpha_o = (2/\Omega_o)^2$ is larger than unity, $\Omega_o \ll 2$] and the limit B of the same rates at the shock (α_o is unity,

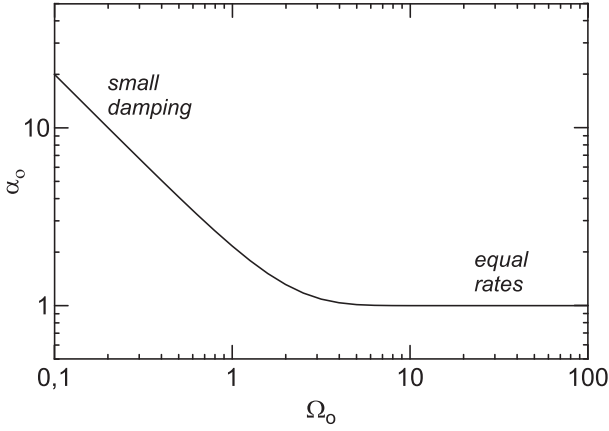


Figure 3. Ratio of the wave growth to damping rates α_o as a function of Ω_o .

$\Omega_o \gg 2$). The maximum damping rate may not be larger than the growth one, as expected (we do not assume a seed turbulence).

Fig. 3 demonstrates that the transition between the two limiting cases is in a rather narrow range. Namely, the first one may be used already for $\Omega < 1$ and the second one for $\Omega > 4$.

It is apparent from the figure that the ratio of the growth to damping rates increases with obliquity, for the same ξ_o and M_{Ao} , because Ω_o decreases with Θ_o , equation (52).

Equation (53) gives the possibility to calculate the wave pressure at the present time, on the shock. The wave pressure on the shock evolves as it follows from equations (53) and (56) and the expression for this evolution may be found as a ratio:

$$\frac{P_{wsi}}{P_{ws}} = \frac{P_{csi}}{P_{cs}} \frac{\xi_{oi}}{\xi_o} \frac{\alpha_o(\Omega_o)^{1/2}}{\alpha_o(\Omega_{oi})^{1/2}}, \quad (57)$$

where the index ‘i’ refers to the time t_i , i.e. P_{wsi} and P_{csi} are the wave and CR pressures in the element a when it was shocked. This formula is general; its limits (which are useful for interpretation of results) are considered in the next two subsections.

3.3.2 Limit case A: small wave damping at the shock

If the damping rate in the shock precursor is negligible compared to the growth rate (limit A), then equation (46) becomes

$$\frac{\partial P_w}{\partial r} = \frac{v_{Ao} \cos \Theta_o}{2u_o} \frac{\partial P_c}{\partial r} \quad (58)$$

with the obvious solution

$$P_{wo} = P_{co} v_{Ao} \cos(\Theta_o) / (2u_o). \quad (59)$$

The same expression may be obtained from the more general formula (53). Namely, if $\Gamma_w P_w \ll \sigma_w P_w$, then $\Omega_o \rightarrow 0$. Decomposition of the exponential terms with small arguments in equation (53) into series and use of the first-order term and equation (52) result in equation (59).⁶

The CR pressure is smooth across the shock: $P_{co} = P_{cs}$. The post-shock pressure in form of waves is therefore

$$P_{ws} = \frac{\sigma_{pw} P_{cs} v_{Ao} \cos \Theta_o}{2u_o} \quad (60)$$

in this limit.

⁶ This way to derive equation (59) proves also the correctness of equation (52).

In a non-uniform medium with a density profile $\rho_o(R)$, the velocity V of the strong adiabatic shock is well approximated by $V(R) \propto (\rho_o(R)R^3)^{-1/2}$ (Hnatyk & Petruk 1999, this formula is exact in the case of a constant density). Numerically, $u_o = V$. In the general case of an ambient medium with non-uniform distributions of density and MF, the variation of the post-shock value of the wave pressure in time follows from equation (60). Namely, the evolution of the wave pressure on the shock may be found as the ratio

$$\frac{P_{wsi}}{P_{ws}} = \frac{P_{csi}}{P_{cs}} \left(\frac{a}{R} \right)^{3/2} \left\{ \frac{B_o(a) \cos \Theta_o(a)}{B_o(R) \cos \Theta_o(R)} \right\}. \quad (61)$$

The term in braces $\{\dots\} = 1$ for a uniform ISMF.

3.3.3 Limit case B: equal rates at the shock

If $\Gamma_w P_w = \sigma_w P_w$ at the shock (limit B), then Ω_o is large. Unity may be neglected comparing to the exponential term both in the nominator and denominator in equation (53), i.e. $\alpha_o = 1$ and the expression for pressure of waves comes simply from equation (55):

$$P_{wo} = P_{co} \xi_o. \quad (62)$$

Therefore, for a general case of non-uniform ISM and ISMF,

$$\frac{P_{wsi}}{P_{ws}} = \left(\frac{P_{csi}}{P_{cs}} \right)^{1/2} \left(\frac{a}{R} \right)^{-3/4} \times \left\{ \frac{B_o(a) \cos \Theta_o(a)^{1/2}}{B_o(R) \cos \Theta_o(R)^{1/2}} \frac{\rho_o(a)^{-1/4}}{\rho_o(R)^{-1/4}} \right\}. \quad (63)$$

The term in braces $\{\dots\} = 1$ for ISM with uniform distributions of density and MF. Equation (63) is derived as a ratio P_{wsi}/P_{ws} directly from equation (62) using expression (51) and the approximation $V(R) \propto (\rho_o(R)R^3)^{-1/2}$.

3.3.4 Obliquity dependence of P_{ws}

In order to simulate polarization images, we need to also know how does the wave pressure vary with obliquity. We will use equation (53) for this purpose, and have therefore to find the obliquity dependences for all the quantities there.

The compression factor σ_{pw} is constant, equation (44).

The obliquity dependence of ξ_o comes from equation (51). In order to find it, we write the ratio of this parameter for a parallel shock (marked with the additional index $\parallel$) and for the shock with a generic obliquity angle (without additional index). Then we have, for a general case of non-uniform ISM and ISMF, that

$$\xi_o \simeq \xi_{o\parallel} \cos \Theta_o^{1/2} \frac{P_{cs\parallel}^{1/2}}{P_{cs}^{1/2}} \left\{ \frac{B_o \rho_{o\parallel}^{1/4} R_{\parallel}^{3/4}}{B_{o\parallel} \rho_o^{1/4} R^{3/4}} \right\}. \quad (64)$$

The term in braces is equal to unity for uniform ambient density and MF. The obliquity variation of Ω_o is given by definitions (52) and (64):

$$\Omega_o = \Omega_{o\parallel} \cos \Theta_o^{1/2} \frac{P_{cs}^{1/2}}{P_{cs\parallel}^{1/2}} \left\{ \frac{\rho_o^{1/4} R^{9/4}}{\rho_{o\parallel}^{1/4} R_{\parallel}^{9/4}} \right\}. \quad (65)$$

In deriving equations (64) and (65), the approximate formula $V(R) \propto (\rho_o(R)R^3)^{-1/2}$ was used.

Now, we know how ξ_o and Ω_o vary with obliquity. Thus, equation (53) gives us the ratio

$$\frac{P_{ws}}{P_{ws\parallel}} = \frac{P_{cs}}{P_{cs\parallel}} \frac{\xi_o}{\xi_{o\parallel}} \frac{\alpha_o(\Omega_{o\parallel})^{1/2}}{\alpha_o(\Omega_o)^{1/2}}, \quad (66)$$

which represents the obliquity dependence of the wave pressure. This reduces, for the Sedov shocks, to

$$\frac{P_{ws}}{P_{ws\parallel}} = \frac{P_{cs}}{P_{cs\parallel}} \cos \Theta_o \quad (67)$$

in the limit A and to

$$\frac{P_{ws}}{P_{ws\parallel}} = \left(\frac{P_{cs}}{P_{cs\parallel}} \right)^{3/2} \cos \Theta_o^{1/2} \quad (68)$$

in the limit B.

3.4 Evolution of the CR pressure P_c

For a given momentum distribution $f(p)$ of CRs, the CR pressure is

$$P_c = \frac{4\pi}{3} \int p^3 v(p) f(p) dp. \quad (69)$$

In order to simplify the calculations of the evolution of δB , we approximate P_c assuming an isotropic test-particle CR distribution $N(p) = 4\pi p^2 f(p)$ that is represented by a power law $N(p) = Kp^{-s}$, with s close to 2, in the range between the minimum and maximum momenta of CRs $p_{\min}$ and $p_{\max}$. The CR pressure in this case is

$$P_c(a, t) = \frac{1}{3} K(a, t) \int_{p_{\min}(a, t)}^{p_{\max}(a, t)} p^{1-s} v(p) dp. \quad (70)$$

Since an approximate treatment of $P_c(r)$ is sufficient to our purposes, in this subsection, we fix $s = 2$, a choice that minimizes the dependence of the CR pressure on $p_{\max}$, while describing reasonably well also the cases with s slightly different from 2.

Then, in the regime $p_{\min} \ll mc \ll p_{\max}$, being $v \simeq c$ for $p \geq mc$, we finally derive

$$P_c(a, t) = \frac{c K_s(t)}{3} \frac{K(a, t)}{K_s(t)} \ln \left(\frac{p_{\max}(a, t)}{mc} \right). \quad (71)$$

In all reasonable cases, the logarithmic term can be approximated with $\ln(p_{\max, s}/mc)$, where $p_{\max, s} \geq 10^3 mc$.

The normalization K_s , related to the injection efficiency η by

$$\int_{p_{\min, s}}^{p_{\max, s}} K_s p^{-2} dp = \eta n_s, \quad (72)$$

evaluates

$$K_s = \eta n_s p_{\min, s}. \quad (73)$$

At the shock ($a = R$), the expression for the CR pressure, equation (71) with equation (73), coincides with equation 30 in Amato & Blasi (2009).

The minimum momentum may be estimated by its relation to the thermal momentum. We assume that the distribution of the thermal particles downstream may be approximated by the Maxwellian

$$f_M(p) = \frac{4}{\sqrt{\pi}} y^2 \exp(-y^2), \quad (74)$$

where $y = p/p_{\text{th}}$ with $p_{\text{th}} = \sqrt{2mkT_s}$ being the thermal momentum and

$$T_s = \frac{2(\gamma - 1)}{(\gamma + 1)^2} \frac{\mu_o m}{k} V^2 \quad (75)$$

the shock temperature and μ_o the mean particle mass in units of the proton mass. Further, we assume that all thermal particles

with momenta $p > p_{\min}$ are to be accelerated. Thus, the injection efficiency is

$$\eta = \int_{y_{\min}}^{\infty} f_M(y) dy. \quad (76)$$

In general, in order to find the minimum momentum $p_{\min, s} = y_{\min} p_{\text{th}}$, one has to solve this equation to find $y_{\min}$ for a given value of η . This formula gives, in particular, $y_{\min} = 3.07$ for $\eta = 3 \times 10^{-4}$ and $y_{\min} = 3.91$ for $\eta = 10^{-6}$. Since $y_{\min}$ varies quite slowly for a wide range of η , we set in our simulations $p_{\min, s} = 3.4 p_{\text{th}}(T_s)$.

Taking all these pieces together,

$$P_c(a) \simeq \frac{2.3 \eta \rho_o V c}{\mu_o^{1/2} (\gamma - 1)^{1/2}} \frac{K(a)}{K_s} \ln \left(\frac{p_{\max, s}}{mc} \right), \quad (77)$$

where all parameters are referred to the time t and some of them depend on the shock obliquity.

Let us parametrize the time dependence of the injection efficiency as $\eta(t) \propto V(t)^{-(b+1)}$ with a parameter b (i.e. $K_s \propto V^{-b}$ because $p_{\min} \propto V$). Then the ratio of CR pressures needed in equation (57) is

$$\frac{P_{cs_i}}{P_{cs}} = \frac{\rho_o(a)}{\rho_o(R)} \left(\frac{V(a)}{V(R)} \right)^{-b} = \left(\frac{\rho_o(a)}{\rho_o(R)} \right)^{1+b/2} \left(\frac{a}{R} \right)^{3b/2}. \quad (78)$$

The way to calculate $K(a)/K_s$ is described in Orlando et al. (2007, 2011) for the general case of non-uniform ISM and ISMF and in Petruk et al. (2011b) for a Sedov shock in ISM with uniform density and MF. In particular, the evolution of the normalization K behind the Sedov shock is self-similar: $K(a, t)/K_s(t) = \bar{K}(\bar{a})$, where

$$\bar{K}(\bar{a}) = \bar{a}^{3b/2} \bar{\rho}(\bar{a})^{(2+s)/3} \quad (79)$$

is time independent, $\bar{a} = a/R$ and R the radius of the shock. The profile of the CR pressure, equation (77), is [to the level of approximation used for the logarithmic factor in equation (71)] self-similar as well, i.e. it may be written in the form $P_c(a, t) = P_{cs}(t) \bar{P}_c(\bar{a})$, where

$$P_{cs}(t) = \frac{2.3 \eta \rho_o V c}{\mu_o^{1/2} (\gamma - 1)^{1/2}} \ln \left(\frac{p_{\max, s}}{mc} \right), \quad (80)$$

$$\bar{P}_c(\bar{a}) = \bar{K}(\bar{a}). \quad (81)$$

We have just described the time evolution of the CR pressure, at the parallel shock. We also need the prescription for the whole SNR surface, i.e. at the oblique shocks as well. The obliquity dependence of P_{cs} is due to the respective dependence of the injection efficiency and variations (if any) of the ambient density and the shock radius. It is given by the ratio

$$\frac{P_{cs}}{P_{cs\parallel}} = \frac{\eta}{\eta_{\parallel}} \left\{ \frac{\rho_o^{1/2} R_{\parallel}^{3/2}}{\rho_o^{1/2} R^{3/2}} \right\} \quad (82)$$

derived from equation (80) where we neglected for simplicity the obliquity dependence of the logarithmic term and used the approximate formula $V(R) \propto (\rho_o(R) R^3)^{-1/2}$.

3.5 Evolution of $k_{\min}$

The function q_2 , equation (39), contains $k_{\min}$. In our model, the downstream evolution of $k_{\min}$ is described as follows. Since $W(k)$ is a decreasing function, the damping is highest for waves with the smallest k , equation (30). Therefore, we assume that, in a given fluid element, at a given time, the only survived waves are those with the wavenumbers larger than $k_{\min}$, which is able to interact resonantly with the Larmor radius of particles of the highest energy:

$k_{\min} \simeq 1/r_L(p_{\max}) = eB/(cp_{\max})$. Then, we consider the evolution of B and $p_{\max}$ within this fluid element.

In order to describe $p_{\max}(a, t)$, we parametrize the time evolution of the maximum momentum that particles reach at the shock as $p_{\max,s}(t) \propto V(t)^q$; then

$$\frac{p_{\max,s}(t_i)}{p_{\max,s}(t)} = \left(\frac{V(a)}{V(R)} \right)^q = \left(\frac{a}{R} \right)^{-3q/2}. \quad (83)$$

Numerically, for the Sedov phase, $q = 1/3$ if $p_{\max}$ is time limited,⁷ $q = 0$ if it is escape limited and $q = 1$ if it is limited by the radiative losses (Reynolds 1998, p. 379). Downstream, even protons with the maximum momentum $p_{\max}$ experience only adiabatic losses, i.e. $p_{\max}(a) \propto E_{\max}(a) \propto \rho(a)^{1/3}$ (e.g. Reynolds 1998); the energy losses due to pion production are neglected assuming that the shock is propagating in a medium with density less than $\sim 10^4 \text{ cm}^{-3}$ (e.g. Beshley & Petruk 2012). The evolution of $p_{\max}$ downstream is therefore given by

$$\frac{p_{\max}(a, t)}{p_{\max,s}(t_i)} = \left(\frac{\rho(a, t)}{\rho_s(t_i)} \right)^{1/3}. \quad (84)$$

Taking equations (83) and (84) together,

$$\frac{p_{\max}(a, t)}{p_{\max,s}(t)} = \left(\frac{a}{R} \right)^{-3q/2} \left(\frac{\rho(a, t)}{\rho_s(t)} \right)^{1/3} \left(\frac{\rho_o(a)}{\rho_o(R)} \right)^{-1/3}. \quad (85)$$

It appears from the above formulae that the evolution of the minimum wavenumber is self-similar for the Sedov shock:

$$k_{\min}(a, t) = k_{\min,s}(t) \cdot \bar{k}_{\min}(\bar{a}), \quad (86)$$

with

$$k_{\min,s}(t) = \frac{eB_s}{p_{\max,s}c}, \quad (87)$$

$$\bar{k}_{\min} = \bar{B}/\bar{p}_{\max} = \bar{B}\bar{a}^{3q/2}\bar{\rho}^{-1/3}. \quad (88)$$

4 SOLUTIONS OF EQUATION FOR WAVES

The evolution of the wave pressure P_w within a fluid element a after its passage through the shock is given by equation (36). In this section, we consider solutions of this equation. Section 4.1 deals with a particular case that allows for analytic expression. The formulae are presented for the general case and for a particular model of Sedov shocks in uniform medium and uniform MF. Numerical solutions are presented in Section 4.2.

4.1 Limit case A: small wave damping

4.1.1 Solution for a general case

If the damping rate is negligible at the shock (i.e. $\Omega_o < 1$) and everywhere downstream, then the damping term in equation (36) may be set $q_2 P_w^2 = 0$ and the solution of equation (36) is

$$P_w(a, t) = \mu(a, t) \left(P_{ws}(t_i) + \int_{t_i}^t \frac{q_0(a, t')}{\mu(a, t')} dt' \right), \quad (89)$$

$$\mu(a, t) = \exp \left(- \int_{t_i}^t q_1(a, t') dt' \right). \quad (90)$$

⁷ In this case, $p_{\max} \propto V^2 t$ (Lagage & Cesarsky 1983) and $V \propto t^{-3/5}$ for the Sedov shock; therefore, $p_{\max} \propto V^{1/3}$.

In order to evaluate this solution numerically, one needs to know the time history of the whole SNR structure; in other words, one should have the MHD data cube for each time moment t_i . It is more suitable for calculations to express the integrals in terms of a rather than t' . With the use of

$$dt' = \frac{dR(t')}{V(t')} = \frac{da}{V(a)}, \quad (91)$$

one has the spatial profile of the wave pressure

$$P_w(a, t) = \mu(a, t) \left(P_{ws} \left[\frac{P_{wsi}}{P_{ws}} \right] + \int_a^{R(t)} \frac{q_0(a', t)}{\mu(a', t)V(a')} da' \right), \quad (92)$$

$$\mu(a, t) = \exp \left(- \int_a^{R(t)} \frac{q_1(a', t)}{V(a')} da' \right), \quad (93)$$

where $P_{wsi} \equiv P_{ws}(t_i)$ is the value at time t_i , while other quantities are referred to time t . In this approach, it is enough to know the present-time SNR structure only. Having the present-time value of P_{ws} and the ratio P_{wsi}/P_{ws} from equation (61) [which, like the integrals in equations (92) and (93), depends on the distribution of MHD parameters at the present time], we may calculate $P_w(a, t)$ numerically.

4.1.2 Solution for a Sedov shock

Let us consider this solution for a particular model, namely, for a Sedov shock in a uniform medium and uniform MF.

For a Sedov SNR evolution in a medium with uniform density and MF, equation (92) becomes

$$P_w(a, t) = P_{ws}(t) \left(\bar{P}_{wa}(\bar{a}) + \bar{P}_{wb}(\bar{a}) \right), \quad (94)$$

where the profiles $\bar{P}_{wa}(\bar{a})$, $\bar{P}_{wb}(\bar{a})$ are time independent, $\bar{a} = a/R$. Namely,

$$\bar{P}_{wa}(\bar{a}) = \bar{a}^{3(b+1)/2} \bar{\mu}(\bar{a}), \quad (95)$$

$$\bar{P}_{wb}(\bar{a}) = \frac{\sigma_B \bar{\mu}(\bar{a})}{\sigma \cos(\Theta_o)} \int_{\bar{a}}^1 \frac{\bar{B} \bar{\rho}^{1/2} \bar{r}^2 \cos(\Theta) d\bar{P}_c}{\bar{\mu} \bar{a}^{1/2}} \frac{d\bar{P}_c}{d\bar{a}'} d\bar{a}', \quad (96)$$

$$\bar{\mu}(\bar{a}) = \exp \left[- \frac{3}{2} \int_{\bar{a}}^1 \frac{\bar{\rho} \bar{r}^2}{\bar{a}^{1/2}} \frac{d\bar{u}}{d\bar{a}'} d\bar{a}' \right]. \quad (97)$$

In order to derive equation (95), we made use of equations (61) and (78) and $u_s = V/\sigma$. In derivation of equation (96), we made use of equations (60), (44) and $V(R)/V(a) = \bar{a}^{3/2}$.

Equations (95)–(97) are written in a way to express the solution through the basic profiles of MHD parameters. It is clear from here that the downstream evolution of P_w is self-similar. Equation (40) shows that $\delta B(a)$ is self-similar as well, $\delta B(a, t) = \delta B_s(t) \cdot \bar{\delta B}(\bar{a})$, with

$$\delta B_s = \sqrt{8\pi P_{ws}} \quad (98)$$

and $\bar{\delta B} = \bar{P}_w^{1/2}$, i.e.

$$\bar{\delta B} = (\bar{P}_{wa}(\bar{a}) + \bar{P}_{wb}(\bar{a}))^{1/2}. \quad (99)$$

The profiles $\bar{\delta B}(\bar{r})$ are shown in Fig. 4 in comparison with profiles of $\bar{B}(\bar{r})$. In the considered limit A, the turbulent MF has a flat distribution in the deep interior (no wave damping) while B decreases. As a result, the ratio $\delta B/B$ increases towards the centre of SNR. The obliquity affects the normalized profiles $\bar{\delta B}(\bar{r})$: the normalized strength of the turbulent MF is larger for a perpendicular shock. However, in the considered limit, the post-shock value

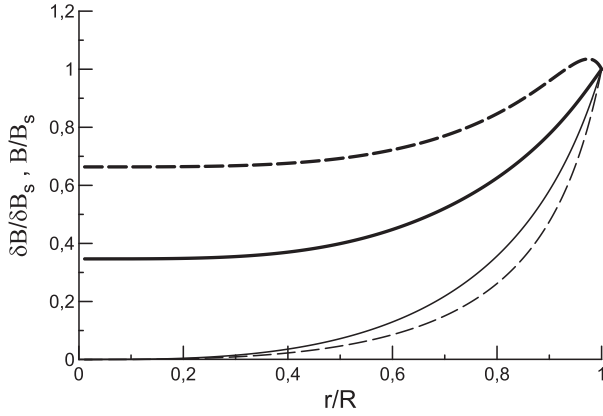


Figure 4. Normalized radial profiles of $\bar{B}(\bar{r})$ (thin lines) and $\delta\bar{B}(\bar{r})$ (thick lines) along SNR radius downstream of the parallel shock (solid lines) and perpendicular one (dashed lines). Limit of the small damping, $b = 0$, $q = 0$.

$\delta B_s \propto P_{ws}^{1/2} \propto \cos \Theta_0^{1/2}$ (equation 67), i.e. it is zero for perpendicular shock.

4.2 General solution for Sedov shock

In a general case when both the wave growth and damping should be considered, the solution of equation (36) may be found numerically.

Let us consider Sedov SNR evolution in a medium with uniform density and MF and rewrite equation (36) in order to have an equation for $\bar{P}_w(\bar{a})$. First, we substitute equation (36) with the self-similar form

$$P_w(a, t) = P_{ws}(t) \bar{P}_w(\bar{a}), \quad a = \bar{a} \cdot R(t). \quad (100)$$

Then we use the same procedure as before, namely, transform from the variable t to the variable a with equation (91). These steps yield the following equation for the normalized wave pressure $\bar{P}_w(\bar{a})$:

$$\frac{d\bar{P}_w}{d\bar{a}} + \bar{q}_1 \bar{P}_w + \bar{q}_2 \bar{P}_w^2 = \bar{q}_0 \quad (101)$$

with

$$\bar{q}_0 = \frac{q_0 R}{V(a) P_{ws}} = \frac{\sigma_B \cos \Theta}{\sigma \cos \Theta_0} \frac{\bar{B} \bar{\rho}^{1/2} \bar{r}^2}{\bar{a}^{1/2}} \frac{d\bar{P}_c}{d\bar{a}} \cdot \frac{\Omega_0 \alpha_0^{1/2}}{2}, \quad (102)$$

$$\bar{q}_1 = \frac{q_1 R}{V(a)} = \frac{3\bar{\rho} \bar{r}^2}{2\bar{a}^{1/2}} \frac{d\bar{u}}{d\bar{a}}, \quad (103)$$

$$\bar{q}_2 = \frac{q_2 R P_{ws}}{V(a)} = \frac{\bar{a}^{3(q+1)/2} \sigma R}{\bar{\rho}^{5/6} x_0} \cdot \frac{\Omega_0 \alpha_0^{-1/2}}{2}. \quad (104)$$

The factor $\Omega_0 \alpha_0^{-1/2} 2^{-1} = (\Omega_0/2)^2$ in the limit of small wave damping. Therefore, $q_2 \rightarrow 0$ in this limit because $\Omega_0 \ll 2$. In addition, $\Omega_0 \alpha_0^{1/2} 2^{-1} = 1$ and we recover results of Section 4.1.2.

In the limit of equal rates, $\alpha_0^{1/2} = 1$. It should also be $\bar{q}_2 \bar{P}_w^2 = \bar{q}_0$ at the shock. This yields

$$\frac{R}{x_0} = \frac{1}{\sigma^2} \left[\frac{d\bar{P}_c}{d\bar{a}} \right]_s, \quad (105)$$

where we have used the relation $\cos \Theta_0 = \sigma_B \cos \Theta_s$. Though expression (105) comes from a limit, we shall use it for any α_0 . Therefore, we adopt

$$\bar{q}_2 = \frac{\bar{a}^{3(q+1)/2}}{\sigma \bar{\rho}^{5/6}} \left[\frac{d\bar{P}_c}{d\bar{a}} \right]_s \cdot \frac{\Omega_0 \alpha_0^{-1/2}}{2}. \quad (106)$$

With equations (81), (79) and for Sedov solutions (Hnatyk & Petruk 1996, 1999)

$$\left[\frac{d\bar{\rho}}{d\bar{a}} \right]_s = \frac{5\gamma + 13}{(\gamma + 1)^2}, \quad (107)$$

we have

$$\left[\frac{d\bar{P}_c}{d\bar{a}} \right]_s = \frac{3b}{2} + \frac{2+s}{3} \frac{5\gamma + 13}{(\gamma + 1)^2}. \quad (108)$$

We use $s = 2$ and $\gamma = 5/3$ for plots and numerical simulations.

In order to have the *spatial profile* $\bar{P}_w(\bar{a})$, we should start from the initial value of $P_w(a, t_i)$ in the fluid element a at time t_i when it was shocked, i.e. from $P_{wsi}(a)$; its normalized version is $\bar{P}_{wsi}(\bar{a}_{ini})$. Then equation (101) has to be used to evolve the wave pressure in this fluid element up to the time t , i.e. to find $P_w(a, t)$; its normalized version is $\bar{P}_w(1)$. Note that $\bar{P}_w(1)$ is different for different initial values $\bar{P}_{wsi}(\bar{a})$. In other words, the solution $\bar{P}_w(\bar{a})$, $\bar{a} \in [\bar{a}_{ini}, 1]$, of equation (101) with the initial value $\bar{P}_{wsi}(\bar{a}_{ini})$ does not represent the spatial distribution of the wave pressure for different $\bar{a}$ but the *time evolution* of P_w within the element a written in terms of time in an indirect way. Therefore, in order to have the *spatial variation* $\bar{P}_w(\bar{a})$, one needs to solve this equation many times with the initial conditions for different $\bar{a}_{ini}$. Different values of $\bar{P}_w(1)$ derived from each solution correspond to the wave pressure in respective fluid elements $\bar{a}_{ini} = a/R(t)$ at time t and therefore represent such a spatial variation, $\bar{P}_w(\bar{a}_{ini})$.

This could look like a complicate procedure. However, the direct solution of equation (36) is not simpler from the point of view of numerical realization. Namely, in our approach, we do not need to keep the time history of spatial distributions of all the parameters to make temporal integration. We just take one, the present-time spatial distribution of parameters, and do the spatial integration instead of the temporal one (cf. Section 4.1).

The initial condition, as derived from equations (57), (51) and (78), is

$$\bar{P}_{wsi} \equiv \frac{P_{ws}(t_i)}{P_{ws}(t)} = \bar{a}^{3(b-1)/4} \left[\frac{\alpha_0(\Omega_0)}{\alpha_0(\Omega_0 \bar{a}^{3(b+3)/4})} \right]^{1/2}, \quad (109)$$

where we substituted $\Omega_{oi} = \Omega_0 \bar{a}^{3(b+3)/4}$ (as from equations 52, 51, 78) and assumed a uniform ambient medium density and MF. In the limit of small damping, this results in

$$\bar{P}_{wsi} = \bar{a}^{3(b+1)/2} \quad (110)$$

(cf. equation 61), while in the limit of equal rates, we obtain (cf. equation 63)

$$\bar{P}_{wsi} = \bar{a}^{3(b-1)/4}. \quad (111)$$

Fig. 5 shows the radial distribution of the wave pressure downstream of the Sedov shock for some values of Ω_0 . The larger the Ω_0 , the closer the damping rate to the rate of the wave growth at the shock (Fig. 3). However, for larger Ω_0 , the values of $\bar{P}_{wsi}$ were higher at previous times (Fig. 6). Combination of these features results in the larger wave pressure P_w in the interior of SNR for larger Ω_0 (Fig. 5).

How to know which regime of the wave behaviour (limit A or B) is more reliable for a certain parameter set? One can note from equations (52), (51) and (80) that

$$\Omega_0 \simeq 1.5 \eta^{1/2} \frac{c}{V} \cos \Theta_0^{1/2}. \quad (112)$$

This means that a typical SNR shock ($\eta^{1/2} c/V \sim 0.1-10$) could be either in the small damping limit or in the limit of the equal damping

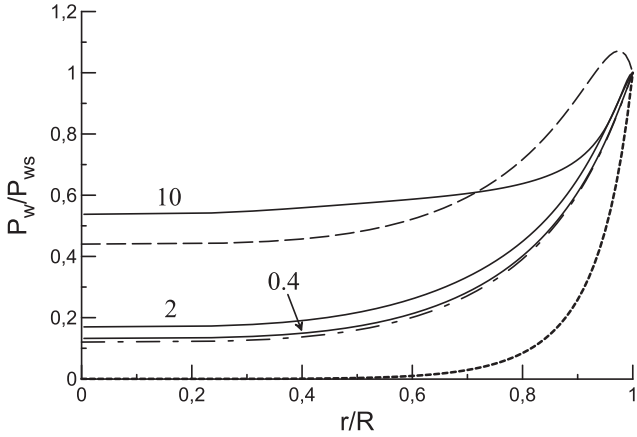


Figure 5. Profiles $\bar{P}_w(\bar{r})$ as from equation (101) for $\Omega_0 = 0.4, 2, 10$ (solid lines). The solution in the limit of negligible damping (equation 94) is shown by the dot-dashed line. For the plot, we have chosen $b = 0, q = 0$. The solid and dot-dashed lines refer to the parallel shock, while the long-dashed line to a perpendicular shock ($\Omega_0 = 0$ for the perpendicular shock, equation 65). The profile $\bar{P}_c(\bar{r})$, equation (81), is shown by the dotted line for comparison.

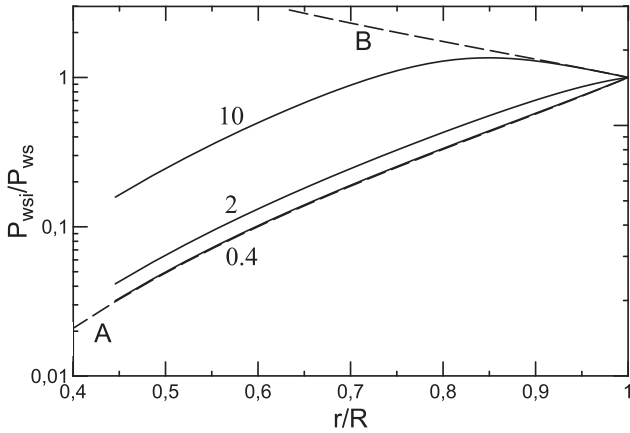


Figure 6. Values of $\bar{P}_{ws}$ (as from equation 109) for the fluid element $\bar{a}$ at time t_i when it was shocked plotted versus the present position $\bar{r}$ of this element. All cases are for a parallel shock with $b = 0$; lines are labelled with the values of Ω_0 . The same for the limit A (equation 110; dashed line marked by 'A') and for the limit B (equation 111; dashed line marked by 'B').

and growth rates. The quasi-perpendicular shocks are always in the regime of the small damping because of the dependence of Ω_0 on the cosine of the obliquity angle.

The solution for the limit of the small damping, equation (94), is shown in Fig. 5 by the dot-dashed line. The radial profiles for small Ω_0 values are close to that approximate solution. The differences are evident deep downstream. The solution in the limit A is obtained under assumption that the condition $q_2 P_w^2 \ll q_0$ is valid everywhere inside the SNR. However, in the solution of the more general equation (101), the ratio $q_2 P_w^2 / q_0$ increases downstream with distance from the shock. Therefore, the condition $q_2 P_w^2 / q_0 \ll 1$ could not be valid at radii lower than some distance from the centre. Nevertheless, the differences are not large and the approximate solution may be used if one needs to reduce the computational cost.

At a first glance, it seems that a similar approximate solution might be obtained for the limiting case B. In fact, this case assumes equal rates at the shock. If the growth and damping would be

almost the same everywhere downstream, then the equation would be much simpler: $d\bar{P}_w/d\bar{a} + \bar{q}_1 \bar{P}_w = 0$. However, the ratio of the damping to growth rates (α^{-1}) increases downstream quite quickly with decrease of $\bar{a}$ (less waves survived) preventing us from such a simplification.

Calculations show that profiles $\bar{P}_w(\bar{r})$ are almost insensitive to the value of q . Smaller values of b result in higher $\bar{P}_w$ in the SNR interior because the saturated level $P_{ws} \propto \bar{a}^{3b/2}$ ($\bar{a} \leq 1$) was larger at previous times for smaller values of the parameter b . In order to reduce the parameter space, b and q are set to zero in our calculations.

5 POLARIZATION MAPS FOR SEDOV SNRS

In this section, we present the results of numerical simulations for SNRs evolving in the Sedov regime (adiabatic expansion in the medium with the uniform distribution of density and MF). For these simulations, we have used the assumptions and formulae as described in the above sections. In all our images, the projected ambient MF is along the horizontal x -axis. Thanks to the semi-analytic nature of our simulations (Sedov solutions are analytic), we are not confined by the fixed grid of the numerical simulations with limited resolution in three dimensions. We can calculate all the necessary parameters in any point inside SNR and we may have as large resolution as we need. In practice, all our images have 100×100 pixels in the projection plane and very large resolution (determined automatically by the integration algorithm) along the line of sight.

5.1 Completely ordered MF

For the sake of comparison with what will follow, let us present first the results of numerical calculations for the case of a fully ordered MF.

Fig. 7 shows maps of the Stokes parameter I (surface brightness), Q , U , the polarization fraction Π , the magnetic polarization angle (angle of 'projected' MF with the x -axis) Ψ and the associated vector map of the 'MF orientations' inferred from the projected Stokes parameters, in the absence of the internal Faraday rotation ($\beta = 0$), for the aspect angle (between the ambient MF direction and the line of sight) $\phi_0 = 90^\circ$. The most prominent features are the quite symmetric patterns for Q and U , the smoothly ordered 'projected' MF and the high level of polarization: it is close to the maximum theoretical value, $\simeq 0.69$, over the whole projection.

Fig. 10 of Paper I shows the same set of images but simulated in the *thin-layer approximation*. The maps from the present *three-dimensional model* (Fig. 7) resemble those images rather well. Some minor differences can be noticed, especially closer to the SNR edge: they are essentially a consequence of the fact that we now model in details the internal structure of SNR that was neglected in the thin-shell approximation adopted in Paper I. In particular, the most apparent differences are the four 'islands' on the map of the polarization fraction, which were not present in the same image in Paper I. They are real, not just a numerical effect, and the reason is the following: in the case of the thin-layer approximation, all the material is in an infinitely thin layer around the SNR shock and there are only two emitting 'points' along each line of sight with different orientations of the MF vectors (in the case of an aspect angle of 90° , the orientations of the MF vectors are aligned on the two points). In contrast, the present model deals with different MF orientations in each point in the SNR interior. The depolarization on the Π image is a bit higher where MF vectors vary to larger

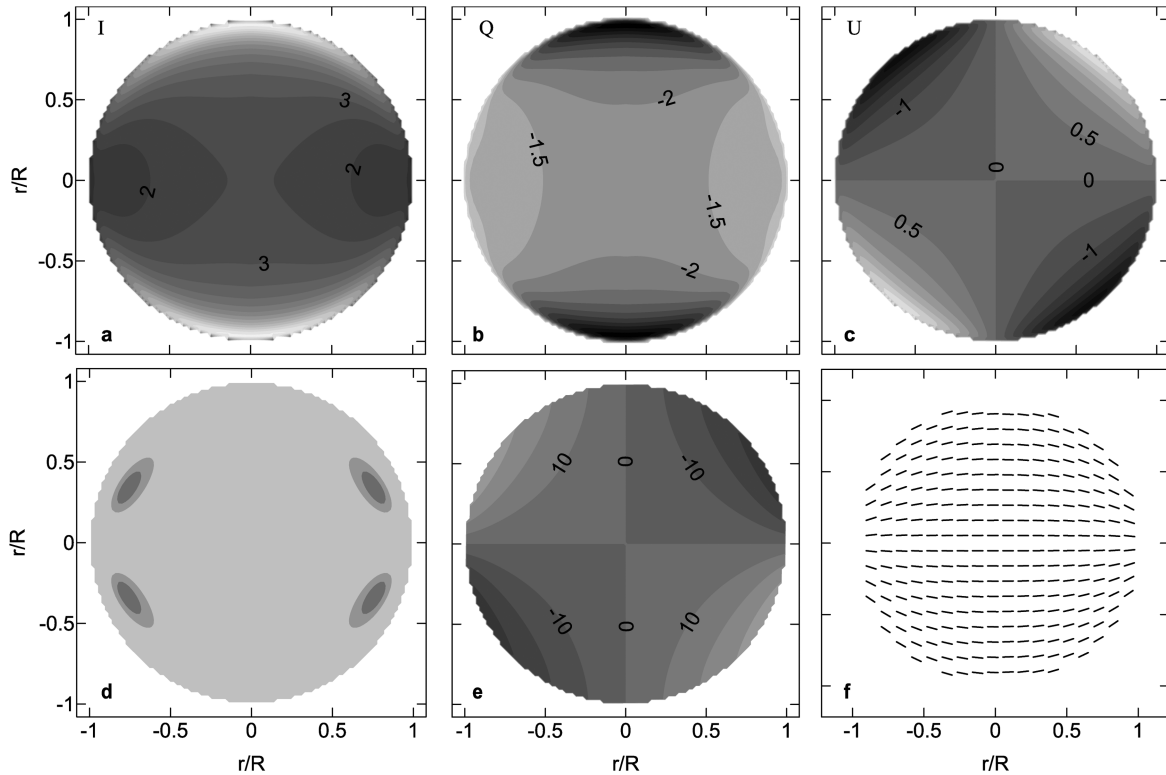


Figure 7. Maps of the Stokes parameter I (surface brightness) (a), Q (b), U (c), polarization fraction Π (d), magnetic polarization angle Ψ (e) and vector map of ‘MF orientations’ (f) for a Sedov SNR with completely ordered MF (projected along the horizontal axis) and no Faraday rotation. The aspect angle is $\phi_o = 90^\circ$ (i.e. B_o is in the projection plane). Grey-scale limits (the smaller the darker): (a) from 0.5 to 9.5, step 0.5 in arbitrary units, (b) from -6.5 to 0.5 , step 0.5 in arbitrary units, (c) from -4.5 to 4.5 , step 0.5 in arbitrary units, (d) from 0.6895 to 0.6905, step 0.0005, (e) min -90 , max 90 , step 10, in degrees. Hereafter, the length of lines in the MF direction maps is proportional to Π with the maximum length for 0.7. In this figure, $\langle \Pi \rangle = 0.692$.

extent along the line of sight. In other words, it is an effect of the MF jiggling along the line of sight, and Π thus is a ‘measure’ of the MF disorder along this line.

Fig. 8 shows the same maps, calculated including the internal Faraday rotation. The polarization fraction is still high in Fig. 8 but the lowest value is now $\Pi = 0.522$ that is smaller than in Fig. 7. However, the polarization fraction is still high over the most of the SNR projection, as is demonstrated by the average value of Π , $\langle \Pi \rangle = 0.686$.

Also in this case, the patterns shown in Paper I (see fig. 14 there) are reasonably reproduced. The most apparent differences are again in the Π map. The regions with the lowest polarization fraction are not lying on the projected boundary, but slightly inside. In addition, this map is not symmetric any more with respect to the horizontal axis: also in this case, because (differently from the thin-layer case) the level of the MF jiggling along the line of sight is now no longer symmetric. The internal Faraday effect causes the asymmetry between the upper and lower half of the Q and U maps. This translates in an asymmetry in the map of the polarization fraction. In fact, this effect is not present in the corresponding figures in Paper I (fig. 14 there) that were simulated in the limit of the infinitely thin layer.

The pattern of this asymmetry depends on the orientation of the ambient MF. In our simulations, it is directed towards the right. Therefore, in the nearer half-sphere of SNR (i.e. for $z \geq 1$, see Fig. 1), the line-of-sight component of the ordered MF (B_z) is preferentially positive (towards the observer) in the left half and preferentially negative in the right half of image. The orientation of B_z in the

nearer half-sphere of SNR is dominant for the internal Faraday rotation (the emission from the rearer part also passes through this SNR part). Therefore, the rotation is preferentially anticlockwise to the left (from the observer point of view) and clockwise to the right (Fig. 9). The polarization planes are rotated by the same angle in the points symmetric with respect to the horizontal axis. However, the plane-of-the-sky components of MF have different orientation in the upper and lower half of image. As a result, the upper–lower asymmetry appears.

The degree of the asymmetry depends on the ‘strength’ of the internal Faraday effect. Equations (5) and (6) show that, due to the scaling property of the Sedov solutions, the angle of internal rotation β in each point of the projection is proportional to the same product

$$\beta_n = n_o B_{o\mu} R_{pc} \lambda_m^2, \quad (113)$$

where $B_{o\mu}$ is the strength of the ambient MF in μG , R_{pc} is the radius of SNR in pc and λ_m is the wavelength in m. The parameter is, for example, $\beta_n = 2.7$ for $n_o = 1 \text{ cm}^{-3}$, $B_o = 3 \mu G$, $R = 10 \text{ pc}$, $\lambda = 30 \text{ cm}$. Thus, the parameter β_n determines how strong is the Faraday effect in the SNR interior.

5.2 Models with the partially disordered MF

In this subsection, we present maps of polarized emission in models that consider both the ordered B and disordered δB MF components. The parameters for a number of considered models are summarized in Table 1. The basic set of parameters is that for the model labelled

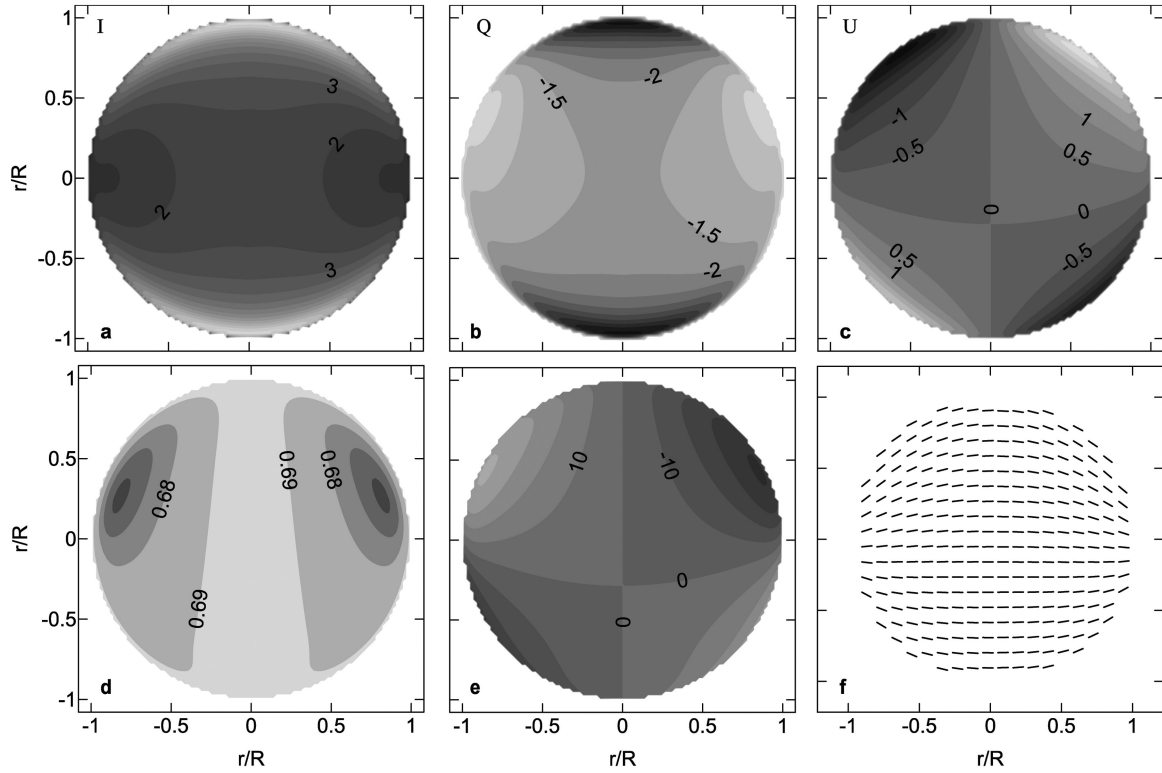


Figure 8. The same as in Fig. 7 but including the internal Faraday rotation, $\beta_n = 1$. Grey-scale for (d): min 0.64, max 0.7, step 0.01. $\langle \Pi \rangle = 0.686$.

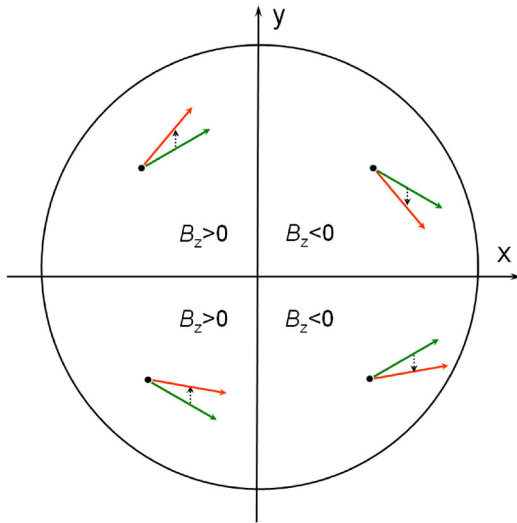


Figure 9. The schematic representation of the MF orientations, from the observer point of view: without (green) and with (red) the internal Faraday rotation; cf. Fig. 1.

as A. Other models have one or at most two parameters changed with respect to model A and only these parameters are displayed in the table.

Fig. 10 shows the same set of images as in Figs 7 and 8 but now including the Faraday rotation and the disordered MF. We can see that the addition of the disordered MF (with $(\delta B/B)_{s\parallel}$ less than unity) does not alter considerably the images of the polarized emission.

However, there are some differences visible. In particular, the surface brightness is somehow higher in the model that includes

Table 1. Sets of parameters for the numerical simulations. The parameter β_n is defined by equation (113). Set A is the reference model; while the other models differ from the case A only for the values shown in the table. ‘iso’ means isotropic injection (i.e. independent of the shock obliquity), while ‘qpar’ means quasi-parallel injection (i.e. mostly at the parallel shocks).

Model	β_n	Injection	$\Omega_{o\parallel}$	$\left(\frac{\delta B}{B}\right)_{s\parallel}$
A	1	iso	0.4	0.3
B	0.2			
C	0.5			
D	2			
E	5			
F		qpar		
G			10	
H				1
I			10	1

the partially turbulent MF: the area of the region with brightness between 2.5 and 3 units is larger in Fig. 10(a) comparing to Fig. 8(a). This is because the Stokes parameter I is higher if we consider the turbulent MF, equation (19); this effect should be more prominent if $\delta B/B$ is larger than unity (Fig. 2). Another feature is visible on the same maps, in the shape of the grey-scale border marked by the value 3: in Fig. 10(a) it is like } while it is like) in Fig. 8(a). The reason of this difference is that the ratio $\delta B/B$ is smaller in the perpendicular shock compared to the parallel one: the shock compression factor for B increases from 1 to 4 respectively while δB depends on the cosine of the obliquity angle, equation 67; thus, $\delta B \rightarrow 0$ towards the perpendicular shock (which is projected as a

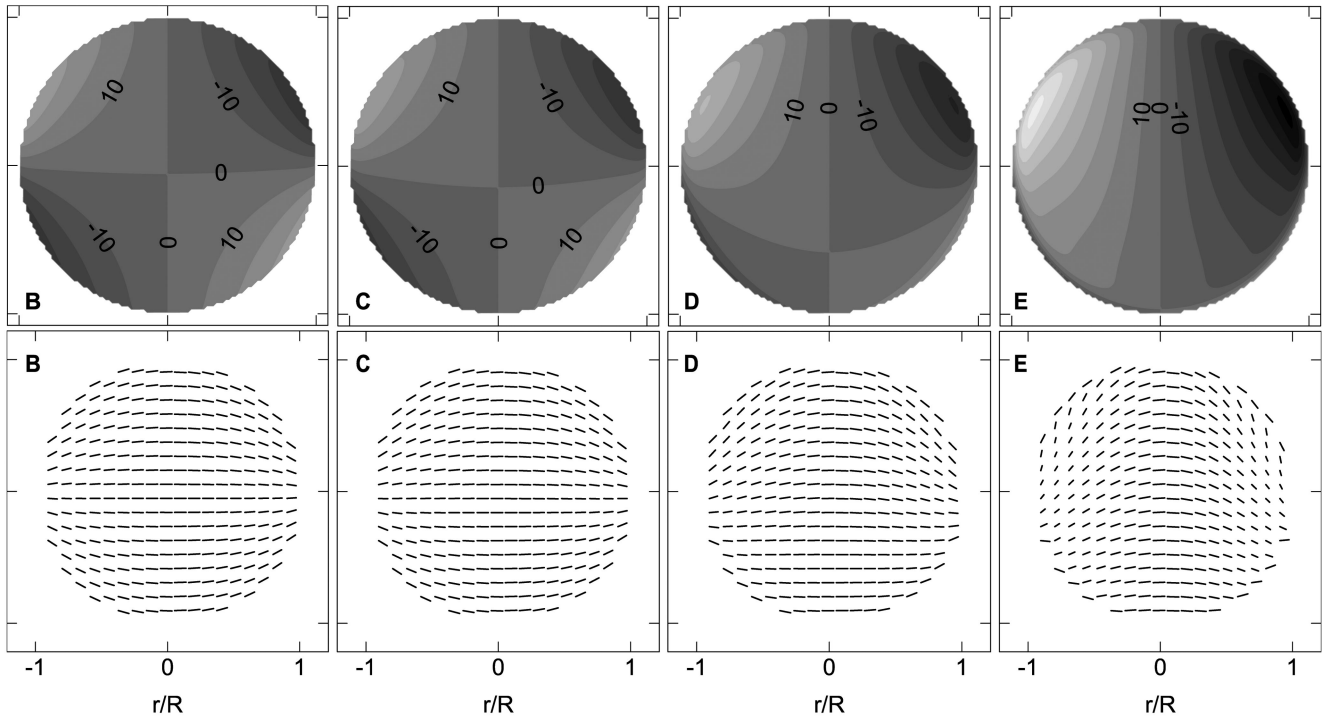


Figure 10. The same as in Fig. 7 but including the internal Faraday rotation and the disordered MF. Model A from Table 1. Grey-scale for (d): min 0.46, max 0.7, step 0.03. $\Pi_{\min} = 0.488$, $\langle \Pi \rangle = 0.602$.

vertical diameter) and the brightness decreases to the value it has without the turbulent MF.

More prominent differences are in the map of the polarization fraction (Fig. 10d, to be compared with Fig. 8d). As expected, the disordered MF depolarizes emission: the area of highly polarized regions is considerably smaller; these regions are located where the perpendicular shock is projected with $\delta B \rightarrow 0$. The values of $\Pi_{\min} = 0.488$ and $\langle \Pi \rangle = 0.602$ show how strong is this effect (to be compared to the maximum possible value 0.692). The polarization fraction is smaller for the same model if the angle ϕ_o between ISMF and the line of sight is smaller. In particular, $\Pi_{\min} = 0.007$ and $\langle \Pi \rangle = 0.428$ for $\phi_o = 60^\circ$.

As we already noticed in Section 5.1, the internal Faraday effect changes the measured polarization directions and the overall effect of Faraday rotation on SNR images depends on a parameter β_n , equation (113). The role of β_n in determining the pattern of the ‘observed MF directions’ is apparent from Fig. 11 where these patterns are calculated for models B–E in Table 1 (see also model A in Figs 10e and f).⁸ The polarization images are sensitive to $\beta_n \geq 0.5$. The larger the parameter β_n , the stronger the effect of the internal Faraday rotation.

Dickel & Milne (1976) have suggested that a change of the ‘inferred MF’ directions from the radial to the mostly tangential one could be the evolutionary trend from young to old SNRs. Since R is increasing with the SNR age, we checked if such a temporal trend is visible with the increase of β_n in our model. In fact, there is no clear trend from preferentially radial to tangential polarization

directions in our model (Fig. 11). Since we consider here the Sedov phase only, our results agree with the expectation of Dickel & Milne (1976) that the change in MF orientation is ‘possibly corresponding to the first and third evolutionary phases of an SNR discussed by Woltjer (1970).’ In fact, (i) we do not consider ejecta (Sedov model is just the point explosion) and thus the MHD instabilities that might result in the radial ‘fingers’ in young SNRs (e.g. Orlando et al. 2012) are not accounted for; (ii) the radiative losses of the shocked plasma (efficient after the Sedov stage) increase the tangential component of MF in old SNRs (Petruk et al. 2016). Future simulations have to be extended to the SNR ages before and after the adiabatic phase in order to reconsider the idea of Dickel & Milne (1976), which seems to be confirmed by recent observations (Dubner & Giacani 2015).

Another observed property – decrease of the polarization at lower frequencies – is restored in our simulations. In fact, the polarization is smaller for larger β_n (Fig. 11, look at values of $\Pi_{\min}$ and $\langle \Pi \rangle$) and β_n inversely depends on the frequency $\beta_n \propto \lambda^2 \propto \nu^{-2}$.

Till now, we have considered the SNR projections for the aspect angle $\phi_o = 90^\circ$, i.e. when the uniform ISMF lies in the projection plane. The polarization is smaller for other orientations of the ambient MF versus the observer (Fig. 12). We see again that the main factor determining the polarization patterns is the internal Faraday rotation. Our simulations demonstrate that the SNR images do not generally reflect the actual orientation of MF inside SNR because they give the polarization directions of emission affected by the internal Faraday rotation. The larger the role of the internal Faraday rotation (i.e. the higher β_n), the less similar is the observed polarization pattern to the actual orientation of MF in SNR. Therefore, observed patterns may not be used to extract the MF orientations in SNR until it is proved that the internal Faraday rotation is negligible (i.e. that $\beta_n < 0.5$; for example, observing at a high enough frequency, the Faraday rotation becomes asymptotically

⁸ The image of I has the same pattern (though with different amplitude) for models A–E because β_n does not affect the contrasts in the map of this Stokes parameter.

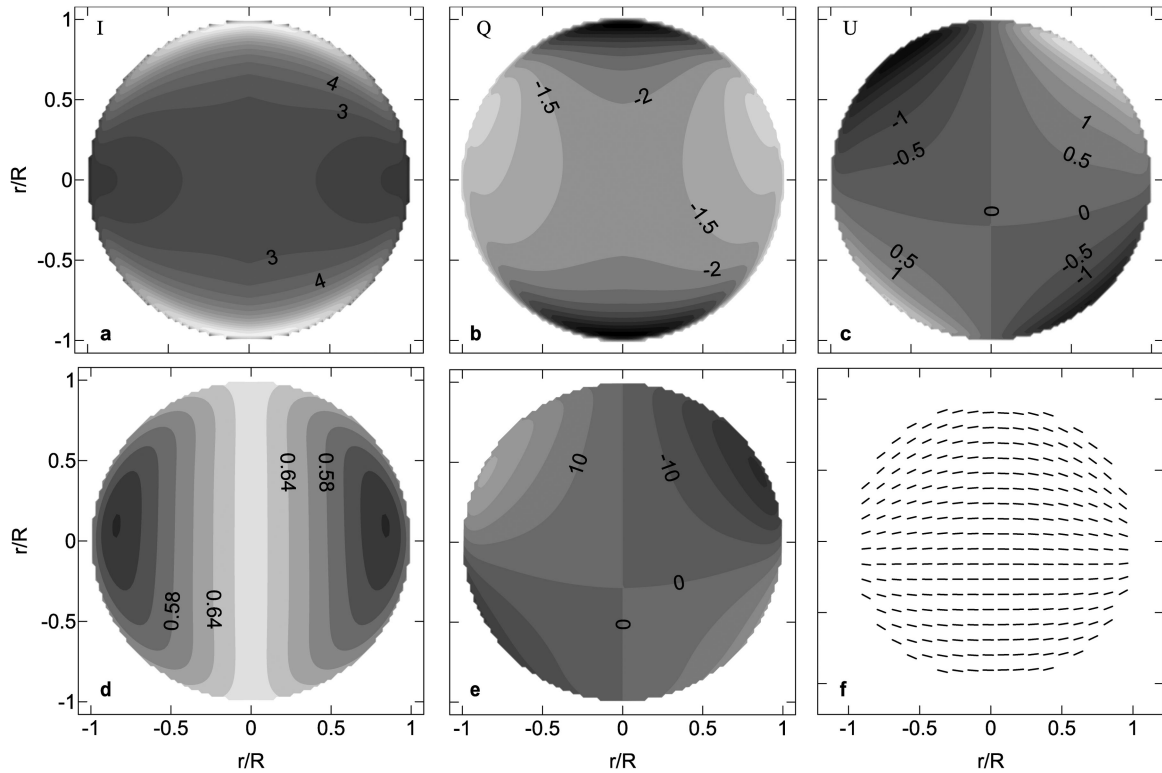


Figure 11. Maps of Ψ (upper panels) and of the inferred ‘directions of MF’ (lower panels) for different β_n (models B–E, marked on the respective plots; to be compared to model A, Figs 10e and f). Aspect angle $\phi_o = 90^\circ$. $\Pi_{\min}$ and $\langle \Pi \rangle$ are respectively: 0.505 and 0.607 (B), 0.502 and 0.606 (C), 0.439 and 0.588 (D), 0.183 and 0.501 (E).

negligible, see e.g. the moments approach in Paper I). This is clearly seen by comparing lower panels in Figs 12 and 13; in the latter one, the images are calculated for the value $\beta_n = 0$ and the maps trace therefore the orientation of MF.

It is visible in our images that the Faraday effect could be responsible for the spatial domains in the maps with abrupt change of the polarization directions. This is a feature observed in many SNRs (e.g. Dubner & Giacani 2015).

If injection preferentially happens at the parallel shocks (model F), then the images of I and of the polarized emission $\sqrt{Q^2 + U^2}$ have maxima located around the parallel shock regions, where emitting particles reside (Fig. 14). Some increase of the polarization fraction from the SNR as a whole is prominent comparing to the isotropic injection case (compare values of $\Pi_{\min}$, $\langle \Pi \rangle$ and $\Pi_{\max}$ given in the figure captions).

How do the properties of the turbulent MF affect images of polarized emission of SNRs? Two parameters in our model regulate behaviour of waves in SNR. The first one, $\Omega_{o\parallel}$, is Ω immediately before the parallel shock. This parameter, defined by equation (52), determines the ratio between the rates of the wave growth and damping (see equation 56). The value $\Omega_{o\parallel} = 0.4$ in the basic model A brings us to the limiting case of the small wave damping (Fig. 3). In this regime, the pressure of waves decreases to zero towards the regions of the perpendicular shock, equation (67). The role of the fluctuating field is therefore prominent mostly around the regions with the parallel shocks (i.e. around ‘poles’ that are on the left and right edges of images with $\phi_o = 90^\circ$). Another limit of the wave evolution, when the growth and damping of waves have the same rates, is represented by model G. Now, the ratio of the rates does not depend on the obliquity. Thus, the effect should lead to overall decrease of the polarization fraction (because of increase

of the volume with turbulent MF) and morphological differences, mostly where the regions with the perpendicular shocks are projected. This is what we see in Fig. 15 (models A and G).

The second parameter that determines properties of the waves is the ratio $(\delta B/B)_{\parallel}$. We have seen that the differences between images with and without fluctuating component of MF are rather small. The reason is that the role of the disordered MF in the SNR images is not strong because of the small value $(\delta B/B)_{\parallel} = 0.3$. Such a value was taken because our model assumes that the nature of the fluctuating MF is Alfvén waves. Theory for these waves implicitly assumes $\delta B \ll B$. Nevertheless, in order to see what could be the effect of the stronger waves, we run simulations also for models H and I, with $(\delta B/B)_{\parallel} = 1$ (Fig. 15). These simulations are done just to imagine an effect of efficient disordered MF on the polarized emission from SNRs. The main effects are the increase of the surface brightness with increase of $\delta B/B$ and the decrease of the polarization fraction, in agreement with Fig. 2.

The model in the present paper is based on a principal condition of unmodified shocks. To this extent, our model is self-consistent: we consider test-particle acceleration, Alfvén waves, no MF amplification in the precursor due to CR streaming. This is in agreement with our assumption of adiabatic SNRs, which is typically applied to evolved SNRs where the CR backreaction is not effective, as commonly agreed, and as we have shown in Bandiera & Petruk (2010) with our statistical analysis. We hope that in the future the effects of the non-linear particle acceleration as well as other modes (including Bell’s one) of waves on the polarized images of SNRs may be considered, in a self-consistent way. We would like to note that there are almost no studies (see review in the introduction) where the overall maps of the SNR surface brightness are considered with the non-linear effects included (though there are papers

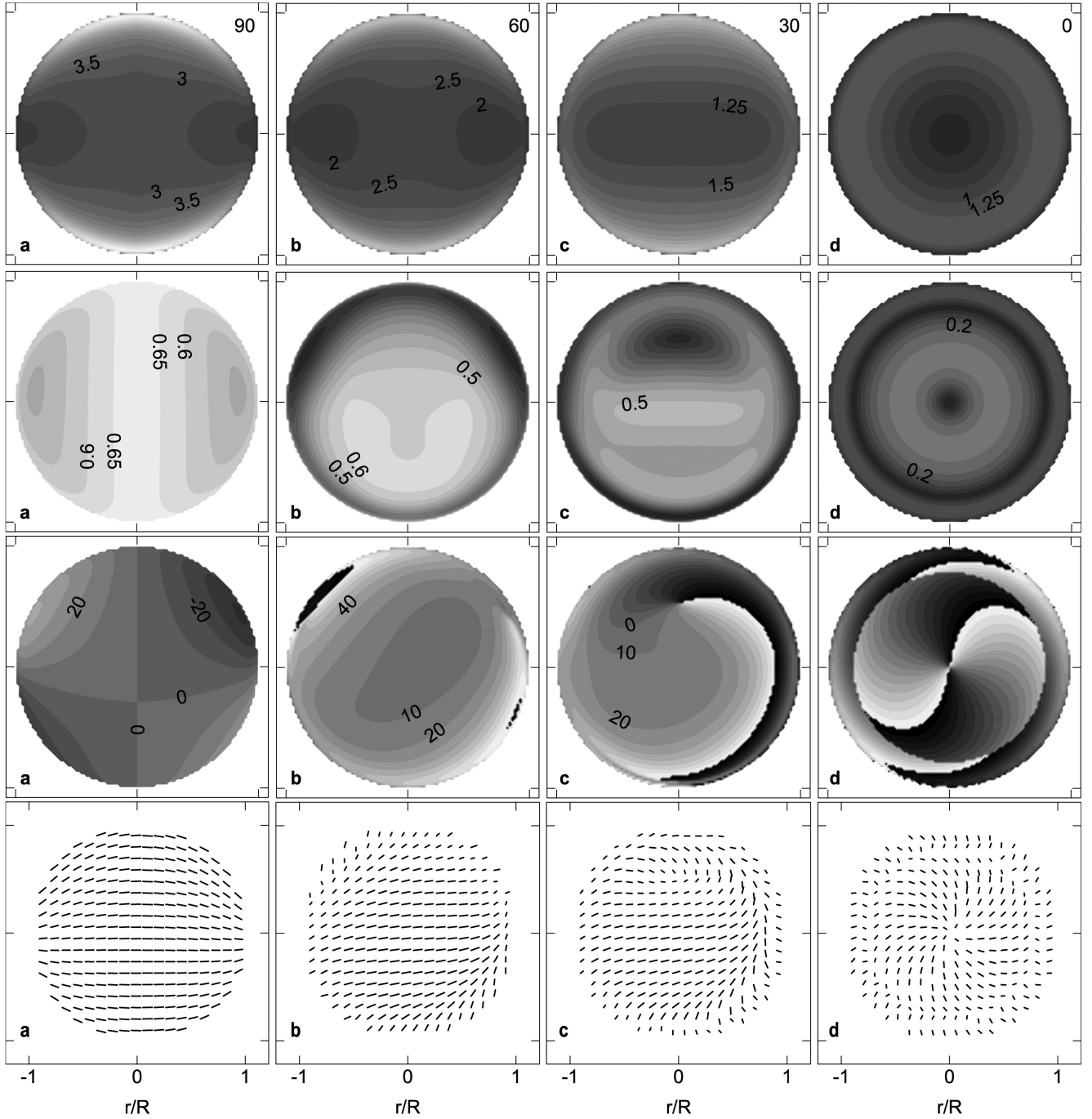


Figure 12. Maps of I (upper panels), Π , Ψ and inferred ‘directions of MF’ (lower panels) for model A and different aspect angles ϕ_0 : a – 90° , b – 60° , c – 30° , d – 0° . Component of ISMF in the projection plane is along the horizontal axis. Scale for I : min 0.5 (black), max 9.5 (white), step 0.5 (a and b), min 0.25, max 4.75, step 0.25 (c and d), in arbitrary units. Scale for Π : min 0 (black), max 0.7 (white), step 0.05. Scale for Ψ : min -90° (black), max 90° (white), step 10° . $\Pi_{\min}$, $\langle \Pi \rangle$ and $\Pi_{\max}$ are respectively: 0.488, 0.602, 0.691 (a), 0.007, 0.428, 0.642 (b), 0.001, 0.331, 0.579 (c), 0.000, 0.187, 0.317 (d).

dealing with such effects locally, e.g. close to the shock only). In order to study these effects in the polarization images, one has to invest much more effort than to simulate the brightness maps.⁹

⁹ Though some aspects of the problem are studied, to our knowledge, there is neither model nor numerical simulations that consider both MF amplification and its evolution deep downstream in the whole SNR volume, for any obliquity. The reason is the different time- and length-scales: the am-

plification involves microphysics that develops on the scale of the shock precursor while MF evolves downstream on the scales of the SNR radius. In the present paper, we consider the Alfvén waves because their theory is well developed.

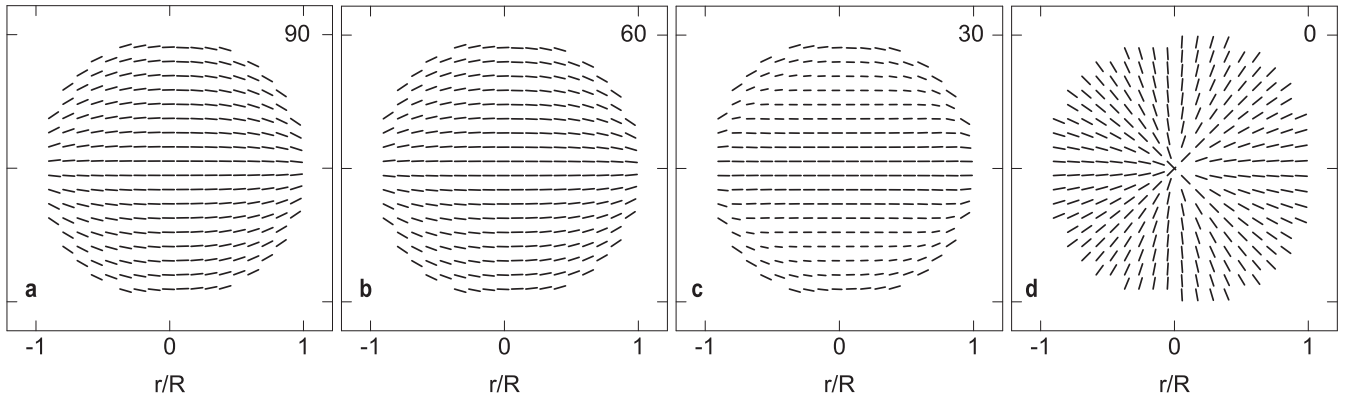


Figure 13. The same as lower panels in Fig. 12, for $\beta_n = 0$.

(2010) and is implemented, in particular, in our papers on SNR images (Orlando et al. 2011; Petruk et al. 2011b). It consists in the use of an ‘effective’ adiabatic index $\gamma = 4/3$ or even $\gamma = 1.1$, which is intended to mimic, respectively, a moderate and a strong shock modification. With these indices, the shock compression is higher: $\sigma = 7$ and 21, respectively (to be compared to the classical value $\sigma = 4$ for $\gamma = 5/3$). The consequences of such an approach are the radially thinner features in the brightness images [e.g. fig. 7 in Orlando et al. (2011) and approximate analytical formulation in Petruk et al. (2011b)]. In addition, the increased compression ratio decreases the electron spectral index s ($s = 1.5$ and 1.15, respectively). This results in a small change of the Stokes parameters Q and U (fig. 1 of Paper I) and $\Pi_{\max}$ [according to equation (18); it is 0.652 and 0.617, respectively, while $\Pi = 0.692$ for $\gamma = 5/3$], and is completely ineffective to change the ratio $\Pi/\Pi_{\max}$ (fig. 2 of Paper I). Therefore, we expect that the non-linear acceleration will create higher order corrections to our test-particle results that are able to catch the most prominent effects.

6 CONCLUSIONS

The present paper is devoted to development of the model and to simulations of images of the polarized synchrotron emission from Sedov SNRs. The main goal is a general analysis of the polarization maps. Namely, we are interested to see how the properties of SNR, its internal structure and the turbulent component of MF affect the polarization patterns of these objects. We leave discussion on certain objects to future studies.

Some aspects of the problem were considered by Schneiter et al. (2015), in limits of the negligible internal Faraday rotation and of the zero turbulent component of MF. The approach we developed in Paper I and in the present paper accounts for both of these components.

In order to model polarized emission from relativistic electrons in SNRs, we have solved the *two essential problems*. First, the classical theory of synchrotron emission has to be generalized to describe the emissivity in the ordered plus disordered MF. A way to such generalization is presented in Paper I; it restores, in the limit $\delta B \ll B$, the known description. Secondly, the distribution of the disordered MF component has to be known inside the SNR interior. To this purpose, we developed a model for the evolution of the random component of MF downstream of the adiabatic shock under the assumption that it is due to the growth and damping of Alfvén waves. This type of waves is suitable because the whole task is complex in itself but the physics of the Alfvén waves is more or

less known. In doing so, we consider the interactions of waves with particles accelerated by the SNR forward shock. To this extent, our treatment is non-linear: evolution of waves is connected to relativistic particles. However, we do not consider possible influence of particles and waves on the MHD structure of SNR. The evolution of the random MF component is considered to be on the MHD ‘background’ of Sedov shock.

Having traced the 3D distribution of all the relevant physical quantities inside SNR, we can consider the detailed spatial distribution of the polarized radio emission and synthesize the projected images of polarization parameters under different SNR orientations with respect to the observer.

Our assumption of adiabatic SNRs implicitly shifts the attention towards not very young SNRs, namely to the cases in which the effects of the non-linear particle acceleration should not be important. Probably, it could be worth specifying this: we miss some part of generality, but we are right in the frames of the clearly described model that may be applied to many SNRs.

We have demonstrated that the random MF component reduces the polarization fraction, as expected. A new effect is that the presence of the random MF component increases the synchrotron emissivity (Fig. 2). This produces important consequences for fitting the broad-band SNR spectra. If, for example, $\delta B \sim B$, then the synchrotron flux is twice the flux for the case where the random MF is neglected.

The role of the Faraday effect *in the SNR interior* (i.e. the different rotation of the polarization plane from each point along the line of sight inside SNR) is important in formation of the Stokes parameter maps. The uniform derotation of the observed polarization maps might give a ‘true’ image of MF only if the internal Faraday rotation is negligible, that is the exception rather than the rule. The uniform derotation corrects for the Faraday effect in ISM (between the SNR and the observer) but not for the internal rotation that varies essentially over the SNR projection. The pattern of the polarization maps is affected by the internal Faraday rotation if the parameter β_n (equation 113) is greater than $\simeq 0.5$.

Our simulations restore the observed properties: (i) there are polarization domains with abrupt change of polarization direction in SNR maps; (ii) the polarization fraction is small; (iii) the polarization fraction decreases for larger λ .

As discussed in Section 5.1, the simulated maps presented here show a general agreement with those already presented in Paper I. The main differences can be noticed close to the SNR projected edge, as a consequence of the fact that we have released here the thin-shell approximation. This leads essentially to two kinds of

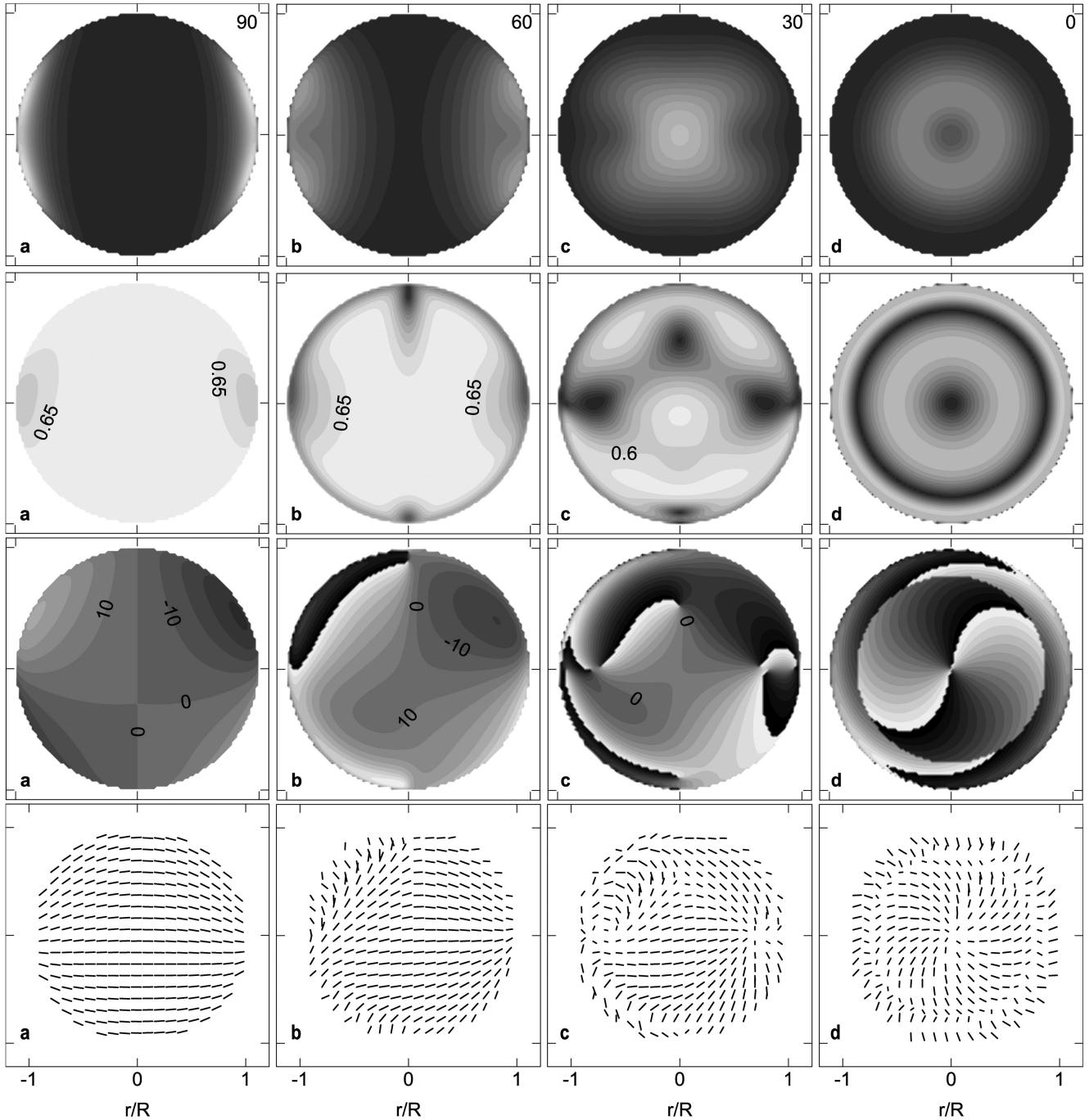


Figure 14. The same as Fig. 12, for the quasi-parallel injection (model F). Min, max and step for I are 5 times (a) and 10 times (b–d) less than in Fig. 12. Grey-scale for Π is min 0, max 0.7, step 0.05. $\Pi_{\min}$, $\langle \Pi \rangle$ and $\Pi_{\max}$ are respectively: 0.565, 0.675, 0.691 (a), 0.062, 0.605, 0.691 (b), 0.005, 0.474, 0.665 (c), 0.000, 0.391, 0.570 (d).

effects: (i) the presence of a shell with a finite geometrical thickness leads to a shift of some features away from the edge, giving rise to features like, for instance, some ‘islands’ now appearing in maps of the polarization fraction; (ii) the fact that the direction of projected MF now can change along the line of sight enhances the level of depolarization, and this effect is even more apparent in the cases with a low local random MF component.

In Paper I, we have drawn the basis to treat the synchrotron emission in a partially ordered MF, as well as to model the basic

and most important geometrical aspects in a shell-type SNR. In the present paper, we have added a treatment of the physics of particle acceleration and evolution, in a test-particle regime. The similarity between the results in these two papers should be seen as a proof of the validity of the simplified approach chosen for Paper I. The simpler thin-layer approach may be used in the cases when one needs an idea about the overall pattern of polarization images. When, however, the goal is to understand the observed patterns or to study some details in images, then 3D simulations

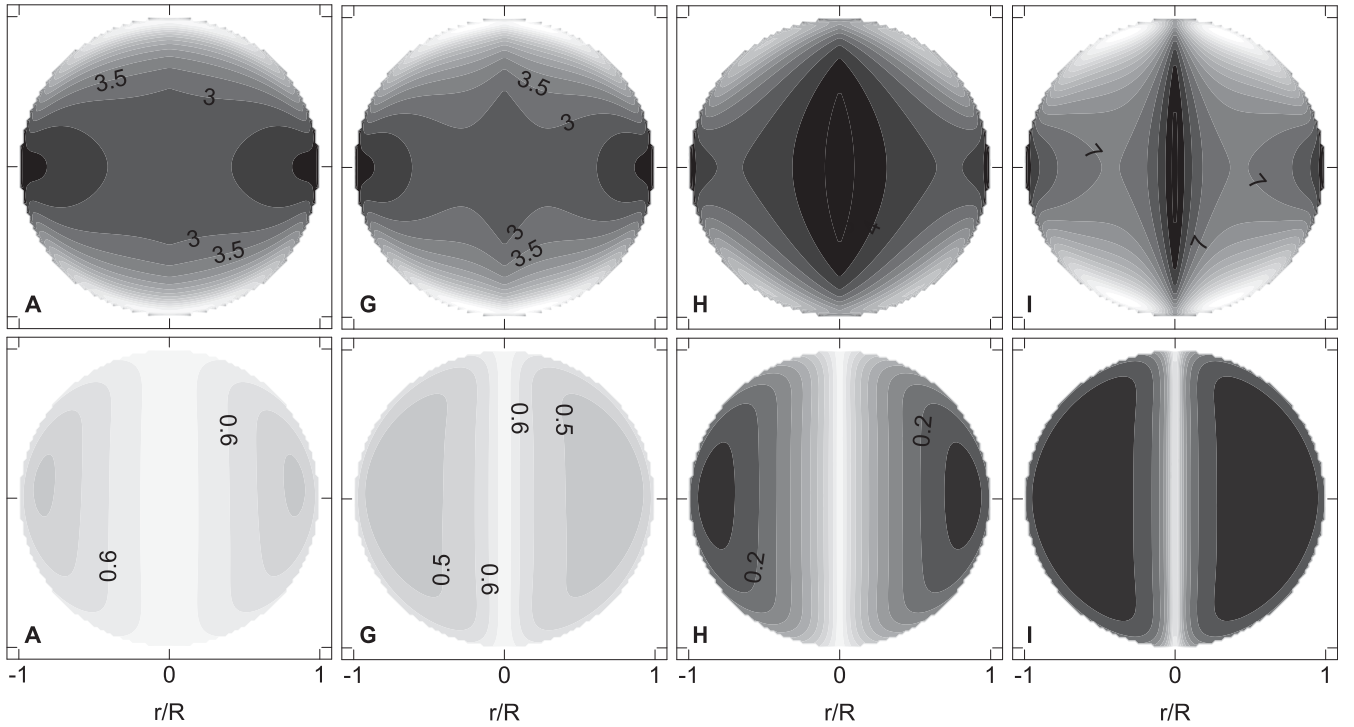


Figure 15. Maps of I (upper panels) and Π (lower panels) for models A, G, H, I (marked on the plots). $\phi_0 = 90^\circ$. The only maps of I and Π are presented because other images (Q , U , Ψ) are very similar in all these models. Min, max and step for I in a and b are the same as in Fig. 7; they are two times larger in c and d. Grey-scale for Π : min 0, max 0.7, step 0.05. $\Pi_{\min}$, $\langle \Pi \rangle$, $\Pi_{\max}$ are 0.488, 0.602, 0.691 (A), 0.456, 0.533, 0.686 (G), 0.127, 0.309, 0.678 (H), 0.105, 0.181, 0.626 (I).

are needed. We believe that an advantage of our approach is that it could be implemented, with a moderate effort, to some real cases, with more complicate geometry.

There are pieces of observational evidence (Dickel & Milne 1976; Dubner & Giacani 2015) that patterns of polarization maps of the young SNRs demonstrate predominantly radial orientation of the projected MF directions while maps of the older SNRs have mostly tangential orientation. Our simulations suggest that, in order to restore this effect numerically, the model has to go beyond the ‘point-explosion’ approach and beyond the adiabatic stage, in order to treat the ejecta–ISM interactions in the young SNRs and the influence of the radiative losses of the shocked plasma on the MF.

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APPENDIX A: COMPONENTS OF MF

In this appendix, we present the formulae to calculate the components of MF.

Let us consider the reference frame with z -axis directed towards the observer. The ambient MF is in the yz plane (without loss of generality). The aspect angle ϕ_o is the angle between the ambient MF $\mathbf{B}_o$ and the line of sight. The corresponding spherical coordinates are (r, θ, φ) .

In each point, MF $\mathbf{B}$ is a vector sum of the radial $\mathbf{B}_r$ and the tangential $\mathbf{B}_t$ components that may be rewritten as $\mathbf{B} = \bar{B}_r \mathbf{B}_{ro} + \sigma \bar{B}_t \mathbf{B}_{to} = \bar{B}_r \mathbf{B}_{ro} + \sigma \bar{B}_t (\mathbf{B}_o - \mathbf{B}_{ro})$, where $\bar{B}_r = B_r/B_{rs}$, $\bar{B}_t = B_t/B_{ts}$, indices ‘s’ and ‘o’ mark the immediate post- and pre-shock values, σ is the shock compression factor. Therefore,

$$\mathbf{B} = \sigma \bar{B}_t \mathbf{B}_o + (\bar{B}_r - \sigma \bar{B}_t)(\mathbf{B}_o \cdot \mathbf{n})\mathbf{n}, \quad (\text{A1})$$

where $\mathbf{n}$ is the unit vector in the radial direction. The projection of $\mathbf{B}$ on the Cartesian x -axis is given by the dot product

$$B_x = (\mathbf{B} \cdot \hat{x}) = \sigma \bar{B}_t B_{ox} + (\bar{B}_r - \sigma \bar{B}_t) B_o \cos \Theta_o n_x, \quad (\text{A2})$$

where Θ_o is the shock obliquity angle. Expressions for B_y and B_z are the same but the index ‘ x ’ should be changed to ‘ y ’ and ‘ z ’, respectively. The Cartesian components of $\mathbf{n}$ are $(\sin \theta \cos \varphi, \sin \theta \sin \varphi, \cos \theta)$. The components of $\mathbf{B}_o$ are $(0, B_o \sin \phi_o, B_o \cos \phi_o)$. Taking all these together, we have the MF components:

$$\begin{aligned} B_x/B_o &= (\bar{B}_r - \sigma \bar{B}_t) \cos \Theta_o \sin \theta \cos \varphi, \\ B_y/B_o &= \sigma \bar{B}_t \sin \phi_o + (\bar{B}_r - \sigma \bar{B}_t) \cos \Theta_o \sin \theta \sin \varphi, \\ B_z/B_o &= \sigma \bar{B}_t \cos \phi_o + (\bar{B}_r - \sigma \bar{B}_t) \cos \Theta_o \cos \theta. \end{aligned} \quad (\text{A3})$$

As to the obliquity angle, it is given by the dot product $\cos \Theta_o = (\mathbf{B}_o \cdot \mathbf{n})/B_o$ and is therefore

$$\cos \Theta_o = \sin \phi_o \sin \theta \sin \varphi + \cos \phi_o \cos \theta. \quad (\text{A4})$$

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