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Quasar Accretion Disk Sizes from Continuum Reverberation Mapping in the DES Standard-star Fields

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Abstract

Measurements of the physical properties of accretion disks in active galactic nuclei are important for better understanding the growth and evolution of supermassive black holes. We present the accretion disk sizes of 22 quasars from continuum reverberation mapping with data from the Dark Energy Survey (DES) standard-star fields and the supernova C fields. We construct continuum light curves with the *griz* photometry that span five seasons of DES observations. These data sample the time variability of the quasars with a cadence as short as 1 day, which corresponds to a rest-frame cadence that is a factor of a few higher than most previous work. We derive time lags between bands with both JAVELIN and the interpolated cross-correlation function method and fit for accretion disk sizes using the JAVELIN thin-disk model. These new measurements include disks around black holes with masses as small as $\sim 10^7 M_\odot$, which have equivalent sizes at 2500 Å as small as ~ 0.1 lt-day in the rest frame. We find that most objects have accretion disk sizes consistent with the prediction of the standard thin-disk model when we take disk variability into account. We have also simulated the expected yield of accretion disk measurements under various observational scenarios for the Large Synoptic Survey Telescope Deep Drilling Fields. We find that the number of disk measurements would increase significantly if the default cadence is changed from 3 days to 2 days or 1 day.

Unified Astronomy Thesaurus concepts: Quasars (1319); Supermassive black holes (1663); Accretion (14); Active galactic nuclei (16); Reverberation mapping (2019)

Supporting material: data behind figure, figure set

1. Introduction

Active galactic nuclei (AGNs) are powered by an accretion disk formed by gas accreted onto a galaxy’s central supermassive black hole (SMBH). The accretion disk produces multitemperature blackbody emission, with a peak that is typically in the ultraviolet (UV). Studies of the size and structure of the accretion disk are important because they help to understand the growth of SMBHs and the evolution of AGNs.

The conventional accretion disk model is the geometrically thin, optically thick disk model (Shakura & Sunyaev 1973). The disk is internally heated by viscous dissipation. Later modifications of the model include external heating by the UV/X-ray source near the SMBH (e.g., Haardt & Maraschi 1991). The disk has a temperature gradient, reaching about 10^5 – 10^6 K near the center and getting colder at larger radii (e.g., Shakura & Sunyaev 1973; Shields 1978). In this model, the temperature profile has the form $T(R) \propto R^{-3/4}$ over a large range of R , where R is the distance from the central SMBH.

It is common to assume that the continuum is well characterized by multitemperature blackbody emission where the annulus at radius R is emitting as a blackbody with temperature $T(R)$ (e.g., Collier et al. 1998; Morgan et al. 2010; Jiang et al. 2017; Mudd et al. 2018). We consequently expect longer-wavelength emission to primarily originate at larger radii. The disk size at effective wavelength λ , defined as the position where $kT(R_\lambda) = hc/\lambda$, scales with wavelength as $R_\lambda \propto \lambda^\beta$, where $\beta = 4/3$ in the standard thin-disk model. Accretion disks are too small to be spatially resolved, and current measurements of the size of accretion disks are mainly from microlensing (e.g., Morgan et al. 2010) and continuum reverberation mapping (RM; e.g., Shappee et al. 2014; Fausnaugh et al. 2016; Jiang et al. 2017; Mudd et al. 2018; Homayouni et al. 2019).

Accretion disk size measurements from continuum RM rely on measurements of continuum lags between bands at different wavelengths. If the variation of the continuum emission from the accretion disk is driven by the variation of a central illuminating source, such as the “lampost” model (e.g., Cackett et al. 2007), the variation at longer wavelengths is expected to lag the variation at shorter wavelengths owing to the light-travel time from the inner disk to the outer disk. The lag between two wavelengths λ

and λ_0 is

$$\tau = \frac{R_{\lambda_0}}{c} \left[\left(\frac{\lambda}{\lambda_0} \right)^\beta - 1 \right], \quad (1)$$

where R_{λ_0} is the effective disk size at wavelength λ_0 . Equation (1) states that the disk size is related to the time lag between two light curves at different wavelengths. This approach to measuring the accretion disk size is called “continuum RM.”

One algorithm used to measure lags is the interpolated cross-correlation function (ICCF), which cross-correlates the linearly interpolated light curves and calculates the lag as the center or peak of the cross-correlation function (e.g., Peterson et al. 1998, 2004). Another method is JAVELIN, which models the variability of AGNs as a damped random walk (DRW) stochastic process and fits for the lag (e.g., Zu et al. 2011, 2013). Simply fitting the continuum lags in different photometric bands with the thin-disk model can provide the accretion disk size at a given wavelength. In addition, Mudd et al. (2018) presented an alternate method to obtain the disk size, the JAVELIN thin-disk model, which assumes a thin-disk model from the outset and then fits for the thin-disk parameters (R_{λ_0} , β) directly that best reproduce a series of light curves of known effective wavelengths, instead of using the individual lags to find a disk size through Equation (1).

Early studies to measure accretion disk sizes with continuum RM include Wanders et al. (1997) and Collier et al. (1998), which measured the continuum lags of NGC 7469 at UV and visible wavelengths, respectively. Sergeev et al. (2005) measured the interband lags of 14 AGNs and found that the lags scale with the luminosity as L^b , where $b \approx 0.4$ – 0.5 . Recently, several studies obtained accurate measurements of continuum lags using intensive observations spanning from the X-ray to the near-infrared, including Shappee et al. (2014) for NGC 2617, Edelson et al. (2015) and Fausnaugh et al. (2016) for NGC 5548, Edelson et al. (2017) for NGC 4151, Cackett et al. (2018) and McHardy et al. (2018) for NGC 4593, and Fausnaugh et al. (2018) for MCG +08-11-011 and NGC 2617. Other studies have used observations from large sky surveys to measure the accretion disk sizes from larger samples. Jiang et al. (2017) measured the continuum lags of 39 quasars using light curves from Pan-STARRS. Mudd et al. (2018) used the

photometric data on the supernova fields of the Dark Energy Survey (DES) and obtained disk size measurements of 15 quasars. Homayouni et al. (2019) presented the continuum lags of 95 quasars from the photometric data for the Sloan Digital Sky Survey (SDSS) RM project.

Some studies, including Fausnaugh et al. (2016) and Jiang et al. (2017), as well as most microlensing studies like Morgan et al. (2010), found that the accretion disks are larger than the prediction of the thin-disk model by a factor of 2–3. One possible explanation of the larger disk sizes is nonthermal disk emission caused by a low-density disk atmosphere (Hall et al. 2018). Another explanation is a disk wind that leads to a higher effective temperature in the outer part of the accretion disk (e.g., Li et al. 2019; Sun et al. 2019). Gaskell (2017) found that the internal reddening of AGNs that leads to an underestimation of the far-UV luminosity can be an explanation of the discrepancy as well. Contamination by the diffuse continuum from the broad-line region (BLR; e.g., Korista & Goad 2001; Lawther et al. 2018) may lead to larger disk size measurements from continuum RM. In addition, an inhomogeneous disk with significant local temperature fluctuations may also explain the larger disk sizes from microlensing studies (Dexter & Agol 2011). However, Mudd et al. (2018) and Homayouni et al. (2019) did not find systematic trends of larger disk sizes than the prediction of the thin-disk model. To address this discrepancy, more disk size measurements are required, especially using high-cadence time series data.

In this paper, we present disk size measurements using the photometric data in the DES standard-star fields and the supernova C (SN-C) fields. The structure of this paper is as follows. Section 2 introduces the photometric data we use. Section 3 introduces the methodology and results of the time series analysis, including the lag and disk size measurements. In Section 4 we discuss various tests we performed to verify the measurements. In Section 5 we describe our measurements of the correlation between the accretion disk size and the mass of the SMBH. Section 6 discusses the objects without lag measurements. In Section 7 we present simulations of the Large Synoptic Survey Telescope Deep Drilling Fields and quantify the effect of observational cadence on lag measurements. Section 8 summarizes the paper. Throughout the paper we adopt Λ CDM cosmology with $H_0 = 70 \text{ km s}^{-1} \text{ Mpc}^{-1}$, $\Omega_m = 0.3$, and $\Omega_\Lambda = 0.7$.

2. Observations

DES is a ground-based, wide-area, visible, and near-infrared imaging survey (Abbott et al. 2018). DES started Commissioning and Science Verification (SV) observations in 2012, and the main survey began in 2013. DES uses the Dark Energy Survey Camera (DECam), a 570 MP, $2^\circ 2'$ field-of-view camera installed on the 4 m Victor M. Blanco telescope at the Cerro Tololo Inter-American Observatory (Flaugher et al. 2015). DES includes a 5000 deg^2 wide-area survey in the *grizY* bands, as well as 27 deg^2 in the *griz* bands that are repeatedly imaged to identify and characterize supernovae. DES typically observes standard-star fields in morning and evening twilight for calibration, and occasionally around midnight as well. Standard-star observations can have a nightly or even higher observational cadence in some fields, with a typical exposure time of 15 s for a single epoch. The high observational cadence supports accurate photometric RM analysis, despite the short exposure time.

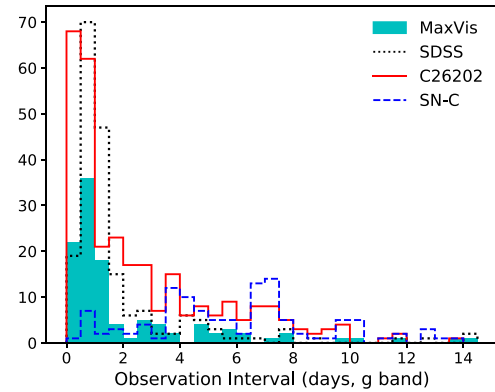


Figure 1. Time interval distribution between consecutive pairs of epochs for the light curve of a representative object in each field. The cyan filled, black dotted, red solid, and blue dashed histograms are the cadence distribution of DES J063037.48–575610.30 in the MaxVis field, DES J005905.51+000651.66 in the SDSS fields, DES J033408.25–274337.81 in the C26202 field, and DES J034001.53–274036.91 in the SN-C fields, respectively.

We use standard-star observations from the DES SV period through Year 4 (Y4) in the MaxVis field, the C26202 fields, and six other fields within the SDSS footprint. We incorporate spectroscopic data for the MaxVis and the C26202 fields from the Australian DES/Optical redshifts for DES (OzDES) program, a spectroscopic survey with the Anglo-Australian Telescope that was designed to follow up targets identified from DES (Yuan et al. 2015; Childress et al. 2017).

2.1. MaxVis Field

The MaxVis field is centered at R.A. = $97^\circ 5'$, decl. = $-58^\circ 75'$. The field is observable throughout the DES observing season, and it was named because of this “Maximum Visibility.” We visually inspected all OzDES spectra flagged as nonstellar within the field, and we selected 130 quasars as candidates with spectroscopic redshifts from the OzDES Global Redshift Catalog (Childress et al. 2017). The cyan histogram in Figure 1 shows the observational cadence distribution of DES J063037.48–575610.30, a representative object in the MaxVis field. The distribution peaks around 1 day, indicating that most epochs for this object are obtained with a nearly daily cadence. The orange squares in Figure 2 show the magnitude uncertainty as a function of the *g*-band magnitude for the quasars in the MaxVis field. The depth of the MaxVis field is intermediate relative to the other standard-star fields.

2.2. SDSS Stripe 82 Fields

We use six fields near the celestial equator that overlap the SDSS Stripe 82 field (e.g., Adelman-McCarthy et al. 2007). We match DES observations to the color- and variability-selected quasar catalog from Peters et al. (2015) and select 884 objects as candidates with more than 200 epochs in the *grizY* bands from SV to Y4, among which 593 objects have spectroscopic redshifts. Similar to the MaxVis field, Figure 1 shows that the observational cadence in the SDSS fields is roughly daily. On the other hand, Figure 2 shows that the observations in the SDSS fields are shallower compared to the other fields.

2.3. C26202 and SN-C Fields

The C26202 field is centered on the standard star C26202 at R.A. = $53^\circ 1'$, decl. = $-27^\circ 85'$, which overlaps with the DES C1, C2, and C3 supernova fields. We match the DES detections

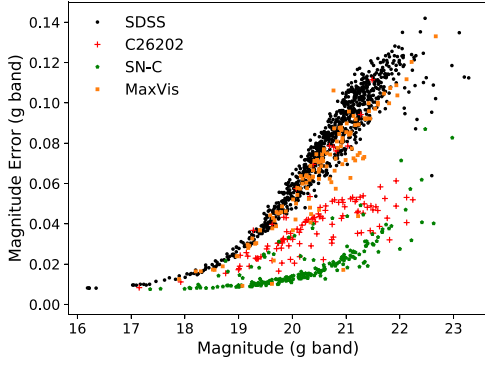


Figure 2. Magnitude uncertainty as a function of magnitude for g -band data for the four data sets. The orange squares, black circles, red plus signs, and green pentagons represent the objects in the MaxVis, the SDSS, the C26202, and the SN-C fields, respectively. The magnitude shown here is calculated as the mean magnitude of the object from SV to Y4, and the magnitude uncertainty is calculated as the mean magnitude uncertainty during this period. The magnitude uncertainties have included the calibration errors.

within a circle of $3^{\circ}5$ radius to the spectroscopically confirmed quasar catalog presented by Tie et al. (2017), and we selected 318 quasars as candidates with more than 200 epochs in the $griz$ bands from SV to Y4. Note that the candidates include not only quasars from the C26202 standard-star field but also quasars within the SN-C fields. The DES observations of the C26202 standard-star field include both approximately daily standard-star observations and approximately weekly supernova observations. Figure 1 shows the cadence distribution of a representative object in this field, where most observations are high-cadence standard-star observations shown by the peak around 1 day, while there are also supernova observations with longer intervals between epochs. Figure 2 shows that quasars within the C26202 standard-star field have the deepest observations (red plus signs) compared to the quasars within the other two, while the observations of quasars within the supernova fields (green pentagons) are even deeper. Hereafter we use “C26202 fields” to refer to both the C26202 standard-star field and the SN-C fields unless otherwise specified.

3. Time Series Analysis

We construct light curves using photometric data from the DES Y4A1 catalogs. We adopt the PSF magnitude and its error for the photometry and exclude bad epochs based on the DES data quality flags. For time series analysis, the calibration between epochs would add additional systematic errors. We adopt the typical error of the DES Forward Global Calibration Method (FGCM) from Burke et al. (2018) and combine it with the magnitude errors by quadrature to calculate the total uncertainty of each single epoch.

There are epochs separated by only minutes, which can be caused by the short acquisition images or the cosmic-ray separation of the supernova observations. Since the variations between these epochs are not likely to be intrinsic to the quasars, we exclude the short acquisition epochs and combine the supernova epochs separated by less than a half hour to avoid possible artifacts in further analysis. We assume that the seeing and the sky transparency do not vary significantly within this time range, and we calculate the magnitude and magnitude

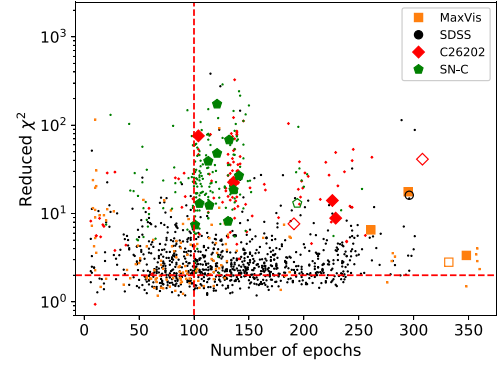


Figure 3. χ_r^2 as a function of the number of epochs. The orange squares, black circles, red diamonds, and green pentagons represent the objects from the MaxVis field, the SDSS fields, the C26202 standard-star field, and the SN-C fields, respectively. The small symbols represent the objects where we do not obtain good lag measurements. The large symbols represent the objects in the main sample, with the open symbols for the flagged objects. For the objects without lag measurements, χ_r^2 and the number of epochs are calculated from the season where χ_r^2 is the largest. For objects in the main sample, χ_r^2 and the number of epochs are from the season where the lags and disk sizes are measured. If an object has lag measurements from multiple seasons, χ_r^2 is from the earliest season that has lag measurements. The horizontal red dashed line is drawn at $\chi_r^2 = 2$, and the vertical line is drawn at $N_{\text{fit}} = 100$.

error of the combined epoch as

$$m_{\text{comb}} = \frac{\sum_i m_i / \sigma_i^2}{\sum_i 1 / \sigma_i^2}, \quad \sigma_{\text{comb}}^2 = \frac{1}{\sum_i 1 / \sigma_i^2}, \quad (2)$$

where m_i and σ_i are the magnitude and its statistical error of each single epoch. We combine σ_{comb} with the calibration error by quadrature to calculate the total uncertainty of the combined epoch.

We assess the variability of an object by calculating a χ^2 value defined as

$$\chi^2 = \sum_X \sum_i \left(\frac{m_{i,X} - \bar{m}_X}{\sigma_{i,X}} \right)^2, \quad (3)$$

where $m_{i,X}$ and $\sigma_{i,X}$ represent the magnitude and uncertainty of the i th data point in band X ($X = g, r, i, z, Y$) and $\bar{m}_X$ represents the mean magnitude in band X . We calculate the χ^2 values both for the whole SV–Y4 period and for the single seasons. We perform a time series analysis on objects and seasons that satisfy (1) $N_{\text{fit}} > 100$, where N_{fit} is the number of epochs in the season to analyze; (2) $N_{\text{other}} > 200$, where N_{other} is the number of epochs in all the other seasons that are not analyzed; and (3) $\chi_r^2 > 2$, indicating significant variability, where $\chi_r^2 = \chi^2 / (N_{\text{fit}} - 5)$ is the reduced χ^2 . There are 48 objects in the MaxVis field, 457 objects in the SDSS fields, and 297 objects in the C26202 fields that met the criteria in at least one observational season. Among these objects, about half of the objects in the MaxVis field and the SDSS fields have only one season that met the criteria, while most objects in the C26202 fields have at least two seasons. We analyze each season that passed the selection independently for computational convenience when measuring time lags. Quasars can have lag detections from multiple seasons, and we discuss this further in Section 3.1.

Figure 3 shows χ_r^2 as a function of the number of epochs for the candidates. The quasars within the SDSS fields show the

Table 1
Quasars in the Main Sample

Object Name	z	Field	Reference Line	M_{BH} ($10^8 M_{\odot}$)
DES J063037.48–575610.30	0.43	MaxVis	H β	1.23
DES J063510.91–585303.70	0.22	MaxVis	H β	0.23
DES J063159.74–590900.60	0.73	MaxVis	Mg II	2.00
DES J062758.99–582929.60	0.49	MaxVis	H β	0.20
DES J033002.93–273248.30	0.53	C26202	H β	0.80
DES J033408.25–274337.81	1.03	C26202	Mg II	1.18
DES J034003.89–264524.52	0.49	C26202	H β	0.44
DES J032724.94–274202.81	0.76	C26202	Mg II	1.71
DES J033545.58–293216.51	0.72	C26202	Mg II	0.82
DES J033810.61–264325.00	0.85	C26202	Mg II	2.05
DES J034001.53–274036.91	1.15	C26202	Mg II	1.98
DES J033853.20–261454.82	1.17	C26202	Mg II	2.65
DES J033051.45–271254.90	0.63	C26202	H β	0.61
DES J032853.99–281706.90	1.00	C26202	Mg II	5.65
DES J032801.84–273815.72	1.59	C26202	Mg II	3.28
DES J033230.63–284750.39	0.86	C26202	Mg II	1.49
DES J033729.20–294917.51	1.35	C26202	Mg II	1.95
DES J033220.03–285343.40	1.27	C26202	Mg II	1.37
DES J033342.30–285955.72	0.55	C26202	H β	2.05
DES J033052.19–274926.80	1.95	C26202	C IV	0.98
DES J033238.11–273945.11	0.84	C26202	Mg II	1.33
DES J005905.51+000651.66	0.72	SDSS	H β	8.87

Note. Basic parameters of the DES quasars in the main sample. Column (1): names of the objects. Column (2): redshifts. Column (3): field names. Column (4): emission lines used to estimate the black hole mass. Column (5): single-epoch estimate of the black hole mass (See Section 5). The uncertainty of the black hole mass is about 0.4 dex.

smallest variations relative to the photometric errors, while many quasars in the SN-C field have large χ_r^2 owing to the deep supernova observations.

In this work, we use JAVELIN, the JAVELIN thin-disk model, and the ICCF method to measure lags and derive disk sizes. We obtain good-quality disk size measurements for 22 quasars. We refer to these quasars as the “main sample.” The basic properties of these quasars are listed in Table 1, and disk size results are presented in Table 2. Seventeen of the 22 quasars form the most reliable subset of the measurements. The remaining five are flagged owing to inconsistencies of lags either between the observational seasons (flag = 1) or the analysis methods (flag = 2), or simulation results that imply lower reliability based on the observational data and an estimate of the disk size (flag = 3). The process of assigning flags is described in the next sections. We separate objects with and without flags in Table 2.

Figure 4 shows the light curves of six randomly selected unflagged objects in the observational season from which we obtain lag measurements. We present the light-curve data and plots in the online journal for all seasons and objects in the main sample.

3.1. JAVELIN Analysis

We use JAVELIN (Zu et al. 2011) to model quasar variability as a DRW. The covariance function of a DRW has an exponential form

$$S(\Delta t) = \sigma_{\text{DRW}}^2 \exp(-|\Delta t|/\tau_{\text{DRW}}), \quad (4)$$

where Δt is the time interval between two epochs, σ_{DRW} is the amplitude, and τ_{DRW} is the characteristic timescale. Previous

studies have shown that quasar light curves are generally well described by a DRW (e.g., Kelly et al. 2009; Kozłowski et al. 2010; MacLeod et al. 2010; Zu et al. 2013). However, several studies found that the *Kepler* light curves of AGNs show steeper power spectral density (PSD) than the DRW model at timescales shorter than ~ 1 month (e.g., Mushotzky et al. 2011; Smith et al. 2018). Here we use JAVELIN with the awareness of the potential effect of this deviation from DRW.

JAVELIN first fits the continuum light curve, which can be the light curve in any of the broad bands in continuum RM, to constrain σ_{DRW} and τ_{DRW} . Then, JAVELIN assumes that the line light curve, which in our case is the light curve in another continuum band, is a shifted, smoothed, and scaled version of the first light curve. This fits three additional parameters: the time lag, the top-hat smoothing factor, and the flux scaling factor. We fix τ_{DRW} to the value from the g-band continuum fitting when fitting for the time lag of most objects, since in the case of an accretion disk the time lag is much smaller than the timescale of the DRW and the fitting result is insensitive to τ_{DRW} .

Figures 5 and 6 show the probability distribution of time lags of the r , i , and z bands relative to the g band. Figure 5 only include objects without flags, while Figure 6 shows flagged objects. In most cases there is a single, clear peak in the lag distribution. While the distributions show secondary peaks in some objects, the amplitude of the secondary peak is very small compared to the main peak. Objects from the MaxVis field, whose observational cadence is around 1 day, produce lags with significantly smaller uncertainty compared to some of the objects in the C26202 field with about a 7-day cadence. We adopt the median of the probability distribution as the best-fit lag and the 16th and 84th percentile of the distribution as the

Table 2
Lags and Accretion Disk Sizes

Object Name(Season)	τ_r (days)	τ_i (days)	τ_z (days)	R_{2500} Å (lt-day)	Flag	Visible Lag
DES J0630–5756(SV)	$2.2^{+0.2}_{-0.9}$	$2.3^{+0.1}_{-0.4}$	$2.4^{+0.1}_{-0.1}$	$0.76^{+0.04}_{-0.04}$	0	Y
DES J0635–5853(SV)	$0.4^{+0.1}_{-0.1}$	$0.5^{+0.1}_{-0.1}$	$0.5^{+0.1}_{-0.1}$	$0.14^{+0.03}_{-0.04}$	0	N
DES J0631–5909(SV)	$3.4^{+2.4}_{-2.2}$	$4.0^{+1.7}_{-1.0}$	$5.2^{+1.7}_{-0.9}$	$1.81^{+0.41}_{-0.28}$	0	Y
DES J0340–2645(Y1)	$0.4^{+0.4}_{-0.4}$	$1.7^{+0.5}_{-0.6}$	$2.1^{+0.5}_{-0.7}$	$0.74^{+0.15}_{-0.16}$	0	Y
DES J0327–2742(Y3,4)	$1.2^{+0.9}_{-0.9}$	$2.6^{+1.0}_{-0.9}$	$4.7^{+1.6}_{-1.4}$	$1.53^{+0.47}_{-0.46}$	0	Y
DES J0335–2932(Y1,3)	$1.9^{+0.7}_{-0.6}$	$2.0^{+0.5}_{-0.5}$	$1.9^{+0.7}_{-0.6}$	$0.83^{+0.25}_{-0.23}$	0	Y
DES J0338–2643(Y1,2,3)	$3.3^{+0.8}_{-0.9}$	$0.9^{+1.0}_{-1.1}$	$5.9^{+1.2}_{-1.1}$	$1.54^{+0.39}_{-0.41}$	0	Y
DES J0340–2740(Y1)	$3.7^{+1.3}_{-1.2}$	$4.3^{+1.1}_{-1.0}$	$5.6^{+0.6}_{-1.0}$	$1.96^{+0.28}_{-0.52}$	0	Y
DES J0338–2614(Y3)	$0.7^{+0.6}_{-0.6}$	$1.1^{+0.6}_{-0.7}$	$1.1^{+0.7}_{-0.7}$	$0.40^{+0.24}_{-0.32}$	0	N
DES J0330–2712(SV)	$1.4^{+1.9}_{-1.2}$	$2.3^{+1.8}_{-1.2}$	$3.2^{+1.8}_{-0.7}$	$1.03^{+0.55}_{-0.47}$	0	Y
DES J0328–2817(Y3,4)	$2.5^{+0.7}_{-0.7}$	$4.8^{+0.9}_{-1.0}$	$6.7^{+1.2}_{-1.2}$	$2.46^{+0.44}_{-0.48}$	0	Y
DES J0332–2847(Y4)	$0.8^{+0.6}_{-0.5}$	$1.9^{+0.5}_{-0.6}$	$2.2^{+0.7}_{-0.6}$	$0.86^{+0.24}_{-0.23}$	0	N
DES J0337–2949(Y4)	$2.0^{+1.3}_{-1.2}$	$2.5^{+0.9}_{-0.9}$	NaN	$1.51^{+0.58}_{-0.58}$	0	N
DES J0332–2853(Y4)	$3.1^{+0.9}_{-1.0}$	$3.9^{+0.8}_{-0.8}$	$3.0^{+0.8}_{-0.8}$	$1.40^{+0.32}_{-0.33}$	0	Y
DES J0333–2859(Y4)	$0.6^{+0.6}_{-0.4}$	$3.3^{+0.6}_{-0.7}$	$3.7^{+0.5}_{-0.6}$	$1.26^{+0.19}_{-0.37}$	0	Y
DES J0330–2749(Y4)	$1.7^{+1.7}_{-1.6}$	$2.5^{+1.7}_{-1.6}$	NaN	$1.67^{+1.13}_{-1.10}$	0	N
DES J0332–2739(Y2,3,4)	$1.4^{+1.3}_{-1.2}$	$3.1^{+1.5}_{-1.5}$	$3.3^{+1.4}_{-1.3}$	$1.28^{+0.47}_{-0.47}$	0	Y
DES J0627–5829(SV)	$1.8^{+1.9}_{-1.1}$	$2.0^{+1.9}_{-1.1}$	$2.0^{+1.9}_{-1.0}$	$0.15^{+0.11}_{-0.12}$	23	Y
DES J0330–2732(Y1)	$1.1^{+1.4}_{-1.3}$	$1.8^{+0.9}_{-0.8}$	$2.9^{+0.7}_{-0.6}$	$0.97^{+0.18}_{-0.15}$	2	N
DES J0334–2743(Y2,3)	$1.5^{+0.6}_{-0.6}$	$4.5^{+0.6}_{-0.7}$	$3.9^{+0.7}_{-0.6}$	$1.66^{+0.13}_{-0.28}$	12	N
DES J0328–2738(Y1,2)	$3.7^{+1.7}_{-1.3}$	$7.7^{+1.1}_{-1.2}$	NaN	$4.78^{+1.31}_{-0.94}$	2	Y
DES J0059+0006(Y2)	$3.4^{+0.4}_{-2.0}$	$2.4^{+0.4}_{-0.9}$	$2.7^{+0.6}_{-0.3}$	$0.78^{+0.05}_{-0.07}$	2	N

Note. Columns (2)–(4) give the JAVELIN r -, i -, and z -band lags relative to the g band and their 1σ uncertainties. “NaN” values mean that we do not have good lag measurements in this band. Column (5) gives the accretion disk sizes from the JAVELIN thin-disk model with 1σ error bars. Column (6) gives the flags indicating the issues to note for the object. flag = 0 means no issue to note, flag = 1 means that the object has lag measurements in multiple seasons that are not consistent with each other, flag = 2 means that we cannot obtain good lags for the object with the ICCF method (see Section 3.2), flag = 3 indicates that the light curves of the object are not likely to provide good lag measurements given its cadence and depth based on simulation (see Section 4.1). Column (7) gives whether the lag signal can be visually seen from the light curve of the object, where “Y” means that the lag is visible, while “N” means that the lag is not clear in the light curve (see Section 3.3).

1σ lower and upper limit of the lag, respectively. We provide more detailed comments on individual objects in the [Appendix](#).

We also use the JAVELIN thin-disk model extension developed by Mudd et al. (2018) to measure the accretion disk size R_{λ_0} and index β in Equation (1) using all four bands simultaneously. The JAVELIN thin-disk model makes use of the information from photometric light curves in all bands to better constrain the accretion disk size and reduces the number of parameters. Similar to Mudd et al. (2018), we find that the JAVELIN thin-disk model could not well constrain both R_{λ_0} and β at the same time, so we fix $\beta = 4/3$ during the fitting. We again fix τ_{DRW} . Figures 7 and 8 show the probability distribution of the g -band accretion disk size R_g in the observed frame, i.e., the disk size at $\lambda = 4730(1+z)$ Å, where z is the redshift. Figure 7 only includes objects without flags, while Figure 8 shows flagged objects. Again, most distributions show clear single peaks. We convert the g -band disk size to rest frame 2500 Å assuming $R_\lambda \propto \lambda^{4/3}$ for comparison with other studies.

We inspected the lag distributions from JAVELIN and the disk size distributions from the JAVELIN thin-disk model for all candidates that satisfied the criteria in Section 3. We define a successful measurement of the single-band lag or the accretion disk size if the probability distributions satisfy three criteria: (1) The 1σ lower limit of the lag or disk size is larger than zero. (2) The probability distribution shows a clear single peak without significant secondary peaks. We define a secondary peak to be “significant” if its peak probability density is more

than 20% of the main peak. Secondary peaks may also be a “bump” in the main peak. We treat a “bump” as a secondary peak if it is separated from the main peak by at least 0.75 days and the probability density difference between the bump peak and where it connects the main peak is larger than 7.5% of the main peak. (3) The 1σ upper limit of the top-hat smoothing factor is smaller than 30. We added the third criterion because large smoothing factors are usually related to smooth lag distributions without clear peaks, which is a common feature of the failed fits from JAVELIN. We define successful measurements for an *object* in an observational season if the lag distributions in at least one of the riz bands and the disk size distributions satisfy the successful measurement criteria. We identify 22 quasars to have successful lag and disk size measurements in at least one observational season, and we refer to these quasars as the “main sample.” Table 1 lists some of the basic parameters of the quasars in the main sample. Table 2 shows the best-fit lag and the 1σ errors from JAVELIN in Columns (2)–(4) and the 2500 Å accretion disk size in Column (5). While the selection criteria require positive lags in only one band, nearly all of the quasars in the main sample have positive lags in at least two of the riz bands relative to the g band.

As is shown in Figure 3, all of the quasars in the main sample have either a large χ_r^2 , implicating significant variability relative to the photometric errors, or a large number of epochs, corresponding to a high observational cadence. Most candidates in the SDSS fields have smaller χ_r^2 than those in the main

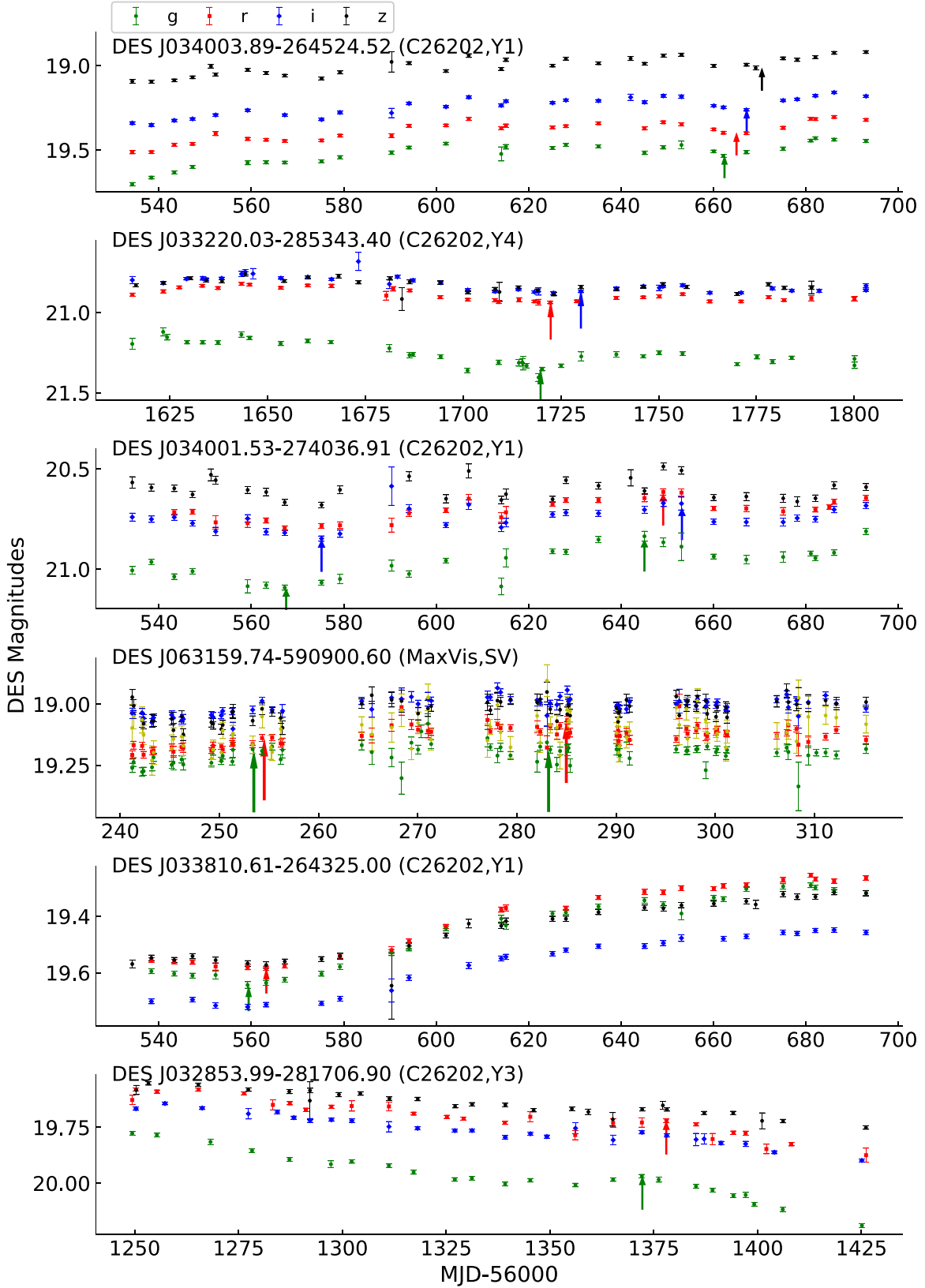


Figure 4. DES light curves of a randomly selected subset of the unflagged objects in the main sample. The object's name, field, and the observational season(s) from which we measure the lag are shown in the upper left corner of each row. The green circles, red squares, blue diamonds, black hexagons, and yellow pentagons represent the g -, r -, i -, z -, and Y -band data, respectively. The green, red, blue, and black arrows point to the approximate positions of the features that show visible lags in the g -, r -, i -, and z -band light curves, respectively.

(The data used to create this figure are available.)

(The complete figure set (22 images) is available.)

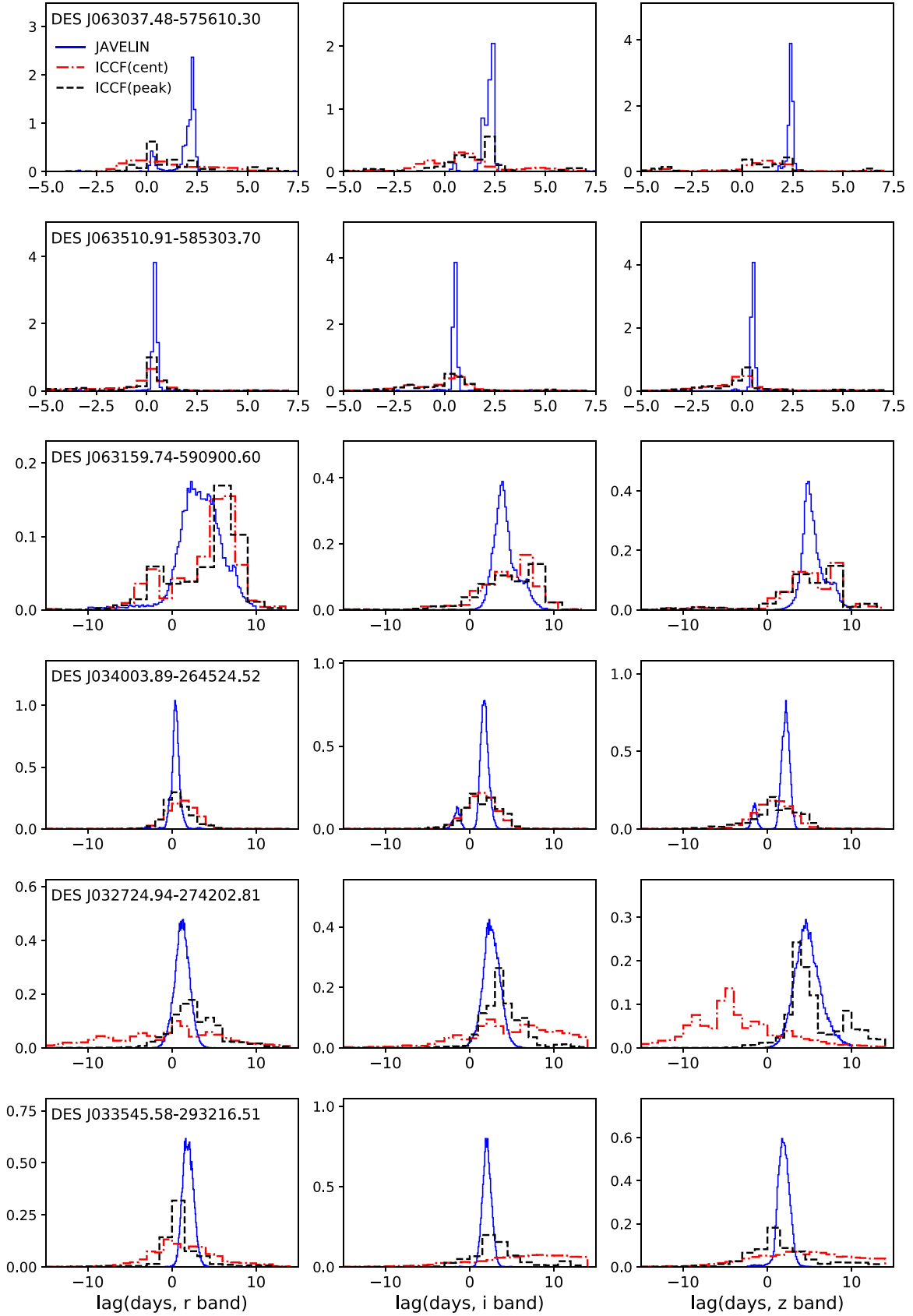


Figure 5. Probability distributions of time lags for quasars without flags in the main sample. Each row represents the results for one object whose name is listed in the upper left corner of the first panel, with the first, second, and third columns representing the lags in the r , i , and z band relative to g band, respectively. In each panel, the blue solid line is the lag distribution from JAVELIN, while the red dashed-dotted line and the black dashed line represent the ICCF center and peak distribution, respectively.

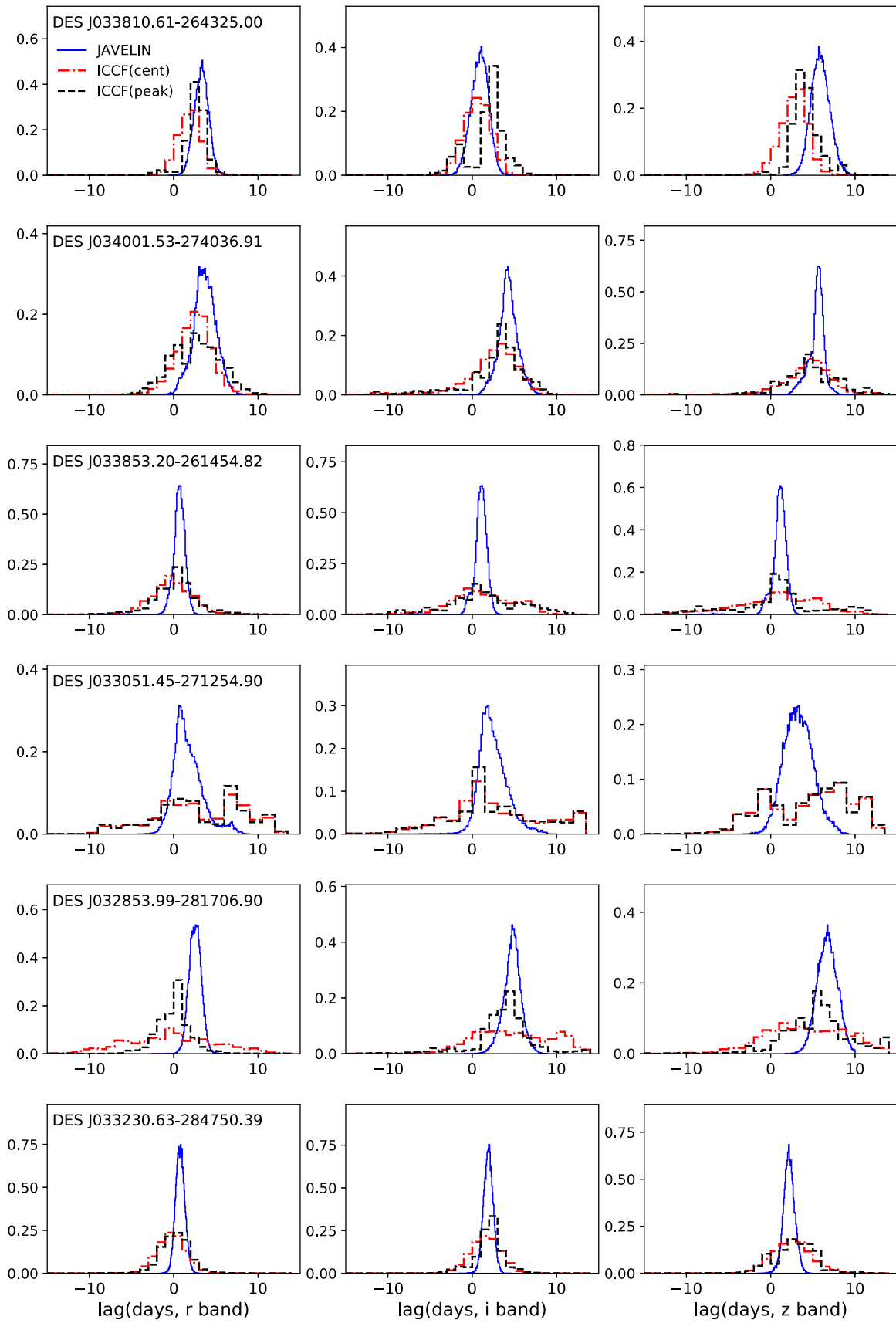


Figure 5. (Continued.)

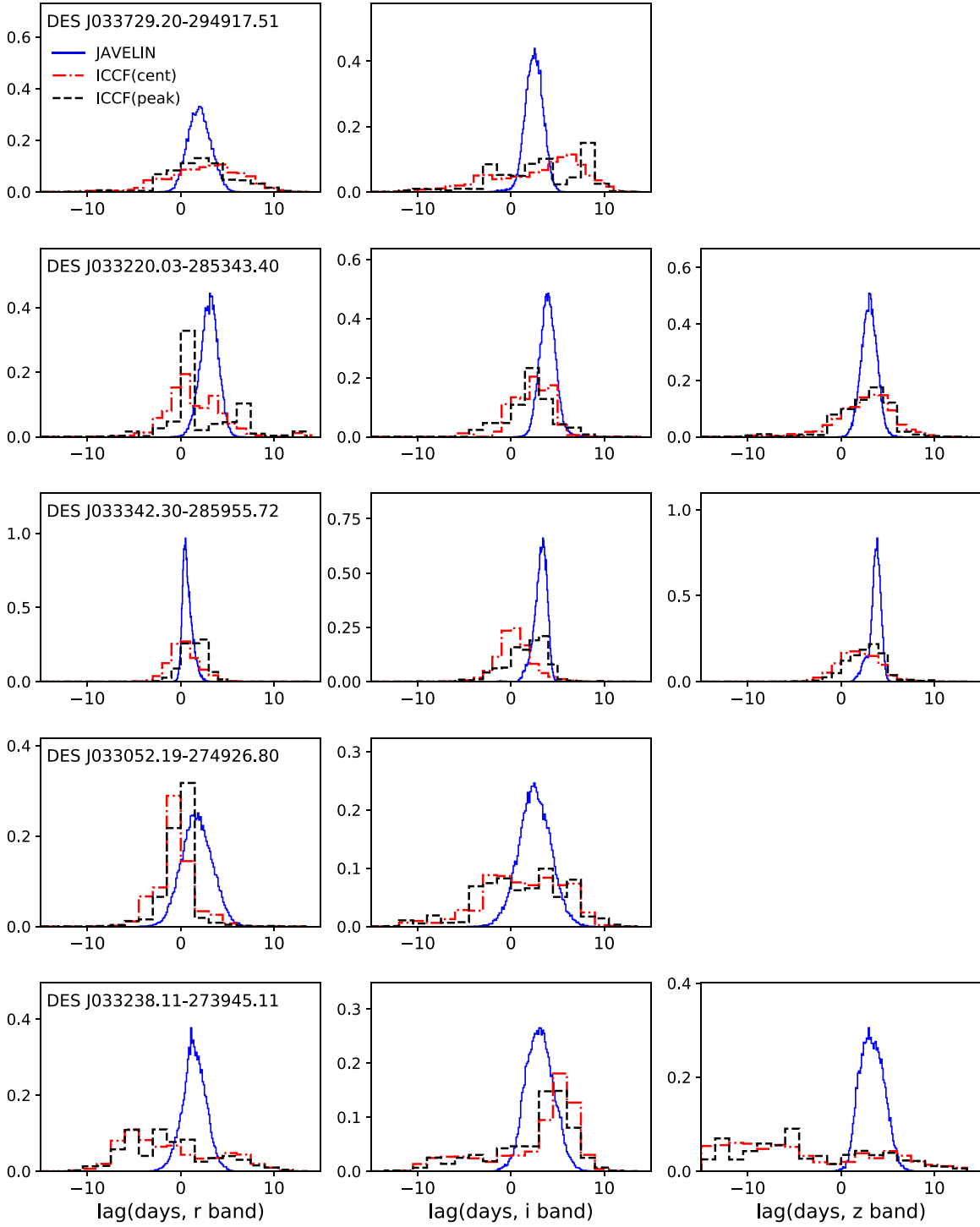


Figure 5. (Continued.)

sample, which may explain why only one quasar from the SDSS fields is in the main sample, even though these fields have so many quasars.

We treat the observations in each season as independent time series and analyze them separately with JAVELIN. Column (1) in Table 2 shows the seasons where we obtain good measurements for each object. There are seven objects that have good measurements in multiple seasons. We compare the accretion disk sizes from different seasons in Figure 9. Most

objects show consistent disk sizes from different seasons at the 1σ level, while only one object (DES J033408.25–274337.81) shows different disk sizes from the different seasons. For these objects, we show the lags and disk sizes from fitting the light curves in all seasons simultaneously in Table 2 and adopt them for further analysis. We add flag = 1 to DES J033408.25–274337.81 in Table 2. The discrepancy in the disk sizes from different seasons may be because the accretion disk undergoes structural changes between seasons, or because the time lags

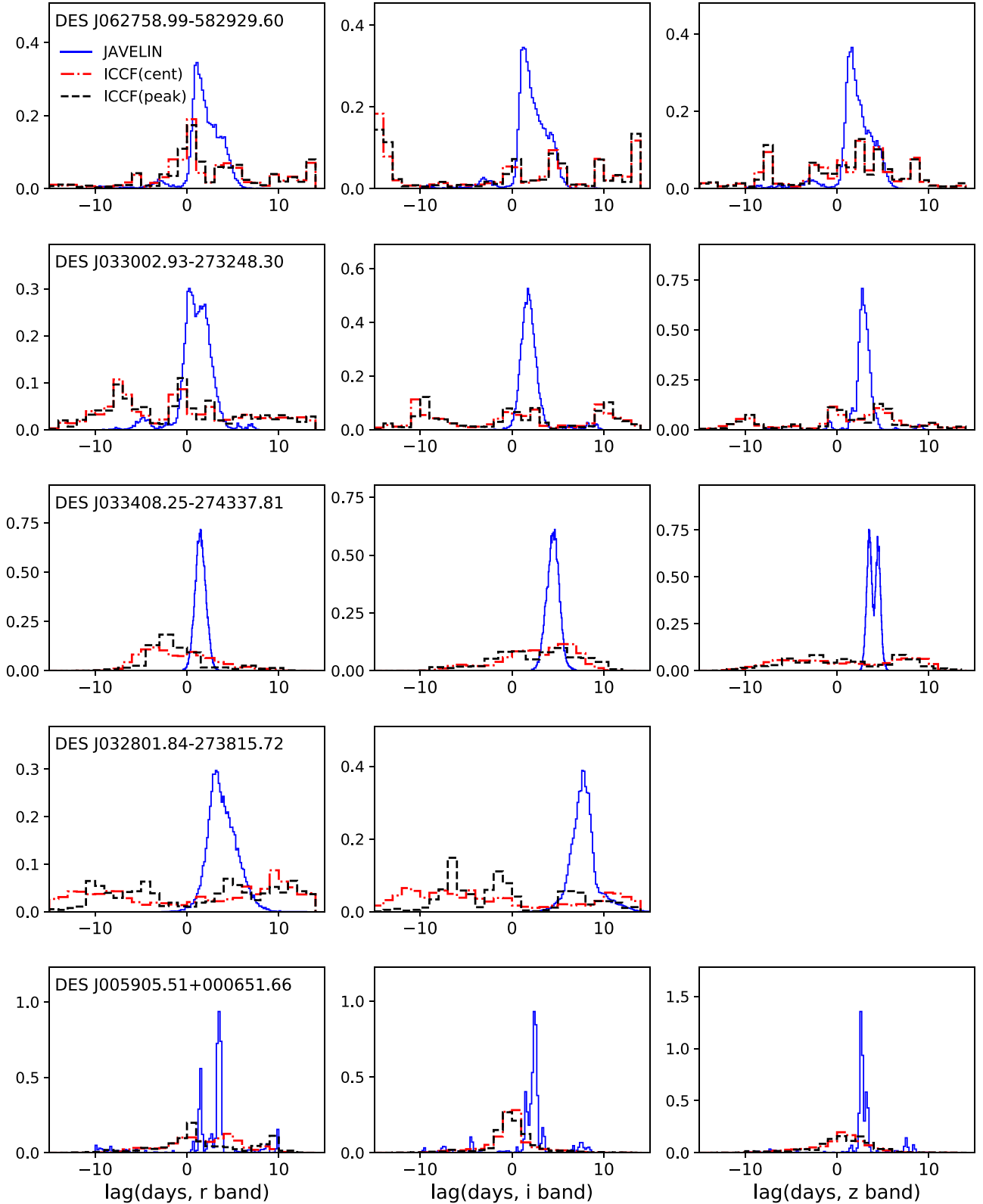


Figure 6. Same as Figure 5, but for quasars with flags in the main sample.

between different photometric bands are not exactly described by the simple scenario that we assumed.

A successful lag measurement in one season does not guarantee successful lag measurements in other seasons. There are three factors that can prevent a lag measurement in a given season: the AGN variability, the light-curve photometric data quality, and the

observational cadence. A successful lag measurement, and particularly one easily confirmed by visual inspection, requires a significant flux variation relative to the photometric errors that is also well sampled by the observational cadence. AGN variability is sufficiently stochastic that the largest photometric variations may fall outside of the range of the light-curve data, be on the

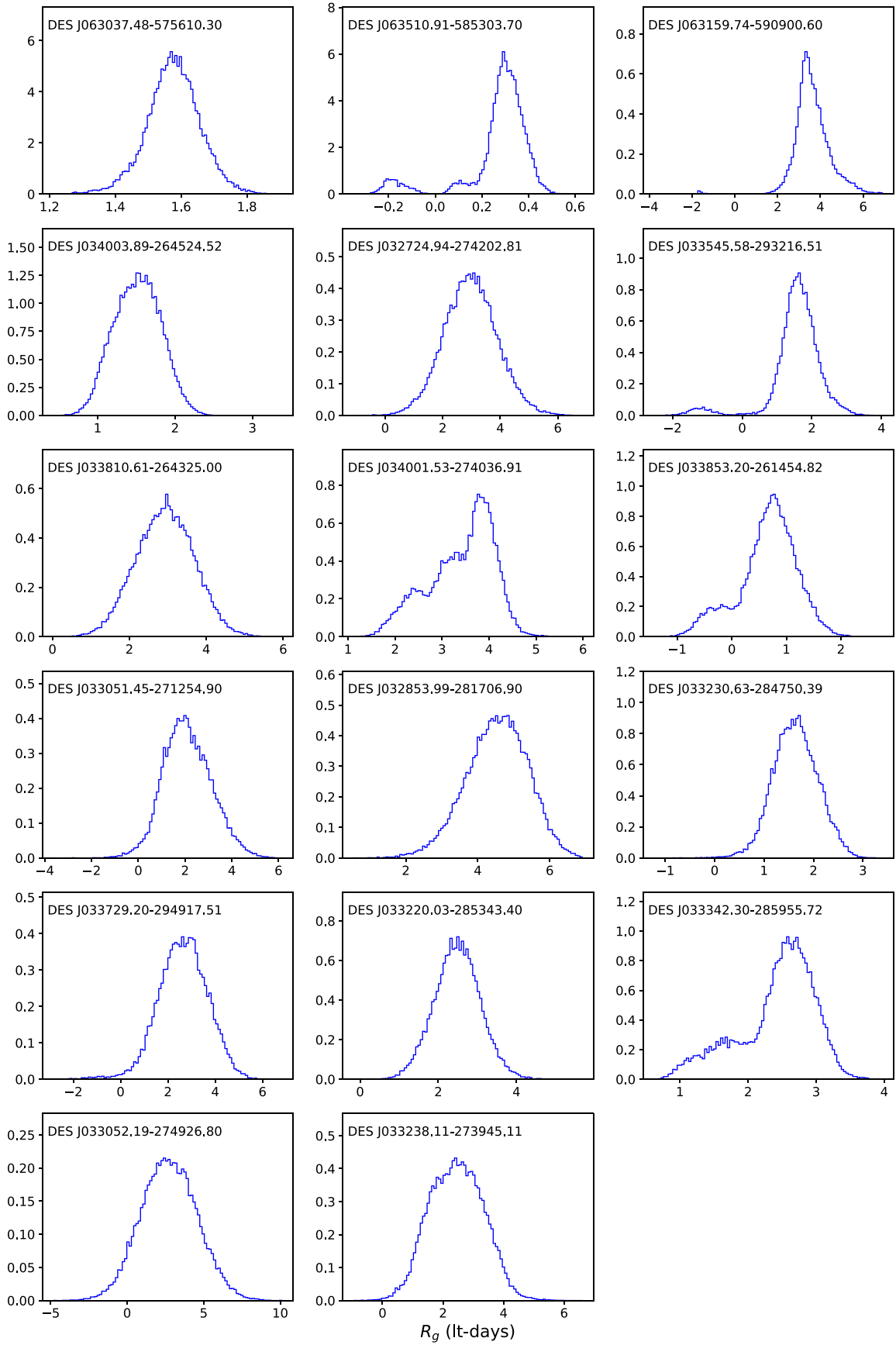


Figure 7. Probability distributions for the observed frame g -band accretion disk sizes from the JAVELIN thin-disk model for quasars without flags in the main sample. Each panel shows the result for one object.

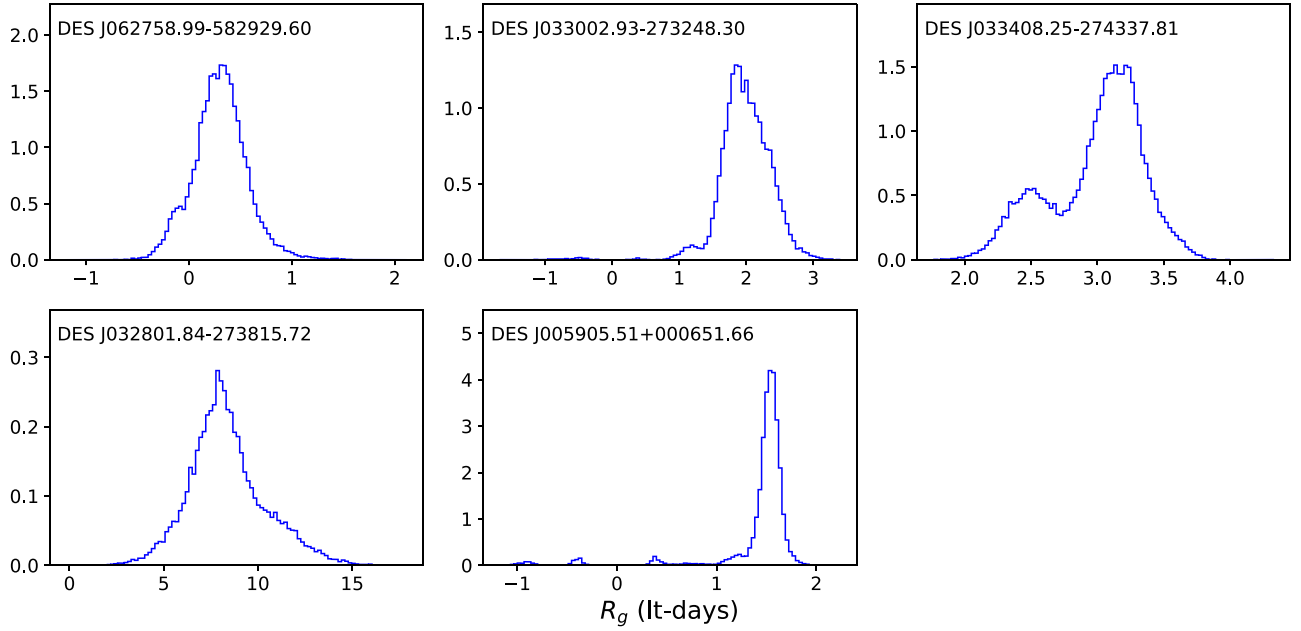


Figure 8. Same as Figure 7, but for quasars with flags in the main sample.

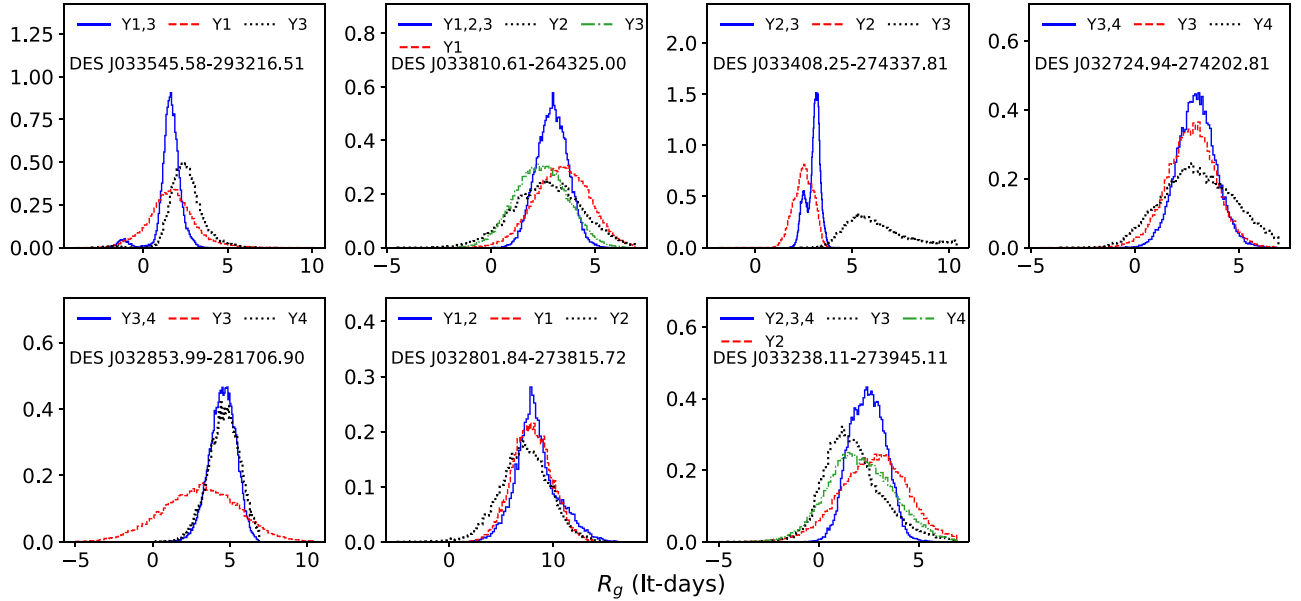


Figure 9. Probability distributions for the observed frame g -band accretion disk sizes from the JAVELIN thin-disk model for objects with multiseason lag measurements. In each panel the blue solid line represents the results of a simultaneous fit to all observational seasons with lag measurements, while the red dashed, black dotted, and green dashed–dotted lines represent the results for individual seasons.

order of the photometric noise (or less), or be insufficiently well sampled to identify a clear signal. For example, less than a quarter of the objects in the MaxVis and SDSS fields meet our selection criteria (Section 3) in more than one season, while the other seasons do not have enough epochs and/or sufficient light-curve data quality (signal-to-noise ratio).

The variability of the broad emission lines can contaminate the continuum lag measurements. The variations of broad emission lines lag the continuum owing to the light-travel time from the accretion disk to the BLR. The broad-line variability may consequently make the measured lag larger than the real continuum lag. We assess the contamination from broad emission lines as the ratio of the equivalent width of the

emission line to the effective width of the broadband filter, referred to as f_{BLR} , similar to Homayouni et al. (2019). Those authors identified potential contamination if $f_{\text{BLR}} > 12.5\%$. For each object in the main sample in the MaxVis and the C26202 fields, we calculated the f_{BLR} for the Ly α , C IV, C III], Mg II, H β , and H α if the line fell into the bandpass of any of the g , r , i , or z bands. For the object within the SDSS footprint, we adopted the equivalent width of the emission lines from Shen et al. (2011). We show f_{BLR} as a function of redshift for the g , r , i , and z bands in Figure 10. All objects show f_{BLR} less than 12.5%, indicating that our continuum lag measurements have little contamination from broad lines. There are a few lines where we did not derive f_{BLR} because the line falls out of the

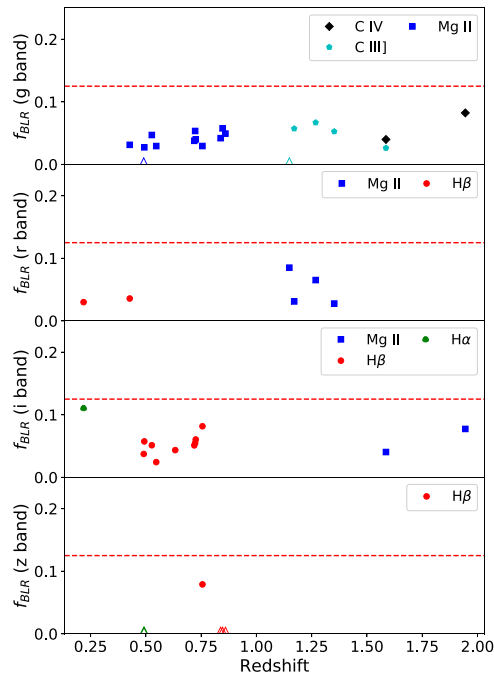


Figure 10. Broad-line contamination fraction f_{BLR} as a function of redshift. f_{BLR} is the ratio of the equivalent width of the emission line to the effective width of the broadband filter. The panels from top to bottom represent the broad-line contamination in the g , r , i , and z bands, respectively. The filled symbols represent the emission lines that could contaminate the continuum lag measurements for the object, with different colors and shapes for different emission lines. The open triangles are the emission lines where we did not derive f_{BLR} because the line falls out of the wavelength range of the spectrum or falls into a region where the spectrum is too noisy. The red dashed line is drawn at $f_{\text{BLR}} = 12.5\%$.

wavelength range of the OzDES spectrum from 3700 to 8800 Å or falls into a region where the spectrum is too noisy. These cases are indicated by the open triangles in Figure 10. However, it is clear from Figure 10 that no emission line has sufficiently large flux that would contaminate the lag measurements, so it is unlikely that the few quasars with unmeasured f_{BLR} would significantly affect our conclusions.

3.2. ICCF Analysis

We also use the conventional ICCF method (e.g., Peterson et al. 1998, 2004) to derive time lags with the public code PyCCF (Sun et al. 2018). It cross-correlates two light curves using linear interpolation and measures the peak location τ_{peak} and centroid location τ_{cent} of the cross-correlation function (CCF) using points with cross-correlation coefficients $r \geq 0.8r_{\text{peak}}$, where r_{peak} is the peak value of the CCF. To estimate the uncertainty of the lag measurements, PyCCF creates a series of independent realizations of the light curve through Monte Carlo iterations with flux randomization and random subset selection (with replacement, also known as “bootstrapping”) and builds up the cross-correlation centroid distribution (CCCD) and cross-correlation peak distribution (CCPD). We create 20,000 realizations of the light curve and set the threshold of a “significant” correlation to be 0.5, i.e., realizations with $r_{\text{peak}} \leq 0.5$ are excluded from CCCD and CCPD. The median fraction of the failed realizations is 14% for the main sample, except five objects that show failure fraction larger than 70% in at least two bands. The objects with large failure fractions are all flagged objects, or objects with lags

significantly smaller than the observational cadence, where ICCF is known to have trouble recovering lags (e.g., Jiang et al. 2017).

Figures 5 and 6 show the CCCD and CCPD compared to the JAVELIN lag distributions. For objects in Figure 5, the ICCF results are generally consistent with the JAVELIN results in at least one of the r , i , and z bands, while the lag distributions from ICCF are significantly wider than the JAVELIN lag distributions. However, we also find a few objects where ICCF does not produce good lag measurements, or the ICCF results deviate significantly from the JAVELIN results in all bands. We add flag = 2 to these objects in Table 2 and show their JAVELIN and ICCF results in Figure 6. Finally, we note that we reanalyzed DES J033719.99–262418.83 from Mudd et al. (2018), which is in the C2 supernova field. This object is a marginal detection both here and in Mudd et al. (2018), with large uncertainties in lags from JAVELIN and ICCF, and we therefore do not include it in our main sample. We provide more detailed comments on the comparison between the JAVELIN and ICCF results in the Appendix.

The larger uncertainties of lag measurements from ICCF compared to JAVELIN are typical. JAVELIN likely underestimates uncertainties because of non-Gaussian or other issues in the light-curve uncertainties and because the second light curve may not simply be a shifted, scaled, and smoothed version of the first. On the other hand, previous studies (e.g., Jiang et al. 2017) find that ICCF does not work well in recovering time lags less than the cadence of the light curve, which is the case of many of our objects in the C26202 field. JAVELIN provides a much better means of interpolating and weighting interpolated points than linear interpolation. We further compare the performance of JAVELIN and ICCF through simulations in Section 4.1. We only report the lags from JAVELIN hereafter.

3.3. Visual Inspection of Light Curves

We visually inspected the light curves of all objects in the main sample to see whether we can identify the lag signals by eye. Figure 4 shows examples of the visible lag signals marked by the arrows. The local peaks or valleys pointed to by the arrows visibly appear later in the bands with longer wavelengths. We also marked the visible lag signals in the full-size light-curve plots presented in the online journal.

We find that 12 out of the 17 unflagged objects and two out of the five flagged objects in the main sample show at least one visible lag feature in at least one of the $griz$ bands. These results are listed in Table 2. We note that most of the unflagged objects in the main sample have lags that are directly visible from the light curves. The objects where the lag signals are not clearly visible often have lags that are smaller than the cadence of the light curve. This is true of a larger fraction of the flagged sample.

4. Verification of Lag Measurements

4.1. Simulations

We ran simulations to further verify the lag measurements. First, we created simulated light curves with just Gaussian noise. For each object in the main sample, we calculated its mean magnitude μ_m and standard deviation σ_m within an observational season in each band. For each season and band, we created a simulated light curve where each epoch is a Gaussian deviation of dispersion σ_m about μ_m with the same sampling as the observed light curve. We

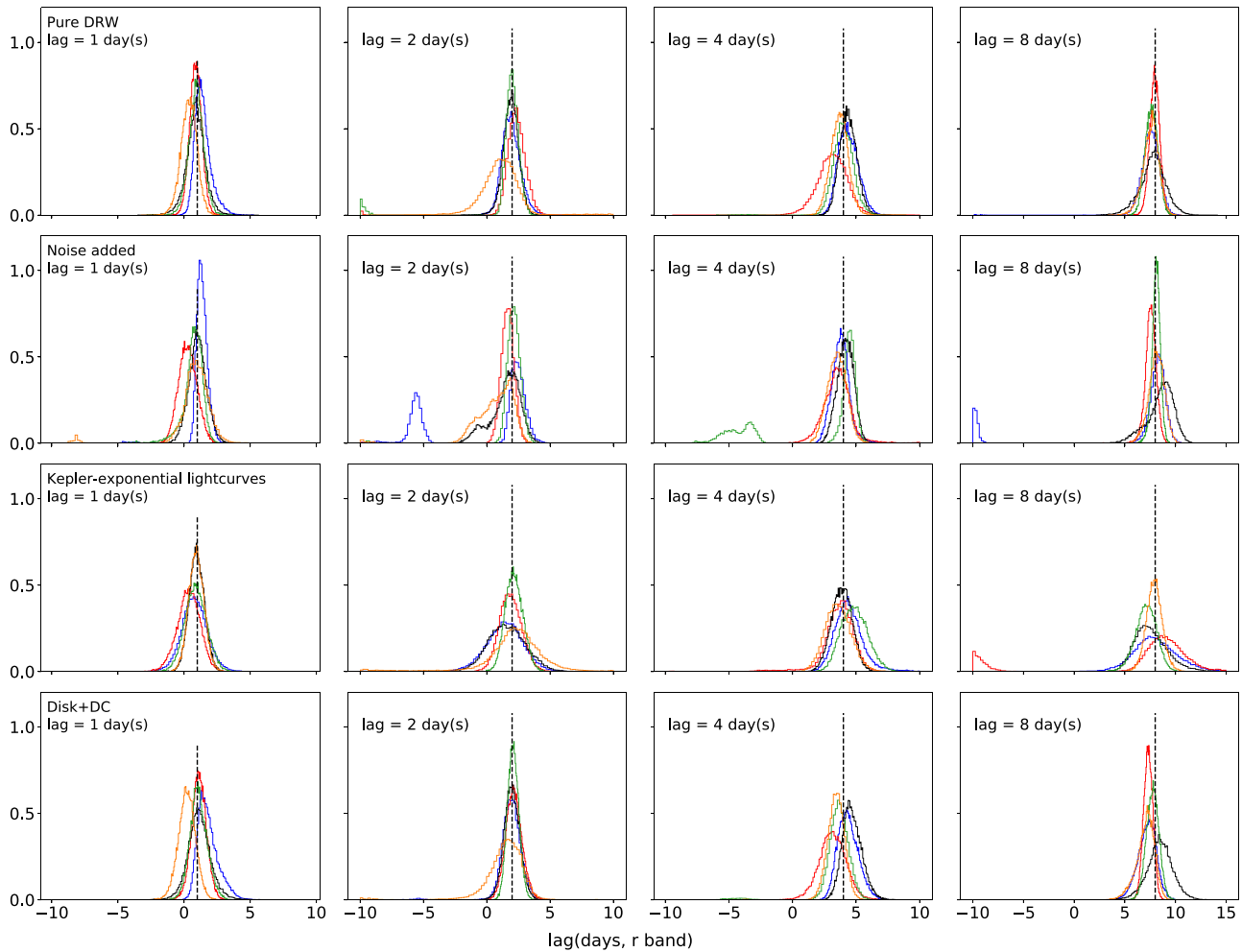


Figure 11. Probability distribution of r -band time lags relative to g -band ones from fitting the five realizations (LC0–LC4) of the simulated light curves of DES J063037.48–575610.30 in the MaxVis field. The histograms with different colors in each panel represent the JAVELIN result for different realizations of the simulated light curves. The black dashed line in each panel represents the position of the input time lag, which is 1, 2, 4, and 8 day(s) for the first, second, third, and fourth columns, respectively. The first through the fourth rows represent the results from pure DRW light curves, DRW light curves with noise, *Kepler*-exponential light curves, and the composite light curves of the accretion disk and the diffuse continuum from the BLR.

set the uncertainty of each simulated data point to be the same as the uncertainty of the corresponding data point in the observed light curve. In this case, we created simulated light curves that have the same cadence as the observed light curve but do not have lags. We then look for the lags between the *observed* g -band light curve and the *simulated* r -, i -, and z -band light curves. We find that the probability distributions of the time lags from JAVELIN have multiple peaks of both signs with no evidence of a clear, positive lag. This indicates that JAVELIN does not produce fake detections from light curves with no lag signal.

We then created simulated light curves from the DRW model. For each object in the main sample, we constructed DRW light curves with a 0.05-day cadence using the best-fit σ_{DRW} and τ_{DRW} from JAVELIN for the g band. We shifted the g -band light curve by a time lag of 1, 2, 4, or 8 days to create simulated light curves in the r , i , and z bands. We did not add further noise to the shifted light curves. We created five realizations of the DRW light curve for each input time lag. We sampled the 0.05-day cadence simulated light curves to the same cadence as the observed light curves and set the photometric uncertainty of each data point to be the same as the corresponding data point in the observed light curve.

We ran JAVELIN on the simulated light curves to check whether JAVELIN can reproduce the input time lag. The first row of Figure 11 shows an example of the JAVELIN results from fitting the simulated DRW light curves of DES J063037.48–575610.30, a quasar in the MaxVis field with a ~ 1 -day observational cadence. Figure 11 shows that JAVELIN can reproduce the input time lags at the 1σ level in most realizations, although there are a few cases where the JAVELIN lags deviate significantly from the input. We performed these simulations for all 22 quasars in the main sample. For only one object we did not reproduce the input lag in most realizations. We add flag = 3 to this object in Table 2.

In addition to JAVELIN, we also test the ICCF method on the simulated DRW light curves. Figure 12 shows the lag distributions for the simulated DRW light curves of DES J063037.48–575610.30 (same quasar as Figure 11) with the ICCF method. It shows that the ICCF lags are also usually consistent with the input, although the uncertainty of the ICCF lags, as well as the number of cases where the ICCF lag deviates significantly from the input, is larger than for the JAVELIN lags. For most quasars in the main sample, the simulation results for the ICCF method are similar to Figure 12. However, we note a few cases where the

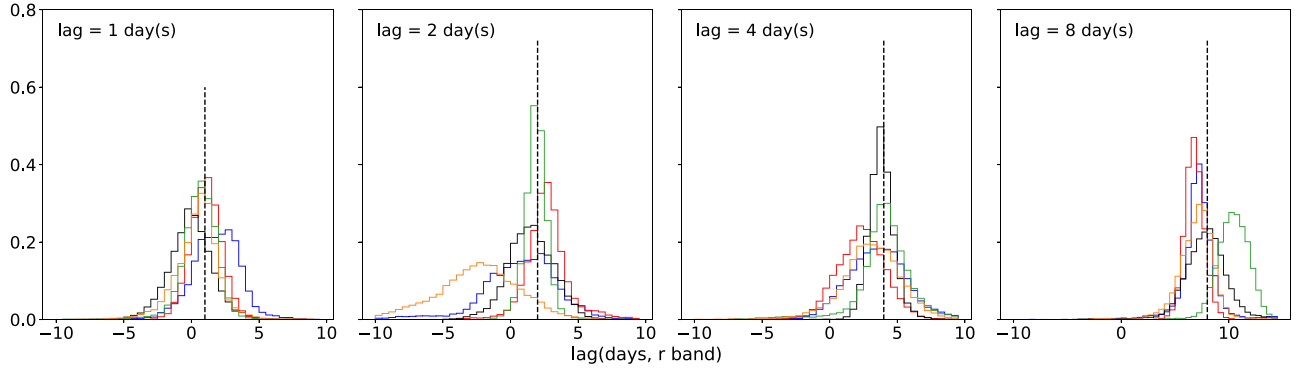


Figure 12. Probability distribution of r -band time lags relative to g -band ones from fitting the five realizations (LC0–LC4) of the simulated DRW light curves with the same ~ 1 -day cadence as DES J063037.48–575610.30 (same quasar as Figure 11) with ICCF. The histograms with different colors in each panel represent the ICCF center distributions for different realizations of the DRW light curves. The black dashed line in each panel represents the position of the input time lag, which is 1, 2, 4, and 8 day(s) for the first, second, third, and fourth columns, respectively.

ICCF method cannot reproduce the input lags at all. For instance, the bottom panel of Figure 13 shows the ICCF lags from the simulated light curves of DES J032801.84–273815.72 with an 8-day input lag. The lag distributions are wide with multiple peaks, or show a peak that deviates significantly from the input lag, indicating that the ICCF method is unlikely to provide reliable lag measurements for this quasar, while the top panel of Figure 13 shows that JAVELIN can recover the input time lag from the simulated light curves of this quasar. Note that in Section 3.2 we flag DES J032801.84–273815.72 because it does not have good ICCF lags from the *actual* light curves. Based on these simulation results, we conclude that objects with flag = 2 in Table 2 are not necessarily unreliable objects. It may be that ICCF does not work as well as JAVELIN for some values of the cadence and variability.

4.1.1. Deviations from Pure DRW

The observed light curves can deviate from the DRW model owing to several factors. First, the observed light curves are not noiseless. To account for this effect, we added noise to our simulated DRW light curves so that each epoch is a Gaussian deviation of dispersion σ_m about the original noiseless value, where σ_m is the uncertainty of the simulated epoch and is the same as the uncertainty of the corresponding observed epoch. We ran JAVELIN on these noisy simulated light curves, and the second row of Figure 11 shows an example of the results. While the noise leads to a few secondary peaks, the lag distributions of most realizations still concentrate around the input lag. This indicates that we are still able to recover the lags with JAVELIN with the signal-to-noise level of the observed light curves. We also created simulated light curves with two times and four times the observed noise. In these cases, JAVELIN produces flatter lag distributions with larger noise and is generally not able to recover the input lag once the noise is as large as four times the observed value.

Some studies of the AGN variability found a steeper PSD than the DRW model at short timescales using *Kepler* data (e.g., Mushotzky et al. 2011; Smith et al. 2018). We define a “*Kepler-exponential*” (KE) covariance function to include this effect in the simulation:

$$S(\Delta t) = \sigma^2 [(1 + C) \exp(-|\Delta t/t_1|) - C \exp(-|\Delta t/t_2|)], \quad (5)$$

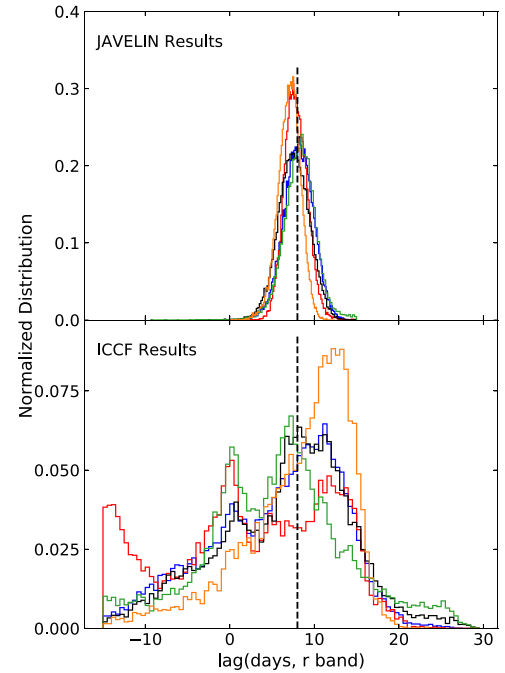


Figure 13. Probability distribution of r -band time lags relative to g -band ones from fitting the simulated DRW light curves of DES J032801.84–273815.72 with JAVELIN (top panel) and ICCF (bottom panel). The histograms with different colors in each panel represent the JAVELIN or ICCF results for different realizations of the DRW light curves. The black dashed line in each panel represents the position of the 8-day input time lag.

where $C = t_2/(t_1 - t_2)$. The σ and t_1 are equivalent to the σ_{DRW} and τ_{DRW} in the DRW model, while we can vary t_2 to make a cutoff at short timescales as found in the *Kepler* light curves. We adjusted t_2 so that the structure function and the PSD start to deviate from DRW at around 30 days and created simulated light curves with the KE covariance function. The third row of Figure 11 shows an example of the JAVELIN results from fitting the KE light curves. We note that JAVELIN can still recover the input time lags. This indicates that the deviations from DRW at short times have little impact on our results and conclusions.

4.1.2. Diffuse Continuum from BLR

The diffuse continuum from the BLR is a potential contamination source for the disk continuum light curves and may lead to an

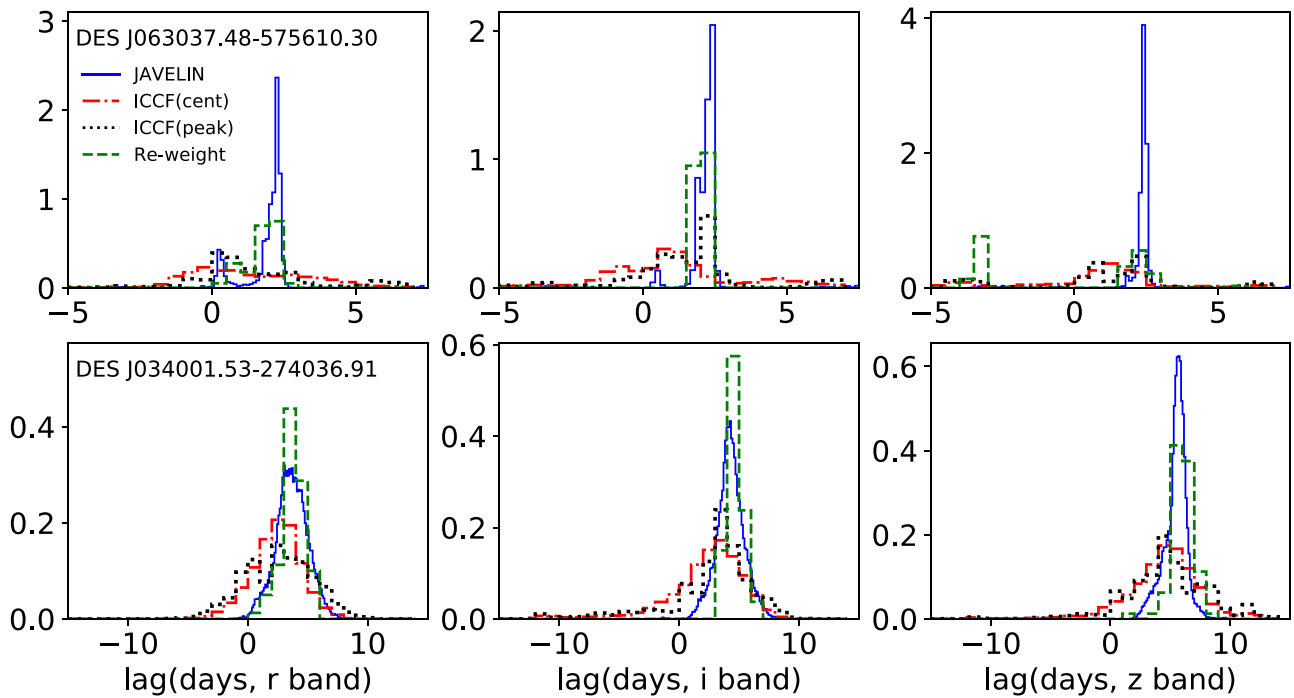


Figure 14. Probability distribution of time lags in the r , i , and z bands relative to g band for DES J063037.48–575610.30 (top row) and DES J034001.53–274036.91 (bottom row). The blue solid, red dashed–dotted, and black dotted lines represent the results from JAVELIN, the ICCF center distribution, and the ICCF peak distribution, respectively. The green dashed line represents the distribution of the median JAVELIN lags from fitting the reweighted light curves.

overestimation of the disk size (e.g., Korista & Goad 2001; Cackett et al. 2018; Lawther et al. 2018). We assess the possible contamination from the diffuse continuum by composite simulated light curves of the accretion disk and the diffuse continuum. We first estimate the fraction of the diffuse continuum in the total continuum using “Model 1” in Figure 8 of Lawther et al. (2018). We then calculate the emission-line lags of our objects using the R_{BLR} –luminosity relation and the flux-calibrated OzDES spectra, and we estimate the diffuse continuum lags using the scaling between the line lags and diffuse continuum lags from “Model 1” in Table 2 and Figure 4 of Lawther et al. (2018). We shift the driving continuum light curve created in Section 4.1 by the diffuse continuum lags to create the diffuse continuum light curves and sample these light curves to the observed epochs. We create the composite light curves by

$$F_{\text{comp},i} = (f_{\text{dc}} \times \text{CF})F_{\text{dc},i} + (1 - f_{\text{dc}} \times \text{CF})F_{\text{disk},i}, \quad (6)$$

where $F_{\text{comp},i}$ is the flux of the i th epoch of the composite light curves, f_{dc} is the diffuse continuum fraction, CF is the covering factor of the BLR, and $F_{\text{dc},i}$ and $F_{\text{disk},i}$ are the fluxes of the i th epoch of the diffuse continuum light curves and the accretion disk light curves, respectively. Here we adopt $\text{CF} = 0.4$ (e.g., Dunn et al. 2007; Lawther et al. 2018). The bottom row of Figure 11 shows an example of JAVELIN results from the composite light curves. We do not find any significant systematic shift of the lags relative to the lags from the pure disk light curves after adding the diffuse continuum component. This indicates that our disk lag measurements have little contamination from the diffuse continuum.

4.2. Reweighting the Light Curves

To further verify the values and uncertainties of the lags from JAVELIN, we adopt a “bootstrap”-like method. For a light curve

in band X ($X = g, r, i, z$) with N_X data points, we randomly pick N_X points with replacements. If a data point is picked N_{pick} times, we divide its error bar by $\sqrt{N_{\text{pick}}}$. If a data point is not picked, we double its error bar. We do not simply exclude the data point like the traditional “bootstrap” method, since the cadence is critical to the time series analysis, while in the traditional “bootstrap” there is no equivalent to the “time” axis for the lag measurements. Doubling the error bar significantly reduces the weight in the data point, which does a similar job as removing the data point without qualitatively changing the light curve. We created 80 reweighted light curves for a few representative objects in the main sample, and we ran JAVELIN on each of the reweighted light curves. We obtain the median JAVELIN lag of each reweighted light curve and compare its distribution to the previous lag distributions from JAVELIN and ICCF. Figure 14 shows the results of DES J063037.48–575610.30 from the MaxVis field in the top row and DES J034001.53–274036.91 from the C26202 fields in the bottom row. The median lag distributions from the reweighted light curves are generally consistent with the previous JAVELIN and ICCF results. The z -band lag distribution of DES J063037.48–575610.30 from the reweighted light curves shows a small secondary peak near -5 days, possibly due to the common ~ 5 -day gaps in its light curve. The positive lag distributions are still consistent with previous lag distributions. These results again verify our lag measurements in Section 3.

4.3. “Gaussianity” of the Photometric Errors

One assumption of JAVELIN is that the input errors are Gaussian. We therefore assess the “Gaussianity” of the photometric errors from DES with the standard stars in the SDSS Stripe 82 fields. We select a subsample of the standard stars from the SDSS Stripe 82 standard-star catalog by Ivezić et al. (2007) with the same distribution of g -band magnitudes as the whole standard-star sample. We construct DES light curves

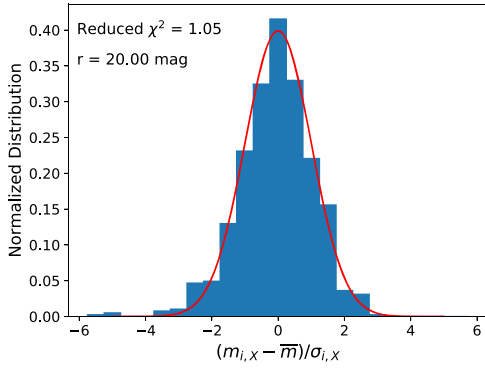


Figure 15. Example of the “Gaussianity” of the DES photometric errors. The blue histograms show the distribution of $(m_{i,X} - \bar{m}_X) / \sigma_{i,X}$ for a standard star. The red line shows a Gaussian profile centered at 0 with a standard deviation equal to 1. The upper left corner shows the χ_r^2 value (see Section 4.3) and the r -band magnitude of the star.

for the stars following the same process as our quasar sample and exclude the stars that have less than 200 epochs over the five DES observational seasons or have unreliable photometries based on DES flags. For each standard star, we calculate the ratio $(m_{i,X} - \bar{m}_X) / \sigma_{i,X}$ for each data point in the light curve, where $m_{i,X}$ and $\sigma_{i,X}$ represent the magnitude and magnitude error of the i th data point in band X ($X = g, r, i, z, Y$), and $\bar{m}_X$ represents the mean magnitude in band X . Assuming that the standard stars from Ivezić et al. (2007) are nonvariable objects, the distribution of the ratio $(m_{i,X} - \bar{m}_X) / \sigma_{i,X}$ should follow a Gaussian distribution centered at 0 with a standard deviation equal to 1. In addition, we calculate χ_r^2 defined in Section 3 for the whole SV–Y3 period for each standard star. If the photometric errors are well estimated, χ_r^2 should be close to 1. We do not include the Y4 data in this section, since the calibrations for the Y4 data in the MaxVis field and the SDSS fields differ from the DES FGCM calibration (Burke et al. 2018) for other seasons and fields, and none of the lag measurements in the main sample are from the Y4 data in these fields.

Figure 15 shows an example of the distribution of $(m_{i,X} - \bar{m}_X) / \sigma_{i,X}$ for a standard star with χ_r^2 around 1.05. The distribution agrees well with the superimposed Gaussian profile, indicating that the DES photometric errors are consistent with Gaussian errors in this case. Figure 16 shows χ_r^2 of the standard stars as a function of the r -band magnitude in the top panel and the distribution of the r -band magnitude of the main quasar sample in the bottom panel. Most stars within the magnitude range of most quasars in the main sample show χ_r^2 close to 1, indicating that the DES photometric errors for quasars within this magnitude range are well estimated. We note that χ_r^2 is also a good indicator of “Gaussianity,” and most stars with χ_r^2 close to 1 show similar distributions to Figure 15, so we expect that the DES photometric errors are also close to Gaussian within the magnitude range of the main quasar sample. For bright stars, χ_r^2 becomes significantly larger than 1 if we do not consider the calibration errors, but it stays near 1 when we take the calibration errors into account. This indicates that the total photometric uncertainties of these bright stars are dominated by calibration errors. Since the DES standard-star observations generally follow the same strategy among the fields we study, we expect that the results from the SDSS Stripe 82 fields are applicable to our other fields. We therefore conclude that the photometric

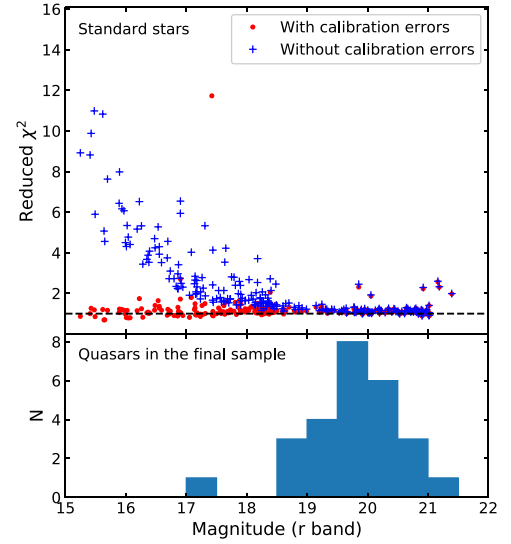


Figure 16. Top panel: χ_r^2 (see Section 4.3) as a function of the r -band magnitude for the standard stars. The blue plus signs show χ_r^2 where we do not consider the DES calibration errors, while the red circles represent the cases where we add the DES calibration errors following the same process as the quasar light curves. The black dashed line represents the position where χ_r^2 equals 1. Bottom panel: magnitude distribution of the quasars in the main sample.

errors of the FGCM calibrated DES data are Gaussian and of the correct amplitude.

5. Disk Size–Black Hole Mass Relation

For objects within the MaxVis and the C26202 fields, we estimate the SMBH mass of each quasar in the main sample through the single-epoch method using the broad H β , Mg II, or C IV line in the OzDES spectra. We calculate the black hole mass as

$$M_{\text{BH}} = f \frac{R_{\text{BLR}} \Delta V^2}{G}, \quad (7)$$

where R_{BLR} is the size of BLR, ΔV is the line width of the broad emission line used for the estimation, and f is the dimensionless “virial factor” that accounts for other unknown factors, such as the inclination, structure, and kinematics of the BLR.

We use the line dispersion of the broad emission lines as our indicator of the line width, as previous studies have shown that this provides more robust black hole mass estimates compared to the FWHM (e.g., Peterson et al. 2004). The line dispersion is defined as

$$\sigma_{\text{line}}^2(\lambda) = \left[\int \lambda^2 P(\lambda) d\lambda / \int P(\lambda) d\lambda \right] - P_0(\lambda)^2, \quad (8)$$

where $P(\lambda)$ is the line profile and $P_0(\lambda)$ is the first moment of the line profile. We use the public code PySpecKit (Ginsburg & Mirocha 2011) in the analysis of the spectra. For the Mg II line, we also fit and subtract the iron emission lines using the template from Vestergaard & Wilkes (2001).

We measure the monochromatic luminosity using the flux-calibrated OzDES spectra (Hoormann et al. 2019) and calculate R_{BLR} using the R_{BLR} –luminosity relations from Bentz et al. (2013) for H β , from McLure & Jarvis (2002) for Mg II, and from Hoormann et al. (2019) for C IV. We adopt a virial factor

of $f = 4.31$ from Grier et al. (2013). For objects within the SDSS fields, we adopt the single-epoch black hole masses from Shen et al. (2011). The error in single-epoch black hole mass is roughly 0.4 dex, based on the uncertainties in the virial factor and the R_{BLR} –luminosity relation (e.g., Peterson 2014). We do not further consider the uncertainties from the line width and continuum luminosity measurements for individual objects, which are very small compared to 0.4 dex.

In comparison to the observed accretion disk sizes, the disk sizes predicted by the standard thin-disk model at effective wavelength λ have the analytical form

$$R_\lambda = \left[\left(\frac{GM}{8\pi\sigma} \right) \left(\frac{L_{\text{Edd}}}{\eta c^2} \right) (3 + \kappa) \dot{m}_E \right]^{1/3} \left(\frac{k\lambda}{hc} \right)^{4/3}, \quad (9)$$

where M is the mass of the SMBH; L_{Edd} is the Eddington luminosity; $\dot{m}_E$ is the Eddington ratio, defined as the bolometric luminosity L_{Bol} divided by the Eddington luminosity; η is the radiative efficiency, defined as $L_{\text{Bol}} = \eta \dot{M} c^2$, where $\dot{M}$ is the mass accretion rate; and κ is the ratio of external to internal heating. Note that the disk size in Equation (9) is defined as the position where $kT(R_\lambda) = hc/\lambda$. This in fact assumes that the emission at wavelength λ is solely contributed from radius R . However, in reality the emission at λ also has contributions from other radii. The disk size from continuum RM is in fact a flux-weighted mean radius $\langle R_\lambda \rangle$ defined as

$$\langle R_\lambda \rangle = \frac{\int_{R_{\text{min}}}^{\infty} B(T(R)) R^2 dR}{\int_{R_{\text{min}}}^{\infty} B(T(R)) R dR} = X R_\lambda, \quad (10)$$

where R_{min} is the inner edge of the disk and $B(T)$ is the Planck function. Assuming the inner edge $R_{\text{min}} \rightarrow 0$, the conversion factor $X = 2.49^{4/3} = 3.36$ if the disk emission does not vary (e.g., Fausnaugh et al. 2016; Tie & Kochanek 2018).

Tie & Kochanek (2018) found that the conversion factor X will be larger when taking the variation of the disk emission into account. Assuming the “lamppost” model (e.g., Cackett et al. 2007) for the variability, the temperature fluctuation of the disk is

$$T(R, t) = T_0(R)[1 + f(t - R/c)], \quad (11)$$

where $T_0(R)$ is the unperturbed temperature at radius R and $f(t - R/c)$ is the fractional change of the temperature lagging the variation at the disk center by the light-travel time R/c . Assuming that the temperature fluctuation is small, the fluctuation of the disk surface brightness is

$$\delta I(R, t) \propto f(t - R/c) G(\xi) \quad (12)$$

$$G(\xi) = \frac{\xi \exp(\xi)}{[\exp(\xi) - 1]^2} \quad \text{where} \quad \xi = \frac{h\nu}{kT_0(R)}, \quad (13)$$

where ν is the frequency, h is the Planck constant, and k is the Boltzmann constant. Equations (12) and (13) state that the outer edge of the disk has larger surface brightness fluctuations than the inner edge with the same temperature variation. Since the continuum RM is only sensitive to the variable

components, Equation (10) becomes

$$\langle R_\lambda \rangle = \frac{\int_{R_{\text{min}}}^{\infty} G(\xi) R^2 dR}{\int_{R_{\text{min}}}^{\infty} G(\xi) R dR} = X_{\text{var}} R_\lambda, \quad (14)$$

where $X_{\text{var}} = 5.04$ (Tie & Kochanek 2018). We adopt this conversion factor for further discussions unless otherwise specified.

We plot the observed accretion disk size at rest frame 2500 Å for all the quasars in the main sample in Figure 17, and we include results from Mudd et al. (2018) for comparison. Many of our measurements show significantly smaller uncertainties than Mudd et al. (2018), as that paper only used the DES supernova observations with a cadence around a week, whereas we have primarily employed the standard-star fields with higher observational cadences.

In addition to taking the Eddington ratio as a free parameter of the thin-disk model, as is shown in Figure 17, we can estimate the Eddington ratio of each quasar in the main sample with the flux-calibrated OzDES spectra. We first calculate the bolometric luminosity using the continuum luminosity discussed above and the bolometric corrections $\text{BC}_{5100} = 9.26$, $\text{BC}_{3000} = 5.15$, and $\text{BC}_{1350} = 3.81$ adopted by Shen et al. (2011) from the quasar spectra energy distributions of Richards et al. (2006). We then divide the bolometric luminosity by the Eddington luminosity to calculate the Eddington ratio. With the Eddington ratio we calculate the predicted accretion disk size R_{model} from the thin-disk model adopting $X = 5.04$, as well as the ratio $R_{\text{obs}}/R_{\text{model}}$ of the observed disk size to the predicted disk size for each quasar in the main sample. We show $R_{\text{obs}}/R_{\text{model}}$ versus R_{model} in Figure 18. Most quasars show accretion disk sizes consistent with the prediction of the standard thin-disk model. This agrees with some previous studies, such as Mudd et al. (2018) and Homayouni et al. (2019). We do not find a systematic trend toward larger disk sizes as found in the Pan-STARRS sample (Jiang et al. 2017) and individual objects such as NGC 5548 (Fausnaugh et al. 2016), NGC 4151 (Edelson et al. 2017), and NGC 4593 (Cackett et al. 2018). Part of the discrepancy can be due to the choice of the correction factor X in the disk model. While most previous studies (e.g., Fausnaugh et al. 2016; Jiang et al. 2017; Cackett et al. 2018) adopted $X = 2.49^{4/3} = 3.36$, we adopt $X = 5.04$ after taking the effect of disk variability into account. We note that if we instead use $X = 3.36$ (the blue dotted line in Figure 18), the observed disk sizes for most quasars will be larger than the prediction of the model. In addition, the small number of well-studied NGC objects are among the brightest nearby AGNs, and their accretion disk sizes may not be representative of typical AGNs, or of the predominantly higher-luminosity quasars in our study.

6. Objects without Lag Measurements

We did not recover time lags for the vast majority of the quasars that passed our first selection cuts, as described in Section 3 and illustrated in Figure 3. Only 22 quasars are in our main sample, while a total of 48 objects in the MaxVis field, 457 objects in the SDSS fields, and 297 objects in the C26202 fields met the initial criteria in at least one observational season. One manifestation of a failed lag measurement is a wide, smooth lag distribution without clear peaks and centered on zero, associated with extremely large top-hat smoothing factors

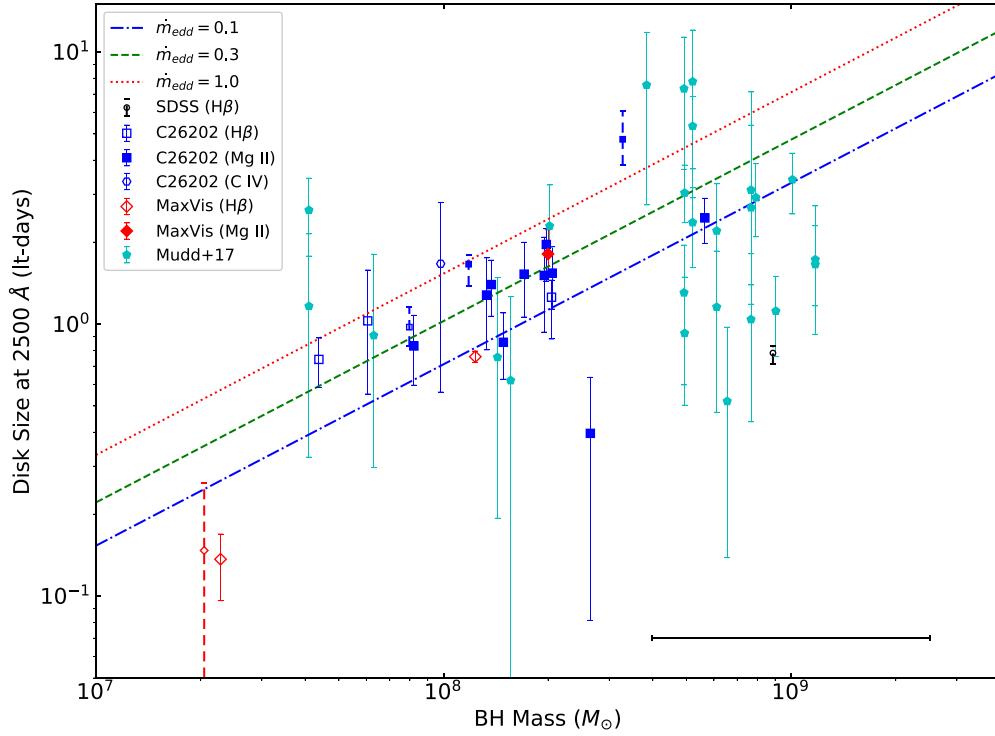


Figure 17. Accretion disk size at rest frame 2500 Å as a function of black hole mass. The blue dashed-dotted, green dashed, and red dotted lines represent the prediction of the thin-disk model for Eddington ratios of 0.1, 0.3, and 1.0, respectively. The red diamonds, blue squares, black circles, and cyan pentagons represent the results from the MaxVis field, the C26202 field, the SDSS fields, and Mudd et al. (2018), with error bars for the 1σ uncertainties. For the objects from this work, the smaller markers with dashed error bars represent the flagged objects, while the larger markers with solid error bars represent the objects with flag = 0 (the most secure results). The open hexagons represent black hole masses measured from C IV. Other open markers represent black hole masses measured from Mg II, while the filled markers represent black hole masses measured from H β . The typical uncertainty of the black hole mass is about 0.4 dex, shown as the black error bar in the lower right corner.

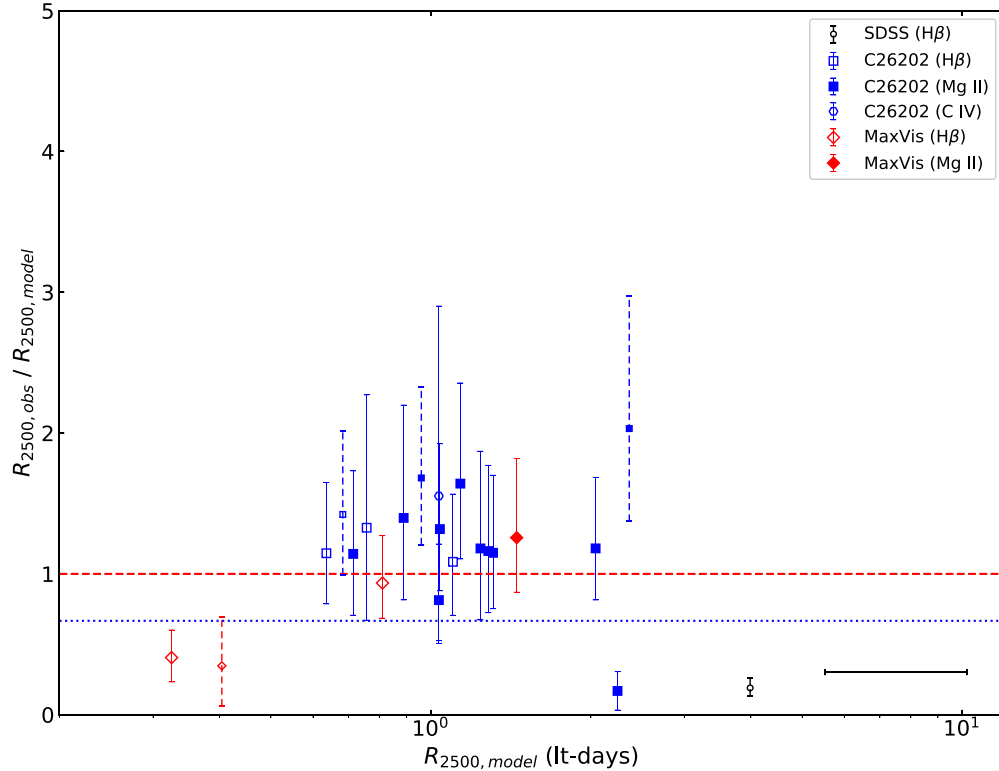


Figure 18. Ratio $R_{\text{obs}}/R_{\text{model}}$ of the observed disk size to the predicted disk size vs. the thin-disk model prediction. The symbols have the same meaning as in Figure 17. The red dashed line is drawn at $R_{\text{obs}}/R_{\text{model}} = 1$, where the observed disk size equals the predicted disk size from the model using $X = 5.04$. The blue dotted line is drawn at $R_{\text{obs}}/R_{\text{model}} = 0.67$, where the observed disk size equals the predicted disk size with $X = 3.36$. The uncertainty of the predicted accretion disk is shown as the black error bar in the lower right corner, considering that the uncertainty of the black hole mass is about 0.4 dex.

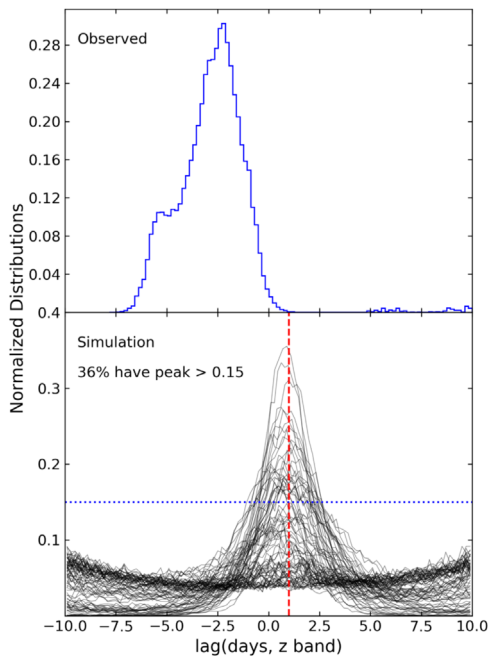


Figure 19. Top panel: probability distribution of the time lags in the z band from the observed light curves of DES J063227.29–583915.00 from JAVELIN. Bottom panel: z -band lag distributions from 80 realizations of the simulated light curves of DES J063227.29–583915.00 with an input time lag of 1 day. The red dashed line shows the position of the input time lag. The blue dotted line shows the position where the probability density equals 0.15. Only 36% of the realizations show significant peaks with the peak probability density larger than 0.15.

from JAVELIN. About 43 objects in the MaxVis field, 433 objects in the SDSS fields, and 126 objects in the C26202 fields show this wide lag distribution and are excluded by criteria 1 and 3 in Section 3.1. These objects tend to have low variability amplitudes relative to the photometric uncertainties.

For quasars with significant variability, another manifestation of an unsuccessful lag measurement is a lag distribution with multiple peaks that have similar amplitudes. About 23 objects in the SDSS fields and 151 objects in the C26202 fields show lag distributions with multiple peaks and are filtered out by criterion 2 in Section 3.1. These objects can violate criterion 1 as well if there are many secondary peaks at negative lags. While one of the multiple peaks can be physical, we cannot distinguish it from other peaks that may be caused by artifacts, so we do not include objects in the main sample if the lag distributions show multiple peaks with similar amplitudes in all bands.

Among the objects without good lag measurements, we find one object in the MaxVis field and two objects in the C26202 fields where JAVELIN produces clear single peaks located at zero or negative lags. As an example, the top panel of Figure 19 shows the z -band lag distribution from the observed light curves of DES J063227.29–583915.00. The lag distribution peaks at a negative lag, which is inconsistent with the standard thin-disk model. To verify whether the negative lags are real, we perform simulations as described in Section 4.1 with 80 realizations. The bottom panel of Figure 19 shows the simulation results of DES J063227.29–583915.00 for a simulated lag of 1 day, the predicted z -band lag from the thin-disk model for this object. The lag distributions from most realizations ($\sim 64\%$) are smooth distributions without clear peaks. Only a small fraction ($\sim 36\%$) show very wide peaks around the input lag with the peak probability density larger

than 0.15, while nearly none of the peaks are significant lag detections according to the standards we used to generate our lag measurements of the main sample in Section 3. This indicates that we are unlikely to obtain a reliable lag measurement for this object. We get similar results from simulations of other objects that seem to have zero or negative lag measurements, and we do not find any objects that show zero or negative lag that are verified by simulations. Note that the number of clear positive lags (22) is significantly larger than the number of possible zero/negative lags we found (3), and none of the possible zero/negative lags are as significant as the positive lags in the main sample. This indicates that the false-positive rate of our sample is very low.

In addition to quantifying the number of negative lags, we also reversed the time order of our light curves to verify that reversing the time order produces negative lags. This is to check that our lag detection algorithms are not biased to yield positive measurements. We created time-reversed light curves for all objects in the main sample in the seasons with lag measurements. For objects with multiseason results, we performed the test on the first season that produces lag measurements. We ran JAVELIN on these time-reversed light curves. Figure 20 shows examples of the comparison between the original and time-reversed results. The original and time-reversed light curves produce nearly⁵⁴ symmetric distributions about zero. That is, reversing the time sequence simply changes the sign of the lags. In this case, the only objects that will possibly have positive detections for the time-reversed light curves are those with clear negative lags. As discussed above, we only found three insignificant zero/negative lags and therefore a very low false-positive rate.

7. Effect of Cadence on Lag Measurements

The next-generation large sky survey after DES is the Large Synoptic Survey Telescope (LSST) project (e.g., LSST Science Collaboration et al. 2009). LSST will carry out a survey covering about $20,000 \text{ deg}^2$, repeatedly scanning the region about 1000 times during a 10 yr period. In addition to the main survey, LSST plans to intensively observe a set of Deep Drilling Fields (DDFs), with about 5% of the total observing time. Each DDF has a diameter of $3''.5$, and the five DDFs in the LSST Reference Simulated Survey “minion_1016” (e.g., LSST Science Collaboration et al. 2017) cover about 50 deg^2 in total. The large amount of observing time dedicated in each Deep Drilling Field is likely to enable the measurement of accretion disk sizes for many more quasars and with smaller uncertainties. In this section, we use our results to consider how to optimize the observation strategy for the DDFs to measure more accretion disk sizes.

One of the most important factors that affect disk size measurements is the observational cadence, which is still under discussion for the LSST DDFs. We investigate the effect of observational cadence on the fraction of quasars with good disk size measurements with simulated light curves. To construct simulated light curves, we first use the LSST Operation Simulator (OpSim) v3.3.5 (Delgado et al. 2014) to generate the observation schedule, as well as the depth of each epoch. We use three configurations in running OpSim. One is the official configuration of the LSST Reference Simulated Survey

⁵⁴ They are not exactly symmetric because of the random sampling inherent in the Markov Chain Monte Carlo method used by JAVELIN.

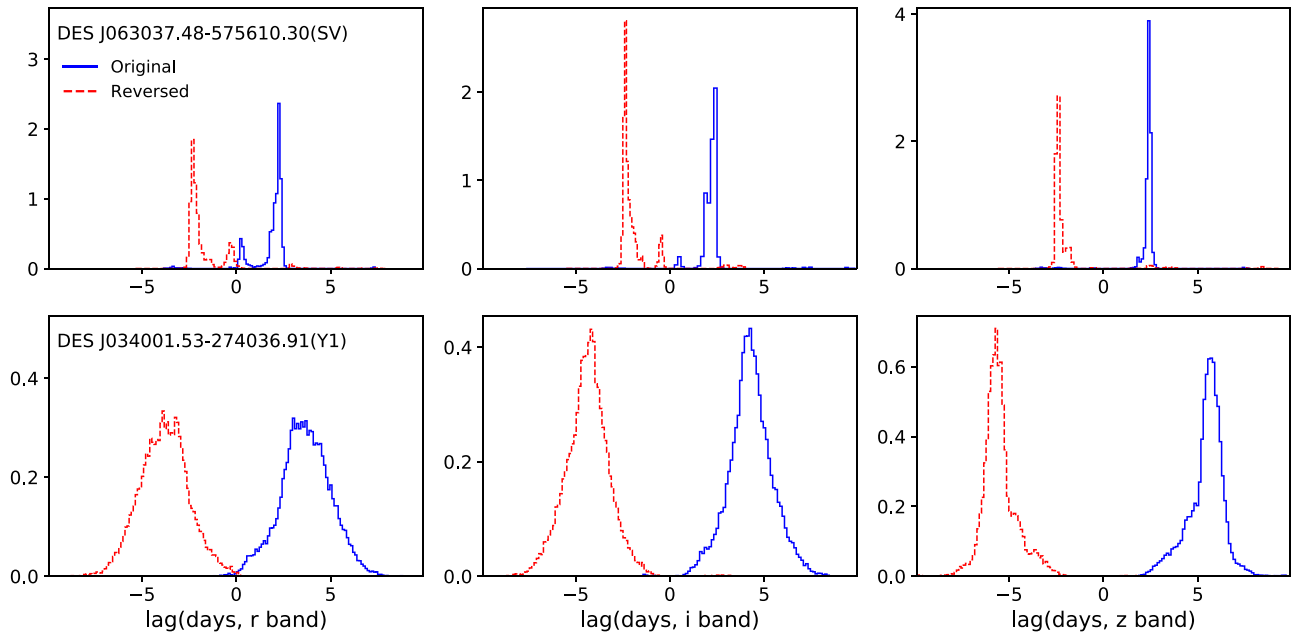


Figure 20. Time lag distributions from JAVELIN for the time-reversed light curves in comparison with the original light curves. The top and bottom rows show the results for DES J063037.48–575610.30 and DES J034001.53–274036.91, respectively. The first through the third columns give the time lag distributions in the *riz* bands, respectively. The blue solid lines represent the results for the original light curves, while the red dashed lines are for time-reversed light curves. See Section 6 for more details.

“minion_1016.” In this configuration, the Deep Drilling Fields are observed on a roughly 3-day cadence in the *grizY* bands. The mean 5σ depth in each epoch is about 25.02, 25.35, 24.81, and 24.48 mag for the *g*, *r*, *i*, and *z* bands, respectively. We refer to this configuration as the “3-day configuration.” We create the “2-day configuration” and “1-day configuration” by requesting OpSim to increase the number of epochs by a factor of 1.5 and 3, respectively, while reducing the exposure time in each single epoch such that the net integration time is nearly unchanged. The “2-day configuration” has an observational cadence around 2 days, with a median 5σ depth of about 24.84, 25.13, 24.57, and 24.25 mag for the *g*, *r*, *i*, and *z* bands, respectively. The “1-day configuration” has nearly daily observational cadence, with a median 5σ depth of about 24.51, 24.73, 24.21, and 23.81 mag for the *g*, *r*, *i*, and *z* bands, respectively. The total exposure time obtained in the Deep Drilling Fields for the three configurations is nearly identical.

We then simulated a quasar with mean $(g, r, i, z) = (21.0, 20.5, 20.0, 19.2)$ mag using a DRW. We converted the magnitudes to fluxes with arbitrary units for the light curves and adopted DRW parameters $\sigma_{\text{DRW}} = 2.5$ (flux unit) and $\tau_{\text{DRW}} = 200$ days. The mean magnitudes and DRW parameters are typical of the quasars in our DES sample. We created the DRW light curves following a similar procedure to what is described in Section 4.1, and with the cadence specified by the observation schedule from OpSim. Combining the magnitude of the quasar and the depth of LSST, we calculate the photometric uncertainties in each epoch. To allow for additional uncertainties, such as if the variability does not exactly follow the DRW, or systematics in the magnitude measurements in the single-epoch data, we set the minimum uncertainty of each data point to be 1%, even if all the photometric uncertainties are predicted to be smaller.

Figure 21 shows an example of the three simulated light curves in the *g* band in the left column. One feature of the observation schedules from OpSim is that the light curves have

gaps between a series of continuous observations, and the width of the gap is about a week. To investigate the effect of these gaps on lag measurements, we create another version of the simulated light curves with the gaps removed. Specifically, if an observation is more than 5 days away from the previous observation, we change this observation to the date when it is 1, 2, or 3 days after the previous observation, depending on the typical cadence of the light curve. As part of this process, we reduce the length of the baseline, while keeping the number of epochs constant. We show an example of the light curves without gaps in the right column of Figure 21. These three alternate scenarios use the same total integration time, although the removal of the gaps decreases the total baseline of observations by approximately a factor of 2.

For these six scenarios, i.e., 1-, 2-, or 3-day cadence, with or without gaps, we create 25 realizations of the DRW light curves in the *g* band. We shift the *g*-band light curves by the same input time lag in *r*, *i*, and *z* bands to create the simulated light curves in these bands. The input time lag ranges from 1 to 8 days in steps of 1 days. We use JAVELIN to measure the time lags between simulated light curves and define a successful measurement for one *band* if the JAVELIN results satisfy the following:

1. the 1σ lower limit from the probability distribution of the time lag is larger than 0;
2. the lag distribution shows a clear single peak at a positive lag; and
3. the 1σ upper limit of the top-hat smoothing factor is smaller than 50.

We added the third criterion because large smoothing factors are usually associated with smooth lag distributions without clear peaks, which is a common feature of the failed fits from JAVELIN. We define a successful lag recovery for a *realization* if the time lags are successfully measured in at least two of the *r*, *i*, and *z* bands. We define the lag recovery

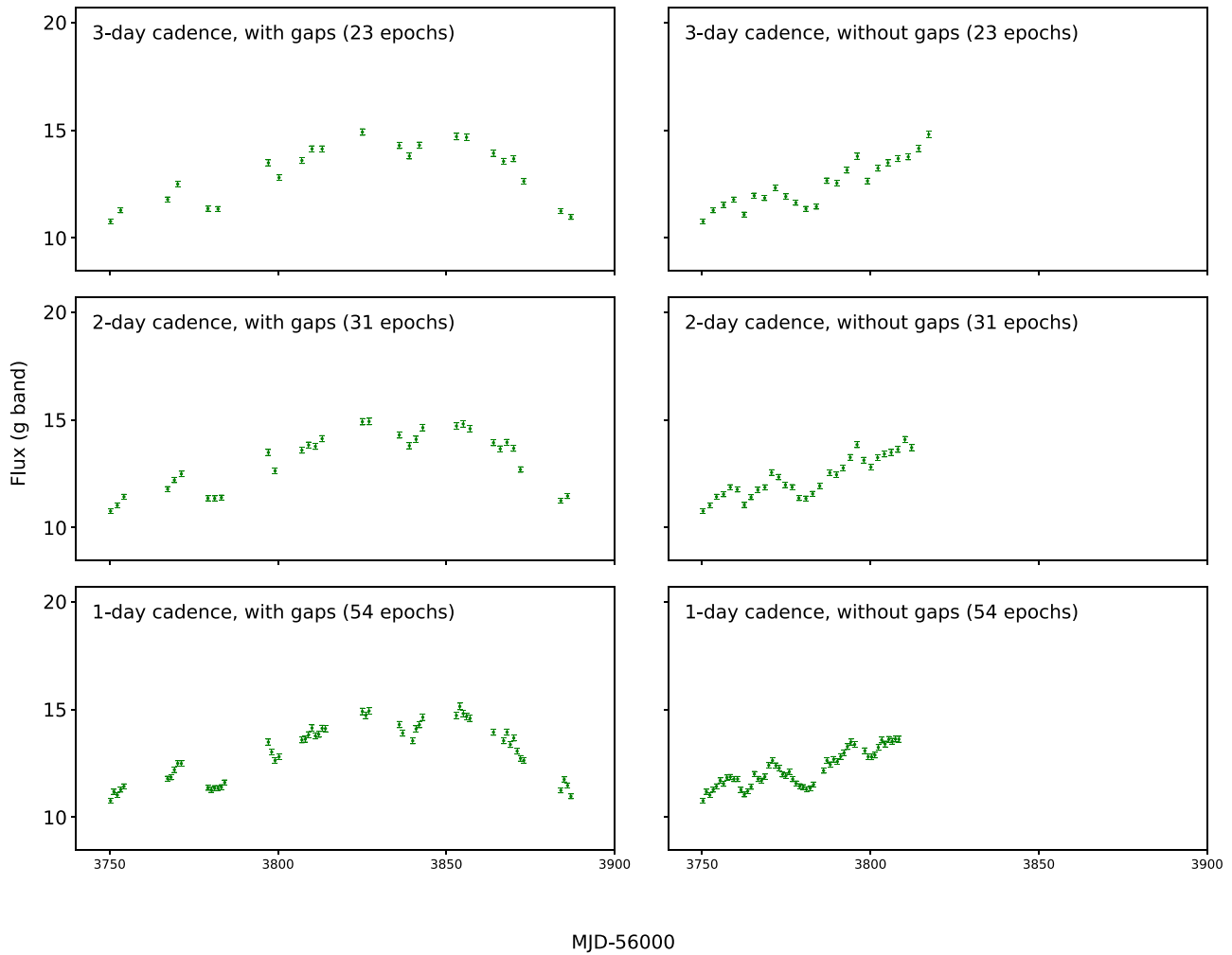


Figure 21. Simulated g -band light curves for one observational season for quasars in the LSST DDFs. The fluxes are in arbitrary units. The top, middle, and bottom rows show the light curve from a 3-, 2-, and 1-day cadence from OpSim, respectively. The left column shows the light curves with gaps, while the right column shows the light curves where gaps are removed. The light curves with the 3-, 2-, and 1-day cadence have about 23, 31, and 54 epochs in one observational season, respectively.

fraction as the number of realizations where we recover lags successfully divided by the total number of realizations (25). We plot the recovery fraction as a function of input time lag in Figure 22. For input time lags smaller than 5 days, the lag recovery fractions increase significantly toward higher cadences. Notably, for an input lag of 1 day, the 2-day cadence and 1-day cadence can increase the lag recovery fraction by a factor up to 5 and 10 compared to the 3-day cadence, respectively. For input time lags larger than 5 days, the trend can reverse for light curves with gaps, which may be due to aliasing produced by the gaps in the light curves. For light curves without gaps, higher cadences never produce recovery fractions smaller than those from lower cadences, as expected. This indicates that we can significantly improve the yield of accretion disk size measurements if we change the observational cadence in the DDFs from the official 3 days to 2 days or 1 day, while the total exposure time and the final co-added depth of the DDFs will not be affected.

To estimate the distribution of the observed time lags from real quasars, we use the SDSS DR7 quasar sample presented by Shen et al. (2011). The uniformly selected quasar sample contains 59,514 quasars with flux limits of $i = 19.1$ mag at $z < 2.9$ and $i = 20.2$ mag at $z > 2.9$, where i is the i -band

magnitude and z is redshift. We adopt the fiducial single-epoch black hole mass from Shen et al. (2011) and use the standard thin-disk model to calculate the accretion disk size and the time lag in the r , i , and z band relative to g band assuming that the Eddington ratio equals 0.1. The bottom panel of Figure 22 shows the distribution of the predicted time lag. A large fraction of the lags are less than 5 days, where higher observational cadence can significantly increase the recovery fraction. The observations of the LSST DDFs will be much deeper than SDSS and will detect more low-luminosity AGNs with smaller black hole masses and hence smaller continuum lags. In addition, AGNs with smaller black hole masses tend to be more variable, and thus lag measurements should be easier. We therefore expect more small time lags in the LSST DDFs than what is implied by the bottom panel of Figure 22. Given that the observed continuum lags from real quasars are expected to be small, a higher observational cadence in the LSST DDFs can help improve the yield of quasar accretion disk sizes significantly.

We present an order-of-magnitude estimate of the number of successful continuum lag measurements in the LSST DDFs. We relate the number of lag measurements in the LSST DDFs

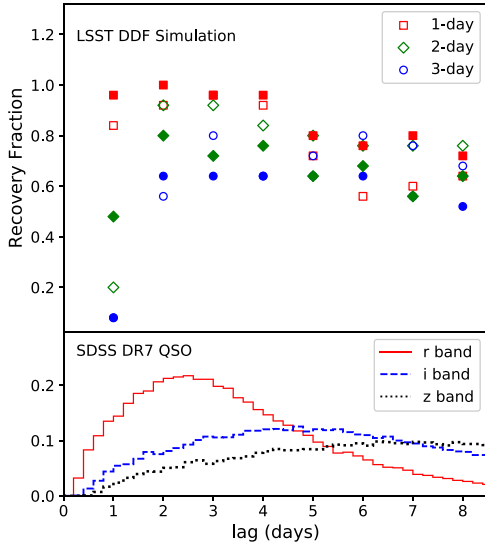


Figure 22. Top panel: recovery fraction of time lags from simulated light curves in the LSST DDFs as a function of input time lags. The red squares, green diamonds, and blue circles represent the result for light curves with a 1-, 2-, and 3-day cadence, respectively. The open symbols represent results from light curves with gaps, while filled markers are from light curves without gaps. Bottom panel: predicted lag distributions for the SDSS DR7 quasars. The red, blue, and black lines represent the lag distribution in the r , i , and z band relative to g band, respectively.

to our DES results as

$$N_{\text{lags}}(<m_{\text{lsst}}) = f_{\text{lsst}} \times N_{\text{qso}}(<m_{\text{lsst}}) \quad (15)$$

$$f_{\text{lsst}} = \frac{\Sigma_{\text{lags}}(<m_{\text{des}})}{\Sigma_{\text{qso}}(<m_{\text{des}})} \times \alpha_{\text{cad}} \times \beta_{\text{depth}}, \quad (16)$$

where $N_{\text{lags,lsst}}$ is the total number of AGNs with continuum lag measurements in the LSST DDFs, $\Sigma_{\text{lags}}(<m_{\text{des}})$ is the surface density of lag measurements in the DES fields, $\Sigma_{\text{qso}}(<m_{\text{des}})$ is the surface density of AGNs detected in the DES fields, $N_{\text{qso}}(<m_{\text{lsst}})$ is the number of AGNs brighter than the magnitude limit m_{lsst} in the LSST DDFs, α_{cad} is the correction factor of different cadences between DES and LSST, and β_{depth} is the correction factor of different depths. We define the magnitude limit m_{lsst} as the magnitude corresponding to 1% photometric errors and do not consider fainter objects.

The term $\Sigma_{\text{lags}}(<m_{\text{des}})/\Sigma_{\text{qso}}(<m_{\text{des}})$ represents the fraction of continuum lag measurements in the DES fields. We estimate this fraction based on the results from the C26202 fields, which combine the 1-day cadence standard-star observations and 7-day cadence supernova observations. We obtain 17 good measurements out of 318 input AGNs, so we have $\Sigma_{\text{lags}}(<m_{\text{des}})/\Sigma_{\text{qso}}(<m_{\text{des}}) \approx 17/318 \approx 0.0536$.

We estimate the cadence correction factor α_{cad} with the same simulation framework as discussed above. The mean observational cadence of the input quasar sample in the C26202 fields is around 5 days, while the proposed cadence for AGN science in the LSST DDFs is around 2 days (Brandt et al. 2018). The mean continuum lag of the riz bands relative to the g band in the C26202 fields is around 3 days. We find that for an input time lag of 3 days, a 2-day cadence can increase the lag recovery fraction by a factor of about 1.35 compared to a 5-day cadence, so we have $\alpha_{\text{cad}} \approx 1.35$.

The correction factor β_{depth} accounts for the depth difference between DES and LSST. One important difference is that

deeper observations lead to smaller single-epoch uncertainties. However, for the deep DES supernova and the LSST DDF observations, the single-epoch uncertainties are dominated by calibration uncertainties instead of statistical errors, so the improvement of lag measurements from smaller single-epoch errors will not be significant. Another difference is that deeper LSST observations allow the detection of more low-luminosity AGNs, which tend to be more variable and therefore make it easier to measure lags. We note that the fraction of successful measurements does increase toward lower luminosities for our results from the C26202 fields, and we estimate $\beta_{\text{depth}} \approx 2.32$.

According to the LSST OpSim, the median single-epoch 5σ depth in the i band for a 2-day cadence is about 24.57 mag, so we have $m_{i,\text{lsst}} \approx 23.8$. Based on the quasar luminosity functions by Manti et al. (2017), we estimate $\log(N_{\text{qso}}) \approx 4.2$. Plugging these parameters into Equation (15), we get $N_{\text{lags}}(<m_{\text{lsst}}) \approx 2653$. That is, we expect to have about 3000 disk size measurements in the LSST DDFs with a 2-day observation cadence.

We stress that this calculation is just an order-of-magnitude estimate. Some potentially important effects that we did not include are as follows: (1) We did not consider AGNs with photometric errors larger than about 1%, while these objects may also yield lag measurements. (2) The fraction of lag measurements based on our DES sample is limited by small number statistics. (3) When estimating α_{cad} and β_{depth} , we used the mean cadences, lags, and depths without considering the distribution of these parameters in detail.

8. Summary

We present quasar accretion disk size measurements through continuum RM using data from DES standard-star observations. We select spectroscopically confirmed and color- and variability-selected quasars in the MaxVis field, the SDSS fields, and the C26202 fields and construct continuum light curves with the DES photometry from SV to Y4 in the $griz$ bands. We use the JAVELIN and ICCF methods to measure time lags between different bands, and we use the JAVELIN thin-disk model to fit for the accretion disk sizes. We create simulated light curves and reweighted light curves to verify the lag measurements from JAVELIN and ICCF. We confirm that the DES photometric errors are Gaussian and appropriate for JAVELIN. We also create simulated light curves in the LSST DDFs and probe the effect of observational cadence on continuum lag measurements. Our main results are as follows:

1. We successfully measure the time lags and accretion disk sizes from 22 quasars, with black hole mass spanning 10^7 – $10^9 M_{\odot}$, among which 17 have no flags and therefore are the most secure. Our measurements have smaller uncertainties than Mudd et al. (2018) thanks to the higher observational cadence of the DES standard-star fields.
2. Most of the measured accretion disk sizes are consistent with the predictions of the standard thin-disk model if we take the disk variability into account.
3. We have simulated several alternative observation strategies for the LSST DDFs and found that the yield of accretion disk size measurements should increase significantly if the cadence were changed from 3 days to 2 days or 1 day.

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Software: JAVELIN (Zu et al. 2011), JAVELIN thin-disk model (Mudd et al. 2018), PyCCF (Sun et al. 2018), pyspeckit (Ginsburg & Mirocha 2011), Astropy (Astropy Collaboration et al. 2013, 2018), SciPy (Jones et al. 2001), Numpy (Travis 2006), Matplotlib (Hunter 2007), Pandas (McKinney 2010).

Appendix Comments on Individual Lag Measurements

We comment on the time lag distributions in Figures 5 and 6 and discuss the comparisons between the JAVELIN and ICCF results for each object in the main sample. First, we clarify the “consistency” between the two methods. There are three cases:

- (1) The lag distributions from both methods show clear peaks, and they agree with each other at the 1σ level.
- (2) Only one method gives lag measurements, while the other method fails to measure the lags. This may also include the case where the lag distribution does show a peak but is much wider than the distribution from the other method.
- (3) The lag distributions from both methods show clear peaks, but they disagree with each other.

We add $\text{flag} = 2$ to the objects where JAVELIN and ICCF produce inconsistent lag distributions that satisfy case 2 or case 3 in all bands.

While both case 2 and case 3 are cases of “inconsistent” results, case 2 is less critical since it only indicates that the uncertainty estimates from the two methods are quite different, or one method does not work well for a particular sampling of the light curve. This difference between JAVELIN and ICCF has been discussed in many RM studies either on continuum or on emission lines (e.g., Grier et al. 2017; Mudd et al. 2018; Czerny et al. 2019), and detailed studies on this difference are beyond the scope of this paper.

Comments on the unflagged objects are as follows:

DES J063037.48–575610.30: The ICCF peak distribution in the i band shows a peak around 2.5 days, consistent with the JAVELIN lag distributions. The ICCF center distributions are much wider than JAVELIN. This is in fact an extreme case of the lag uncertainty difference between JAVELIN and ICCF. The ICCF center distributions do show peaks and are consistent with JAVELIN at the 1σ level, while these peaks are too wide to see clearly in normalized histogram plots.

DES J063510.91–585303.70: The ICCF distributions show clear peaks in all three bands and are consistent with JAVELIN.

DES J063159.74–590900.60: The ICCF distributions show clear peaks in all three bands. The distributions are consistent with JAVELIN in the i band and z band. The main peaks of ICCF in the r band differ slightly from the JAVELIN results, but they still agree at the 1σ level.

DES J034003.89–264524.52: The ICCF distributions show clear peaks in all three bands and are consistent with JAVELIN.

DES J032724.94–274202.81: The ICCF center distributions are much wider than JAVELIN in the r band and i band, i.e., case 2 discussed above. The ICCF center distribution in the z band shows a peak at negative lags and disagrees with the JAVELIN results. However, the ICCF peak distributions show clear peaks in all three bands and are consistent with JAVELIN.

DES J033545.58–293216.51: The ICCF center distributions are generally much wider than JAVELIN. However, the ICCF peak distributions show clear peaks in all three bands and are consistent with JAVELIN.

DES J033810.61–264325.00: The ICCF distributions show clear peaks in all three bands. They are consistent with JAVELIN in the r band and i band. The JAVELIN results differ from the ICCF center distribution but still agree with the ICCF peak distribution at the 1σ level in the z band.

DES J034001.53–274036.91: The ICCF distributions show clear peaks in all three bands and are consistent with JAVELIN.

DES J033853.20–261454.82: The ICCF distributions show clear peaks in the r band and are consistent with JAVELIN. In the i band the ICCF distributions are much wider than JAVELIN and are closer to case 2 discussed above. The ICCF center distribution in the z band is ambiguous, while the ICCF peak distribution still shows a clear peak and is consistent with JAVELIN.

DES J033051.45–271254.90: The ICCF distributions are ambiguous in the r band and z band, which satisfies the case 2 inconsistency. However, the ICCF distribution in the i band shows a clear peak and is consistent with JAVELIN.

DES J032853.99–281706.90: The ICCF center distributions are generally much wider than JAVELIN. However, the ICCF peak distributions show clear peaks in all three bands and are consistent with JAVELIN in the i band and z band. The ICCF peak distributions differ from JAVELIN in the r band.

DES J033230.63–284750.39: The ICCF distributions show clear peaks in all three bands and are consistent with JAVELIN.

DES J033729.20–294917.51: The ICCF distributions show clear peaks and are consistent with JAVELIN in the r band. While the ICCF peak distributions are ambiguous in the i band, the ICCF center distributions still show a peak and are consistent with JAVELIN at the 1σ level.

DES J033220.03–285343.40: The ICCF distributions show clear peaks in all three bands and are consistent with JAVELIN in the i band and z band. While the ICCF peak distributions seem to differ from JAVELIN in the r band, they still agree at the 1σ level.

DES J033342.30–285955.72: The ICCF distributions show clear peaks in all three bands and are consistent with JAVELIN, except for a slight difference between JAVELIN and the ICCF center distributions in the i band.

DES J033052.19–274926.80: The ICCF distributions show clear peaks in both bands and are consistent with JAVELIN.

DES J033238.11–273945.11: The ICCF distributions are ambiguous in the r band and z band, which satisfies the case 2 inconsistency. However, the ICCF results show clear peaks in the i band and are consistent with JAVELIN.

Comments on the flagged objects are as follows:

DES J062758.99–582929.60: The ICCF distributions are generally ambiguous and satisfy the case 2 inconsistency with JAVELIN.

DES J033002.93–273248.30: The ICCF distributions are generally ambiguous and satisfy the case 2 inconsistency with JAVELIN.

DES J033408.25–274337.81: The ICCF distributions are generally much wider than JAVELIN and are closer to the case 2 inconsistency.

DES J032801.84–273815.72: The ICCF distributions are generally ambiguous and satisfy the case 2 inconsistency with JAVELIN.

DES J005905.51+000651.66: The ICCF distributions are much wider than JAVELIN and are closer to the case 2 inconsistency in the r band and z band. The ICCF distributions show clear peaks in the i band but disagree with JAVELIN.

In summary, all unflagged objects in the main sample have consistent JAVELIN and ICCF results in at least one of the riz bands. Most discrepancies between JAVELIN and ICCF follow case 2 discussed above, and the case 3 discrepancies are rare.

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