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Turbulent pressure support and hydrostatic mass bias in the intracluster medium

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ABSTRACT

The degree of turbulent pressure support by residual gas motions in galaxy clusters is not well known. Mass modelling of combined X-ray and Sunyaev–Zel’dovich observations provides an estimate of turbulent pressure support in the outer regions of several galaxy clusters. Here, we test two different filtering techniques to disentangle bulk from turbulent motions in non-radiative high-resolution cosmological simulations of galaxy clusters using the cosmological hydrocode ENZO. We find that the radial behaviour of the ratio of non-thermal pressure to total gas pressure as a function of cluster-centric distance can be described by a simple polynomial function. The typical non-thermal pressure support in the centre of clusters is ~ 5 per cent, increasing to ~ 15 per cent in the outskirts, in line with the pressure excess found in recent X-ray observations. While the complex dynamics of the intracluster medium makes it impossible to reconstruct a simple correlation between turbulent motions and hydrostatic bias, we find that a relation between them can be established using the median properties of a sample of objects. Moreover, we estimate the contribution of radial accelerations to the non-thermal pressure support and conclude that it decreases moving outwards from 40 per cent (in the core) to 15 per cent (in the cluster’s outskirts). Adding this contribution to one provided by turbulence, we show that it might account for the entire observed hydrostatic bias in the innermost regions of the clusters, and for less than 80 per cent of it at $r > 0.8 r_{200,m}$.

Key words: hydrodynamics – turbulence – methods: numerical – galaxies: clusters: general – galaxies: clusters: intracluster medium – large-scale structure of Universe.

1 INTRODUCTION

Turbulence plays a key role in the assembly of large-scale structure and in controlling the physics of the intracluster medium (ICM) (e.g. Brunetti & Jones 2014). The origin and evolution of turbulence in the ICM have been widely studied using hydrodynamical simulations (e.g. Dolag et al. 2005; Lau, Kravtsov & Nagai 2009; Vazza et al. 2011; Gaspari et al. 2014; Miniati 2014). Various physical processes produce turbulence in galaxy clusters, such as the injection and amplification of vorticity by shock waves (e.g. Ryu et al. 2008; Porter, Jones & Ryu 2015; Vazza et al. 2017) or ram pressure stripping (e.g. Cassano & Brunetti 2005; Subramanian, Shukurov &

Haugen 2006; Roediger & Brüggen 2007). Moreover, winds from starburst galaxies and outflows from active galactic nuclei stir the ICM, especially in cluster cores (e.g. Brüggen, Hoeft & Ruszkowski 2005; Gaspari et al. 2011).

Direct observations of turbulent gas motions in the ICM are almost entirely missing. Only the soft X-ray spectrometer on-board *Hitomi* satellite has directly detected turbulent gas motions in the core of the Perseus cluster, a fairly relaxed cluster. Using the width of atomic lines, the root mean square (rms) velocities were found to be $\sim 200 \text{ km s}^{-1}$ on $\leq 60 \text{ kpc}$ scales (e.g. Hitomi Collaboration et al. 2016; ZuHone et al. 2018). This would correspond to a 2–6 per cent non-thermal pressure support in the case of isotropic turbulent motions, or to a 11–13 per cent non-thermal pressure support in case the motions are due to larger scale sloshing (Hitomi Collaboration et al. 2018).

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Radio observations of Faraday rotation of polarized sources located behind galaxy clusters hint at a tangled magnetic field in the ICM with typical coherence scales in the range of $\sim 10\text{--}50$ kpc (e.g. Murgia et al. 2004; Vogt & Enßlin 2005; Bonafede et al. 2010), which is naturally explained by volume-filling stretching motions induced by turbulence (e.g. Dolag et al. 2001; Donnert et al. 2018; Domínguez-Fernández et al. 2019). In order to explain their observed morphology and strength, other indirect probes of turbulent motions are obtained from highly resolved X-ray surface brightness fluctuations, which are interpreted as indications of moderate density fluctuations induced by turbulence (e.g. Schuecker et al. 2004; Churazov et al. 2012; Gaspari et al. 2014; Zhuravleva et al. 2014). From a comparison between X-ray and radio observations, it has been suggested that the surface brightness fluctuations correlate with the diffuse radio emission (Eckert et al. 2017b; Bonafede et al. 2018). This suggests that turbulence detected in X-ray emission could be linked to the re-acceleration of radio-emitting particles, via different mechanisms (e.g. Brunetti & Lazarian 2011; Brunetti & Vazza 2020). This turbulence is expected also to contribute to the total pressure of the ICM, thus biasing the hydrostatic mass reconstruction (Morandi et al. 2011; Parrish et al. 2012; Shi & Komatsu 2014; Shi et al. 2015, 2016; Fusco-Femiano & Lapi 2018; Ota, Nagai & Lau 2018; Fusco-Femiano 2019).

Recently, Eckert et al. (2019) and Ettori et al. (2019) presented results of a systematic study of non-thermal support and hydrostatic mass bias in a sample of galaxy clusters observed for the *XMM-Newton* large program X-COP (Eckert et al. 2017a). The observed mass bias implies that the non-thermal pressure support in the outskirts of nearby, relaxed, massive galaxy clusters (such as the X-COP targets) should vary between 5 and 15 per cent. Such values are a factor of 2 to 3 below what is found in numerical simulations (e.g. Kay et al. 2004; Faltenbacher et al. 2005; Hallman et al. 2006; Rasia et al. 2006; Nagai, Kravtsov & Vikhlinin 2007; Lau et al. 2009; Vazza et al. 2011; Nelson, Lau & Nagai 2014a; Biffi et al. 2016). This discrepancy may either be due to missing physics in the simulations such as physical viscosity, magnetic fields, or due to an incorrect separation of turbulent and bulk motions. The results from cosmological simulations may depend on the numerical techniques used to disentangle bulk from turbulent motions. As recently discussed in Vazza et al. (2018), different definitions of turbulent motions in numerical simulations could yield non-thermal pressures that differ by factors of 2 to 3, even within the same simulations. Valdarnini (2019a) studied turbulent motions in galaxy clusters simulated with (radiative and non-radiative) *N*-body/SPH (smoothed particle hydrodynamics) codes, using a multiscale filtering technique. Their results are consistent with Vazza et al. (2018), despite the difference in the underlying hydro schemes. This suggests that advanced filtering techniques to study the internal dynamics of the simulated ICM are important to assess the mass bias in galaxy clusters.

In this paper, we measure the non-thermal pressure support by gas motions in the simulated ICM. We apply advanced filtering techniques to identify turbulence in a sample of galaxy clusters produced with high-resolution Eulerian simulations. Our results for the turbulent pressures are then compared to the constraints obtained in the X-COP sample (Eckert et al. 2019), and in other numerical simulations (Nelson et al. 2014a). The paper is structured as follows. In Section 2, we describe our cluster sample and the numerical techniques used in the analysis of turbulent motions in the simulated ICM. In Section 3, we present the results from the analysis of our sample and compare them to recent observational and numerical constraints. In Section 4, we analyse some possible

sources of discrepancies in the computation of hydrostatic bias, while in Section 5, we discuss our main findings, the limitations of our analysis, and their implications for future work.

2 METHODS

2.1 The Itasca Simulated Cluster (ISC) sample

We used the ISC sample for our analysis,¹ which is a set of nine galaxy clusters in the $5 \times 10^{13} \leq M_{100}/M_{\odot} \leq 4 \times 10^{14}$ mass range simulated at uniformly high spatial resolution with adaptive mesh refinement (AMR) and the piecewise parabolic method (PPM) in the ENZO fluid dynamics code (Bryan et al. 2014). Our simulations do not include radiative processes and assumed the WMAP7 Λ CDM cosmology (Komatsu et al. 2011), with $\Omega_B = 0.0445$, $\Omega_{DM} = 0.2265$, $\Omega_{\Lambda} = 0.728$, Hubble parameter $h = 0.702$, $\sigma_8 = 0.8$, and a primordial index of $n = 0.961$. Each cluster was generated from two levels of nested grids as initial conditions (each with 400^3 cells and dark matter particles and covering 63^3 Mpc³ and 31.5^3 Mpc³, respectively). At run time, we also imposed two additional levels of *static* mesh refinement in a 6.3^3 Mpc³ box around each object, for a fixed $\Delta x = 19.6$ kpc/cell comoving resolution. More information on the ISC sample can be found in Vazza et al. (2017), Wittor et al. (2017), and Vazza et al. (2018).

These simulations are non-radiative, in the sense that they do not include radiative gas cooling, nor the effect of heating from star-forming regions, reionization, or active galactic nuclei. Several studies have shown that the influence of non-gravitational effects is very limited in affecting the global properties of turbulence on the $\gg 100$ kpc scales of interest here, and outside of cluster cores, compared to the impact of mergers and accretion phenomena in the ICM (e.g. Vazza, Roediger & Brueggen 2012; Vazza, Brüggen & Gheller 2013; Valdarnini 2019b). However, the combination of cooling and feedback is known to increase the number of density substructures (and in general of the clumping of gas) in the ICM (e.g. Nagai & Lau 2011; Roncarelli et al. 2013), which can locally bias the estimates of gas density and temperature required to compute the global pressure profile of clusters. In this respect, while the gas velocity fields produced by our simulations can be considered realistic enough for regions outside of the cluster core, the gas pressure model of these simulations is likely to be smoother than in reality.

2.2 Cosmological selection of independent clusters

We take a new approach to building a large sample of galaxy clusters by treating clusters at different redshifts as dynamically independent. Under certain assumptions and for the sake of analysing the properties of turbulent motions in the ICM, these clusters can then be regarded as independent objects (Giocoli, Tormen & Sheth 2012a; De Boni et al. 2016). Hence, we obtained a sample of 68 clusters from $z \simeq 2$ to $z = 0$, which are separated in redshift by $\langle \Delta z \rangle \simeq 0.12$ that, for the Λ CDM cosmology, it corresponds to $\langle \Delta t \rangle \simeq 0.91$ Gyr. First, we computed $r_{100,c}$ and $M_{100,c}$ of each available snapshot for each object in the $z \leq 1$ range and reconstructed the mass growth of each cluster. Based on this, we could also compute the dynamical time of the cluster in each snapshot, assuming $t_{dyn} \approx r_{100}/\sigma_v$, with $\sigma_v = \sqrt{G M_{100}/r_{100}}$, which gives us an estimate for the time between two dynamically independent realizations of the same

¹<http://cosmosimfrazza.myfreesites.net/isc-project>.

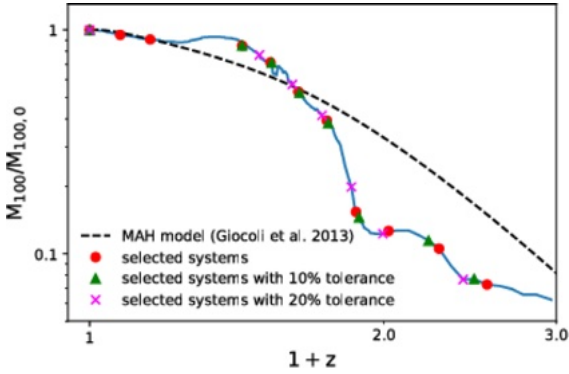


Figure 1. Example of real mass growth history (blue solid line) against the theoretical one (black dashed line) for one galaxy cluster of our sample. The different points represent the selected snapshots for different level of tolerance (red points 0 percent, green triangle 10 percent, pink cross 20 percent; see Section 2.2 for details).

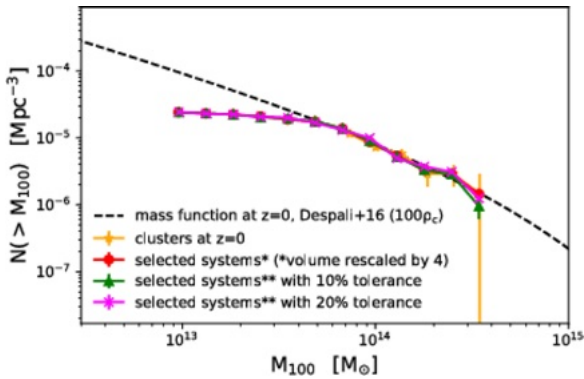


Figure 2. Mass functions of selected clusters at different levels of tolerance (i.e. the difference between the expected cosmological mass growth over a given time interval and the measured one). For comparison, the dashed black line gives the theoretical mass function for the cosmology used in our analysis at $z = 0$.

object. Going back in time from $z = 0$, we selected those snapshots that are separated by one dynamical time. Finally, we have to verify that the mass growth between the snapshots is compatible with the expected growth. In particular, we checked that the corresponding M_{100} mass is *below or equal* to the predicted mass, within some tolerance (0 ÷ 20 per cent), based on the theoretical mass growth for a given M_{100} at $z = 0$ for the given cosmology, as outlined in Giocoli et al. (2012a) and De Boni et al. (2016).

We treat each new selected cluster, along the mass growth, as independent from the previous one when calculating the theoretical mass accretion history (Giocoli, Tormen & Sheth 2012b). In Fig. 1, the blue curve displays the mass growth history of one of our cluster from $z = 0$ to $z = 2$. The dashed black line shows the corresponding mass accretion history model starting from the $z = 0$ system. The various data points indicate the selected independent clusters along the growth with different tolerance thresholds. Thus, we obtained a final sample of 68 clusters (with 0 per cent tolerance), yielding the total mass function shown in Fig. 2.

For comparison, the Despali et al. (2016) mass function at $z = 0$ for the same cosmology and total volume is shown as a black dashed line, and this suggests that our final sample is sufficiently

mass complete for $M > 5 * 10^{13} M_{\odot}$. This allows us to proceed with a statistical study of the dependence of turbulence on mass, redshift, and dynamical state parameters in subsamples. The limitations connected to this selection procedure are discussed in Section 5.

2.3 Identifying turbulence in the ICM

To disentangle turbulent from bulk motions, we use a small-scale filtering approach. In this technique, we assume that turbulent velocities are approximated as those parts of the gas velocities that fluctuate on the smallest scales, while bulk motions on the largest scales are approximately laminar. The validity of such an approach in cosmological simulations of galaxy clusters is supported by a large body of works on this subject (e.g. Dolag et al. 2005; Lau et al. 2009; Vazza et al. 2011, 2012; Miniati 2014; Vazza et al. 2017). With the use of an appropriate small-scale filter, it is possible to define the velocity of the bulk motions and to calculate the velocity of turbulent motions as the difference between the total velocity and the one associated to the bulk motions. In this section, we discuss the updated filtering technique that we used to disentangle turbulent from bulk motions, and the parameters that we tuned to limit the spurious contributions by shocks and clumps.

2.3.1 Iterative multiscale filtering of turbulent motions

The non-thermal to total pressure ratio, α , is given by

$$\alpha \equiv \frac{P_{nt}}{P_{tot}}, \quad (1)$$

where P_{nt} is the non-thermal pressure caused by turbulent motions and $P_{tot} = P_{nt} + P_{th}$ is the total pressure of the gas. P_{th} is the thermal gas pressure, computed as

$$P_{th} = \frac{k_b}{\mu m_p} \times \rho \times T, \quad (2)$$

where ρ is the gas density, T is the gas temperature, k_b is the Boltzmann constant, m_p is the proton mass, μ is the mean molecular mass for electrons gas, and its value is 0.59.

The non-thermal pressure P_{nt} is estimated as

$$P_{nt} = \frac{1}{3} \times \rho \times \delta v^2, \quad (3)$$

where δv is the local turbulent velocity; its estimate is in general non-trivial, and in the following we discuss our fiducial procedure to reconstruct it in simulation, as well as test another method used in the literature (see Section 2.3.2).

We use an adaptive, iterative filtering to disentangle turbulent from laminar motions in hydrodynamical grid simulations, which follows from previous works by our group (e.g. Vazza et al. 2012, 2018). The algorithm does not assume any a priori coherence scale and the local mean velocity field around each cell is reconstructed with a multiscale filtering technique, yielding the maximum scale of turbulent eddies by means of iterations in the smoothing scale length. The key assumption is that the gas flow in these simulations is generally part of a cascade of kinetic energy starting from scales much larger than the cell size.

In the original work, we applied a fixed tolerance on the increase of the local rms velocity amplitude with the filtering scale to stop the iterations, and find the smoothing scale of each cell (Vazza et al. 2012). For a better removal of spurious contribution from shock waves, the method has been later combined with a velocity-based shock finder (Vazza et al. 2017).

As a novelty of this work, we apply here instead a more physical definition for the tolerance needed by our iterative algorithm to stop and converge on the local turbulent velocity field. In particular, we modify the multiscale adaptive filtering by Vazza et al. (2012) to include the scale-dependent expected increase in the local rms velocity. In the original work, we applied a fixed tolerance of 1 percent to stop the iterations and find the smoothing scale of each cell. Here instead, we adopt a more physical condition and, based on Kolmogorov's theory, we define a variable tolerance ϵ_w for each iteration from the following equation

$$\epsilon_w = \frac{w^f - (w-1)^f}{w^f}, \quad (4)$$

where w is the size of the smoothing scale in cell's unit and f is the exponent of the Kolmogorov-like relations, which we fix to 0.77 based on our test, as detailed in Appendix A. At the lower smoothing scale, this value is too high and the best choice is the minimum value between ϵ_w and the fixed tolerance used in Vazza et al. (2012). We verified that only for scales smaller than 200 kpc, ϵ is greater than 1 per cent. As discussed in Vazza et al. (2012), we define the turbulent velocity in each cell as

$$\delta v = v - v_{\text{sm}}, \quad (5)$$

where v is the velocity field obtained from simulations and v_{sm} is the velocity field obtained by a 3D spatial filtering around each i-cell, defined as (in the simple 1D case)

$$v_{\text{sm};i} = \frac{1}{w} \sum_{j=i-\frac{w}{2}}^{i+\frac{w}{2}} v_j, \quad (6)$$

where w is the size of the smoothing scale in cell's unit, which determines the number of cells on which v_{sm} is calculated at each iteration step. We compute the relative variation of the turbulent local velocity δv between two successive iterations 'w-1' and 'w' as

$$\delta_w = \frac{\delta v_w^2 - \delta v_{w-1}^2}{\delta v_w^2}. \quad (7)$$

Wherever $\delta_w < \epsilon_w$, we find the value of turbulent velocity and the value of the smoothing scale. We test this procedure with two different exponents for the definition of the tolerance and also with a fixed tolerance as described in Vazza et al. (2012). The distribution of smoothing scales reconstructed by our algorithm is shown in Fig. 3. The reconstruction of the turbulent velocity before the application of other filtering techniques is shown in Fig. 4 for different configurations of the filtering. Both Figs 3 and 4 show that the definitions of tolerance have a minor effect on the distribution of the scales or the reconstruction of the turbulent velocity field. This behaviour is also visible in the radial profile of α , as shown in Fig. 5.

Here, it is clear that variations in the tolerance lead to small effects on the resulting non-thermal pressure. We also tested if this new definition of tolerance could affect the radial behaviour of the smoothing scales. We noticed an increase in the smoothing scale of ≤ 20 per cent from the centre of the cluster to the outskirts, which also results in an average increase of the non-thermal pressure at most by ≤ 30 per cent (e.g. Vazza et al. 2012). However, the radial trend of the turbulent pressure support measured in our data (see the following section) is not an artefact of the filtering procedure: when no filtering is applied, the predicted radial increase of non-thermal support from gas motions in our data (Vazza et al. 2018) as well as in other works (e.g. Nelson et al. 2014a) is much steeper. In the following, we use the variable

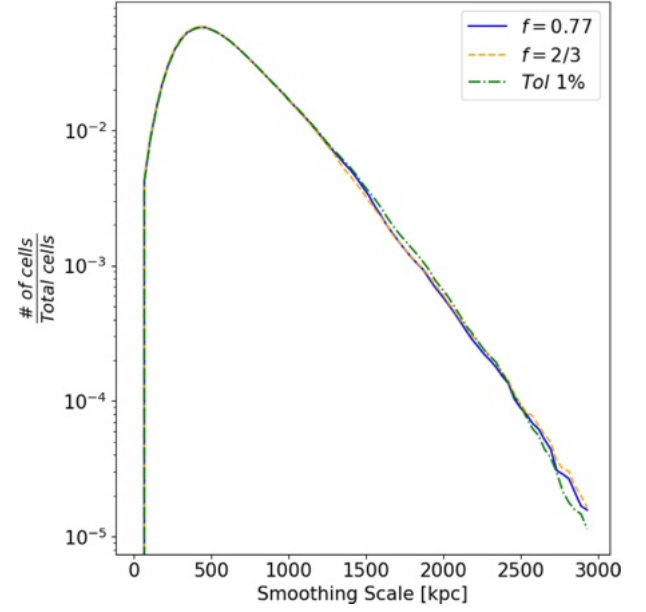


Figure 3. Median distribution of smoothing scales for a subsample of clusters at $z = 0$. The different colours identify different definitions of tolerance, i.e. by varying the exponent for the expected trend of the local rms velocity field as a function of the filtering scale, as explained in Section 2.3.1.

tolerance referred to the $f = 0.77$ case, and combine this with the additional filtering of shocks and gas clumps, to better disentangle turbulent motions from other small-scale hydrodynamical features.

2.3.2 Radial filtering of turbulent motions

Other types of filtering techniques are available in the literature. For the sake of comparison, we also consider the model proposed by Nelson et al. (2014a, hereafter N14) in our data set. The definition of the fraction of the non-thermal pressure support in N14 is

$$\alpha_{\text{Tot}} = \frac{P_{\text{rand}}}{P_{\text{rand}} + P_{\text{therm}}} = \frac{\sigma_{\text{gas}}^2}{\sigma_{\text{gas}}^2 + (3k_b T / \mu m_p)}, \quad (8)$$

where the gas velocity dispersion σ_{gas} within radial shells is estimated as

$$\sigma_{\text{gas}} = \sqrt{\frac{\sigma_r^2 + \sigma_t^2}{3}} \quad (9)$$

with σ_r and σ_t as the radial and the tangential velocity components, respectively. These components are computed as

$$\sigma_i = \sqrt{\langle v_i^2 \rangle - \langle v_i \rangle^2}, \quad (10)$$

where $\langle v_i^2 \rangle$ is the mean-square gas velocity, while $\langle v_i \rangle$ is the mean gas velocity, computed in each radial bin, both in radial and tangential direction. Both mean and mean-square gas velocity are weighted by the mass of each gas cell.

In the remainder of the paper, we will compare our definition of α_{Turb} to the definition of α_{Tot} above, in which the main difference between them stems from the definition of the 'turbulent' velocity. In the N14 model, the turbulent velocity is basically the gas velocity dispersion within radial shells, while we filter out also motions that are coherent on small scales (e.g. bulk flows associated to

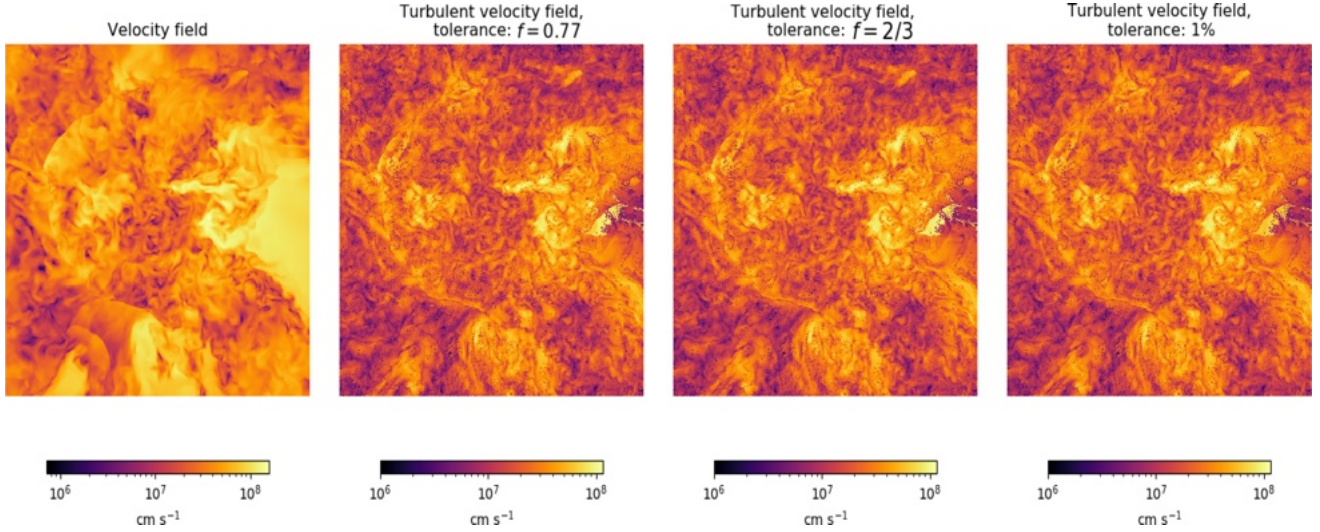


Figure 4. Maps of central slice of IT92.0 at $z = 0$. From left to right: first panel: unfiltered velocity field [cm s^{-1}]; second panel: filtered velocity field for tolerance determined by Kolmogorov relation with 0.77 exponent [cm s^{-1}]; third panel: filtered velocity field for tolerance determined by the standard Kolmogorov relation [cm s^{-1}]; and fourth panel: filtered velocity field for fixed tolerance equal to 1 percent [cm s^{-1}].

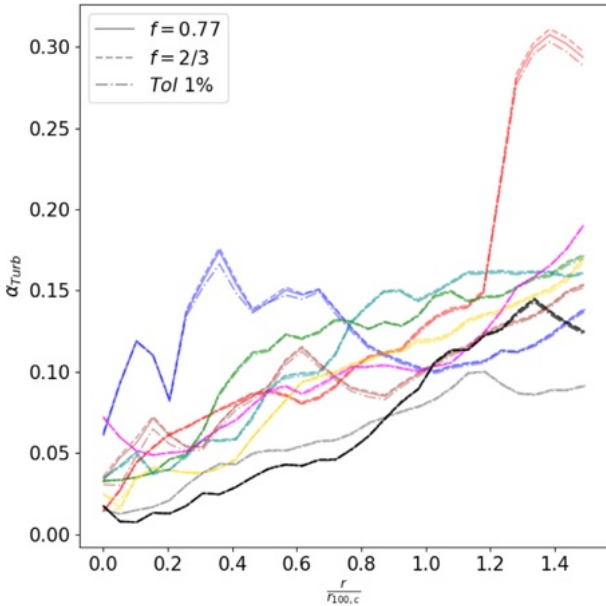


Figure 5. Radial profile of non-thermal pressure support for each cluster at $z = 0$ for different definitions of the tolerance ϵ_w (equation 4) used to stop out iterations on the local turbulent velocity field.

clumps). The differences between these types of definition will be discussed with more details in the following sections (for additional discussion, see also Vazza et al. 2018).

2.3.3 Spurious contributions: shocks and density clumps filtering

Shock identification: In the study of turbulence, shocks can introduce spurious terms in the estimate of turbulent kinetic energy. In the presence of shocks, it is possible to use the Rankine–Hugoniot conditions and use velocity or temperature jumps to determine the Mach number. The Mach number is used to calculate the flux of kinetic energy that is dissipated into gas thermal energy. Here,

we use the shock finding algorithm based on the velocity jump between neighbouring cells (Vazza, Brunetti & Gheller 2009; Vazza et al. 2017, 2018). Detecting shocks with high Mach numbers is relatively easy task in grid simulations with a uniform resolution (and all clusters in the ITASCA sample were simulated with uniform resolution in the ‘zoom’ region), yet the detection of shocks with small Mach numbers is made uncertain by several factors such as numerical errors due to strong gradients or oblique directions of the shocks. In order to reduce the potential noise in the reconstruction of the local turbulent velocity field due to weak shocks sweeping our volume, we set a lower limit to the Mach number of $\mathcal{M}_{\text{thr}} = 1.3$. We refer the reader to Vazza et al. (2017, 2018) for an overview of this shock finding method.

Clump excision: Dense clumps associated with infalling structures can introduce a bias in the estimate of the local velocity field (e.g. Dolag et al. 2005), due to the fact that these structures are correlated with large bulk motions, mostly in the inwards radial direction (e.g. Vazza et al. 2018). These spurious terms could lead to an overestimate of the non-thermal pressure support. Clumps in simulations are routinely identified as peaks with high-density contrast in the radial gas density distribution of the host cluster (e.g. Ruszkowski & Oh 2011; Zhuravleva et al. 2011). Therefore, restricting the analysis to a fraction of the gas density distribution at every radius, obtained after excising the highest percentiles in the gas distribution at each radius, is a practical way to limit the bias from the most *clumpy* structures in the ICM. Hence, we tested three different values for masking the densest cells (considering gas density only) at each radius from the cluster centre: the cells in the top 50 per cent, 25 per cent, or 10 per cent of the gas density distribution at every radius. As shown in Fig. 6, the profile of non-thermal pressure support α_{Turb} we can derive in our clusters at $z = 0$ is overall quite robust against a more restricting selection of cells in the low-density part of the distribution at each radius. On the other hand, when we use the same cells selection to compute the radial profile of α_{Tot} , we notice a larger impact of the gas clumping factor, shown by the increase of non-thermal support when denser cells are retained in the procedure (see Zhuravleva et al. 2013, for a detailed study on the ICM inhomogeneities). This suggests that α_{Tot}

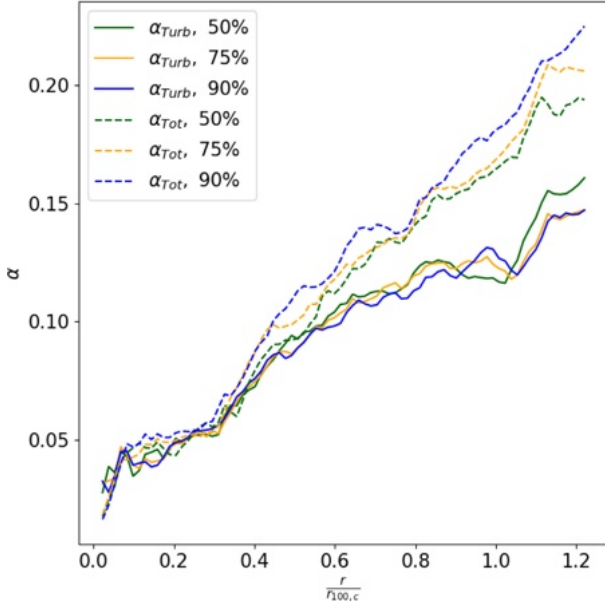


Figure 6. Radial profile of median value of non-thermal pressure support for a subsample of clusters at $z = 0$, obtained by considering the 50 per cent, 75 per cent, or 90 per cent least dense cells at each radial bin from the centre of clusters. The solid lines are the result for α_{Turb} , while the dashed lines are the α_{Tot} ones.

is susceptible to clump expulsions, while α_{Turb} is more stable with respect to the presence of clumps. Based on our results and previous work (e.g. Roncarelli et al. 2013; Zhuravleva et al. 2013), we will use the 90 per cent masking in our analysis, which roughly mimics the approach applied to the X-ray spatial analysis (e.g. Ghirardini et al. 2017; Eckert et al. 2019). Our tests show that adoption of $\mathcal{M} \geq 1.3$ and the exclusion of cells in the top 10 percentile in density in each shell yields the best filtering combination. In the following, we will refer to the results of our best filtering configuration as the turbulent velocity.

3 RESULTS

Our projected maps of gas density, dark matter density, gas temperature and unfiltered velocity field, as well as the turbulent velocity field and shocks for one of the objects in our sample are given in Fig. 7. The maps well illustrate the complex gas flow patterns that are typically found in the simulated clusters at all epochs, with expanding shocks that mark recent heating episodes in the ICM (top and lower right-hand panels) and a mixture of large-scale bulk flows (lower left-hand panel) and small-scale turbulent motions (lower central panel).

To extract the radial profiles of α , we first define the cluster centre based on the maximum value of the thermal energy of the gas at each snapshot since this definition of the centre makes it the most stable, in highly perturbed systems, as well.

We consider mass-weighted values of the pressures, estimated on the same cells selected with our turbulent filtering technique (see Section 2.3.1).

In the following analysis, we consider two methods to estimate the ratio $\alpha = P_{\text{nt}}/P_{\text{tot}}$: (i) either applying our filtering technique (α_{Turb}) or the N14 model (α_{Tot}); (ii) by comparing the mass estimated from the hydrostatic equilibrium equation with the total mass distribution ($\alpha_{\text{HS,Turb}}$ or $\alpha_{\text{HS,Tot}}$). Furthermore, when we refer to α or α_{HS} , we are considering both ‘Turb’ and ‘Tot’ quantities at the same time.

Otherwise, if we consider only one of these quantities, we will indicate it with the related subscript. In Fig. 8, we show values of mass and non-thermal pressure support α_{Turb} at radius $r_{100,c}$ in function of redshift. We notice that there is a strong relation between mergers and an increase of α_{Turb} . Instead, when the cluster is not affected by mergers the value of α_{Turb} decreases. The red points in Fig. 8 are the selected snapshots obtained by the selection described in Section 2.2. In the following, we will refer to the different typical radii $R_{500,c}$, $R_{200,c}$, $R_{100,c}$, and $R_{200,m}$. From the cluster’s centre to the peripheries we find $R_{500,c}:R_{200,c}:R_{100,c}:R_{200,m}$ and they are related by these approximated ratios 1:1.4:1.9:3 (see Walker et al. 2019, and references therein).

3.1 Parametrizing the profile of non-thermal pressure support in galaxy clusters

The radial distribution of non-thermal pressure support we find in our cluster sample is so regular that an analytic formula reproduces well the trend of α_{Turb} with radius

$$\alpha_{\text{Turb}}(r) = a_0 \times \left(\frac{r}{r_{200,m}} \right)^{a_1} + a_2. \quad (11)$$

The physical meaning of our parameters is straightforward: a_0 represents the normalization of α_{Turb} at $r_{200,m}$, a_1 gives the slope of the profile, and a_2 gives the value of non-thermal support in the cluster centre. We notice that Shi & Komatsu (2014) develop an analytic model to describe the trend of α_{Turb} with the radius. They use three fundamental time-scales to develop their model: turbulence dissipation time-scale, t_d ; the time elapsed between the initial time and the time of observation, $(t_{\text{obs}} - t_i)$, which characterizes the age of the cluster; and a time-scale characterizing the mass growth rate of the cluster defined by t_{growth} . They define also a turbulence injection efficiency η , which they constrain to be $\eta \approx 0.5 - 1$ based on simulations. However, the turbulence injection efficiency is strongly correlated with the slope of the fitting formula, and compared to Shi & Komatsu (2014) we report a lower injection efficiency, which may also be connected to the role of numerical dissipation of our hydro scheme on small scales. We also notice that in real systems, and especially at low mass, the turbulence in the core may be dominated by the interplay of cooling and feedback (e.g. Brighenti & Mathews 2002; Brüggen 2003; Gaspari et al. 2018); hence, our a_2 may be underestimated. However, we notice that, although our simulations do not include feedback mechanism or cooling, our estimate for a_2 is close to the only available direct spectral measurement from the *Hitomi* (Hitomi Collaboration et al. 2016).

Nelson et al. (2014a) present the following analytical fit to the radial distribution of the non-thermal pressure in a data set of 65 simulated galaxy clusters with masses in a range similar to ours

$$\frac{P_{\text{rand}}}{P_{\text{tot}}}(r) = 1 - A \left\{ 1 + \exp \left[- \left(\frac{r}{r_{200,m}} \right)^\gamma \right] \right\}, \quad (12)$$

with best-fitting values $A = 0.452 \pm 0.001$, $B = 0.841 \pm 0.008$, and $\gamma = 1.628 \pm 0.019$. This fit formula is based on 3D gas velocity fields without explicitly filtering out bulk motions (for details, see Section 2.3.2). The same function also fits our data after filtering, albeit with a slightly higher χ^2 value (see Table 1). In Fig. 9, we show the different fits overplotted to the median radial profiles of our objects.

From the comparison of the χ^2 , it appears that our model yields a better fit to the data than, or as good as, the model in N14. The fit suggested by N14 can also fit our data, albeit with different parameters. However, the advantage of our best-fitting form is that the fit parameters have a simple physical meaning.

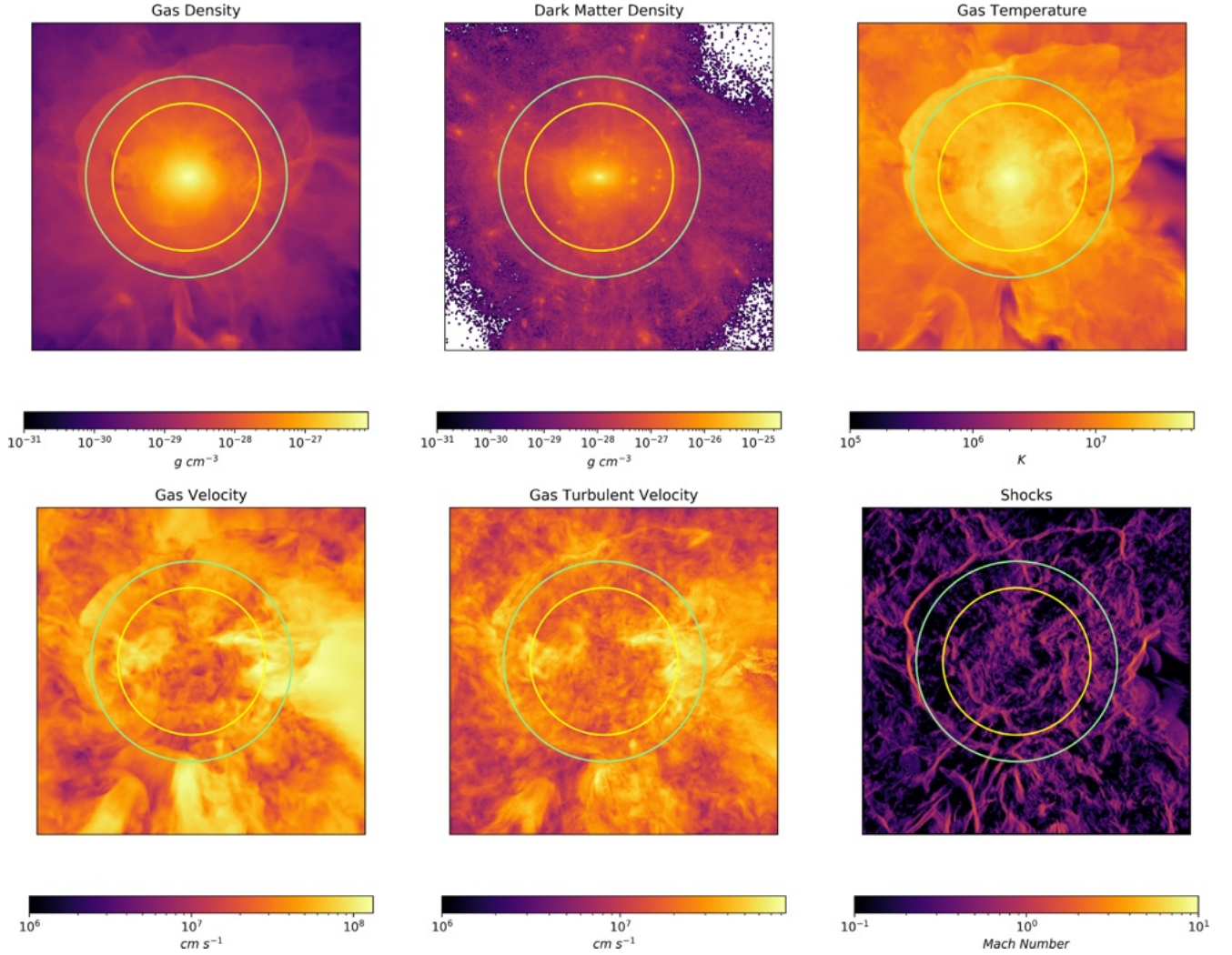


Figure 7. Maps of the central region in IT92.0 at $z = 0$. The inner circle is $r_{200,c}$, while the outer one is $r_{100,c}$. From top left to bottom right: first panel: gas density [g cm^{-3}]; second panel: dark matter density [g cm^{-3}]; third panel: gas temperature [K]; fourth panel: unfiltered velocity field [cm s^{-1}]; fifth panel: turbulent velocity field [cm s^{-1}]; and sixth panel: shock Mach number.

As we discussed already in Vazza et al. (2018), the differences between our results and those of N14 stem from the different choices in filtering velocities, and the two methods yield formally the same result if no filtering is applied to the 3D velocity field in our simulations. However, our work suggests that our filtering yields the isotropic part of the turbulent pressure, while filtering out the spurious contribution to the non-thermal pressure support by inward radial motions.

We apply our model also to the profile of α_{Tot} and compare the results with the fit obtained by N14 model. The results are shown in Fig. 9 and Table 1. We notice that our model can reproduce also the α_{Tot} trend. From the comparison of χ^2 we can notice that, as for α_{Turb} case, our model is slightly preferred over the N14 model.

We investigated the possible correlations between the non-thermal pressure and mass, redshift, and sparsity of each cluster in our sample. The Sparsity is defined as the ratio between the total mass within $r_{100,c}$ and $r_{200,c}$

$$s = \frac{M_{100,c}}{M_{200,c}}. \quad (13)$$

For all of these quantities, we divided our samples into three subsamples that contain the same number of objects. The results are discussed in Appendix B. Here, we just note that our model reproduces the radial behaviours of α for all subselections of our sample. The same best-fitting parameters are valid for all subsamples, suggesting that no strong dependencies between the non-thermal to total pressure ratio and the cluster mass, the redshift or the mass sparsity can be detected in our sample.

Recently, Eckert et al. (2019) present some constraints on the non-thermal pressure support in a sample of 12 massive, nearby and mostly relaxed clusters observed in X-rays with *XMM-Newton* and in Sunyaev–Zel’dovich (SZ) with *Planck*. They compare the values of the hydrostatic mass, recovered up to $r_{200,c}$ by using a combination of the SZ pressure profile and X-ray based thermodynamical properties (for details, see Ettori et al. 2019), with mass estimates based on the assumption that hydrodynamical simulations provide the correct baryon fraction distribution in clusters. In the latter estimate, the gas mass is inferred directly from X-ray measurements and the contribution of the mass in stars is evaluated statistically from published work. From the mismatch between the two estimates of the total mass, it is then possible to infer the hydrostatic bias,

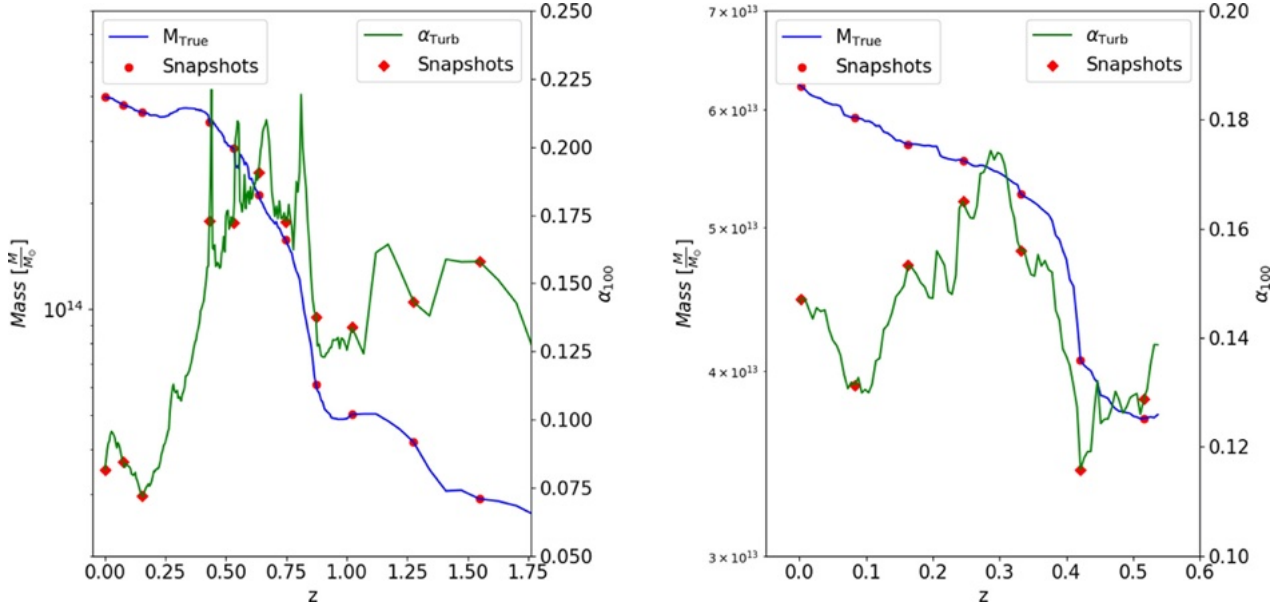


Figure 8. $M_{100,c}$ growth (blue solid line) and non-thermal pressure support at $r_{100,c}$ time behaviour (green solid line) for IT92.0 and IT90.4. The red points are the selected snapshots as explained in Section 2.2.

Table 1. Parameters and values of χ^2 statistical test for the different formula used to fit the radial behaviour of α_{Turb} and α_{Tot} . We show also the values of the parameters presented in N14. The errors on the parameters are the values at 3σ confidence.

	Our model			
	a_0	a_1	a_2	χ^2
α_{Turb}	$(1.427 \pm 0.002) * 10^{-1}$	1.246 ± 0.005	$(8.44 \pm 0.02) * 10^{-2}$	10^{-4}
α_{Tot}	$(3.388 \pm 0.009) * 10^{-1}$	0.822 ± 0.004	$(6.97 \pm 0.08) * 10^{-2}$	0.001
	N14 model			
	A	B	γ	χ^2
α_{Turb}	$(4.550 \pm 0.003) * 10^{-1}$	1.966 ± 0.004	1.508 ± 0.005	$2 * 10^{-4}$
α_{Tot}	$(4.483 \pm 0.003) * 10^{-1}$	0.865 ± 0.002	1.633 ± 0.006	0.046
N14	0.45	0.84	1.63	

which turns out to be, on average, consistent with the results obtained by other methods (see Ettori et al. 2019).

If we attribute the origin of this hydrostatic bias to the contribution from a non-thermal pressure component, $P_{\text{nt}}(r)$, we can write (e.g. Eckert et al. 2019)

$$\frac{d}{dr}(P_{\text{th}}(r) + P_{\text{nt}}(r)) = -\rho \frac{GM_{\text{T}}(< r)}{r^2}, \quad (14)$$

where P_{th} is the thermal pressure component, and M_{T} is the total mass. By defining $\alpha(r) = P_{\text{nt}}(r)/P_{\text{tot}}(r) = P_{\text{nt}}(r)/[P_{\text{nt}}(r) + P_{\text{th}}(r)]$, the equation above can be rewritten as

$$M_{\text{T}}(< r) = M_{\text{H}}(< r) + \alpha(r)M_{\text{T}}(< r) - \frac{P_{\text{th}}r^2}{(1 - \alpha)\rho G} \frac{d\alpha}{dr}, \quad (15)$$

where M_{H} is the hydrostatic mass

$$M_{\text{H}}(i) = -\frac{\left(\frac{dP_{\text{th}}}{dr}\right)_i r_i^2}{G\rho_{i-1}}. \quad (16)$$

From the equations above and using our radial profiles of total mass and hydrostatic mass, we can then define α_{HS} at each radius r as

$$\alpha_{\text{HS}} = 1 - \frac{M_{\text{H}} + \sqrt{(M_{\text{H}})^2 - 4M_{\text{T}}P_{\text{th}}\frac{r^2}{\rho G}\frac{d\alpha}{dr}}}{2M_{\text{T}}}, \quad (17)$$

and link it to the parameter b , which is usually used in literature to identify the hydrostatic mass bias (e.g. Pratt et al. 2019; Salvati et al. 2019) and defined as

$$M_{\text{H}} = (1 - b)M_{\text{T}}, \quad (18)$$

to obtain

$$b = \frac{\alpha + A}{1 + A}, \quad (19)$$

where A encloses the pressure's contributions

$$A = (P_{\text{th}} + P_{\text{nt}}) \frac{d\alpha/dr}{dP_{\text{th}}/dr}. \quad (20)$$

We notice that if α is radially constant, then $b = \alpha$. However, α is not generally constant with radius in our sample (see Fig. 9). Hence, the $d\alpha/dr$ term plays a small but non-negligible role here.

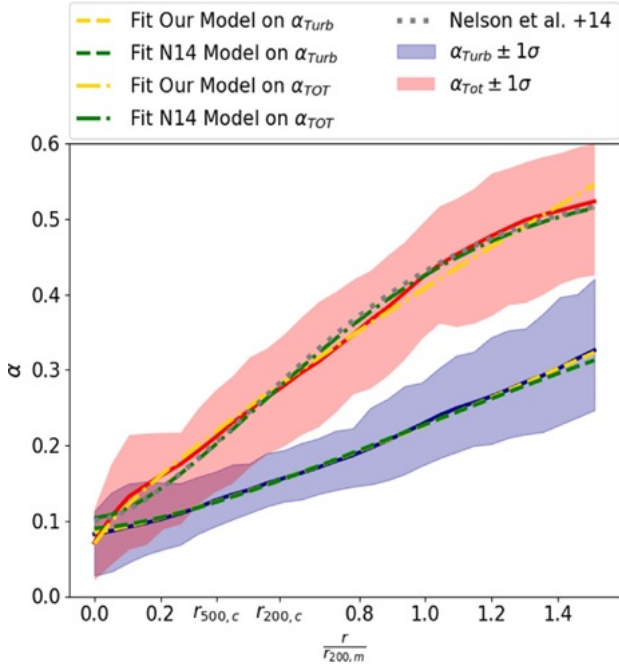


Figure 9. Radial profile of median value of α_{Turb} (blue solid line) and α_{Tot} (red solid line). The shadow regions represent the 1σ distribution of the sample. The yellow and green dashed lines are the best fits of our model and N14's one on α_{Turb} profile, while the dash-dotted ones are the fits of the models on the α_{Tot} profile. The dotted grey line is the profile obtained in N14.

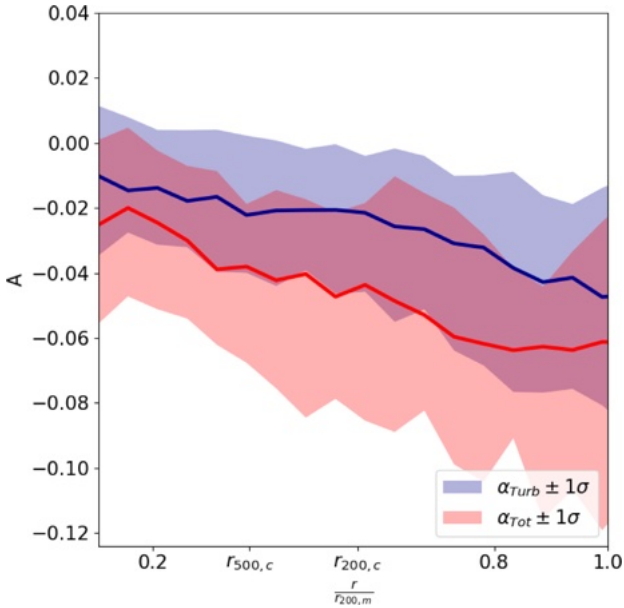


Figure 10. Radial profiles of A pressure correction term of equation (19). In blue solid line, the profile is computed with the radial derivative of α_{Turb} , while in red solid line the profile is computed with the α_{Tot} . The shadow regions represent the 1σ distribution of the data.

As described below, we use both α_{Turb} and α_{Tot} profiles to estimate da/dr and propagate it to the measurement of α_{HS} . We show in Fig. 10 the radial profile of the term A , where the different effect of the radial derivative of α allows us to distinguish between the ‘Turb’ and ‘Tot’ cases.

We compute the hydrostatic mass M_{H} through the radial derivative of thermal pressure associated with a spectroscopic-like temperature profile, and computed as follows²

$$\left(\frac{dP_{\text{th}}}{dr}\right)_i = \frac{P_{\text{th},i-2} - 6P_{\text{th},i-1} + 3P_{\text{th},i} + 2P_{\text{th},i+1}}{6r_i}, \quad (21)$$

where P_{th} is the thermal pressure defined as in equation (2) and i represents each radial shell. To limit the contribution from dense, self-gravitating clumps, we use the same masking procedure of Section 2.3.1, in order to consider only the thermal pressure exerted by the gas within the cluster. We also applied a box-averaged smoothing function along 10 radial shells at density, thermal pressure, and α_{Turb} or α_{Tot} profiles, in order to reduce numerical fluctuations in the profiles. This procedure allows us to obtain smoothing profiles that are more similar to the typical profiles obtained in observational works and are also less affected by spurious numerical effects.

For each radius, we computed the value of α_{HS} by applying equation (17). The radial derivative of α allows us to define two different α_{HS} , already presented above, $\alpha_{\text{HS,Turb}}$ and $\alpha_{\text{HS,Tot}}$. To check the dependencies of α_{HS} on physical quantities such as mass, redshift, and mass sparsity of clusters, we used the subsamples analysis presented in Appendix B. We notice that the variance of the α_{HS} data is larger with respect to the α ones. As for α profiles, also for α_{HS} ones we could not identify any strong correlation with the physical properties of host clusters.

Several factors may influence the comparison between observational results and numerical ones. To test different choices to compute radial profiles of thermodynamical quantities, in a way similar to what is commonly feasible with observations, we built both a volume-weighted version of α_{HS} , and one using the ‘spectroscopic-like’ temperature suggested by Mazzotta et al. (2004) (hereafter *MZ04*), which approximately takes into account the real spectroscopic response of X-ray detectors in determining the average gas temperature in the ICM. The results are shown in Fig. 11.

We notice that there are no strong differences between the volume-weighted pressure profile and the pressure profile based on the spectroscopic-like temperature. This is consistent with the finding that the hydrostatic mass bias is relatively small in AMR grid-based simulations, while the temperature bias could be large in SPH simulations, owing to the enhanced formation of substructures there (Rasia et al. 2014). We also notice how our definition of turbulent motions is more in agreement with the radial trend of α_{HS} , mostly in the inner regions that are more accessible to the present X-rays observations. Instead, the α_{Tot} is larger than α_{HS} at any radius. In the following sections, we will use the α_{HS} parameter to easily compare our results to the ones in Eckert et al. (2019), as shown in the plots (black points with errorbars).

Similarly to Vazza et al. (2018), but extended in the present study to the full set of simulated clusters, the scatter in the simulations is typically larger than the one observed in real cluster data, with the

²We tested this procedure in idealized (semi-analytically generated) control atmospheres and we verified that our approach is robust to recover the correct mass bias (within a few ~ 0.01 per cent) for the typical pressure profile of ICM. Furthermore, we also tested that smoothing our data on scales larger than our spatial resolution (19.6 kpc/cell), in order to mimic what can be realistically done by X-ray observations, *worsens* the match between the hydrostatic mass and the total mass, especially in 3D simulated clusters as the smoothing accuracy with which the internal substructures orbiting in the cluster potential well can be modelled.

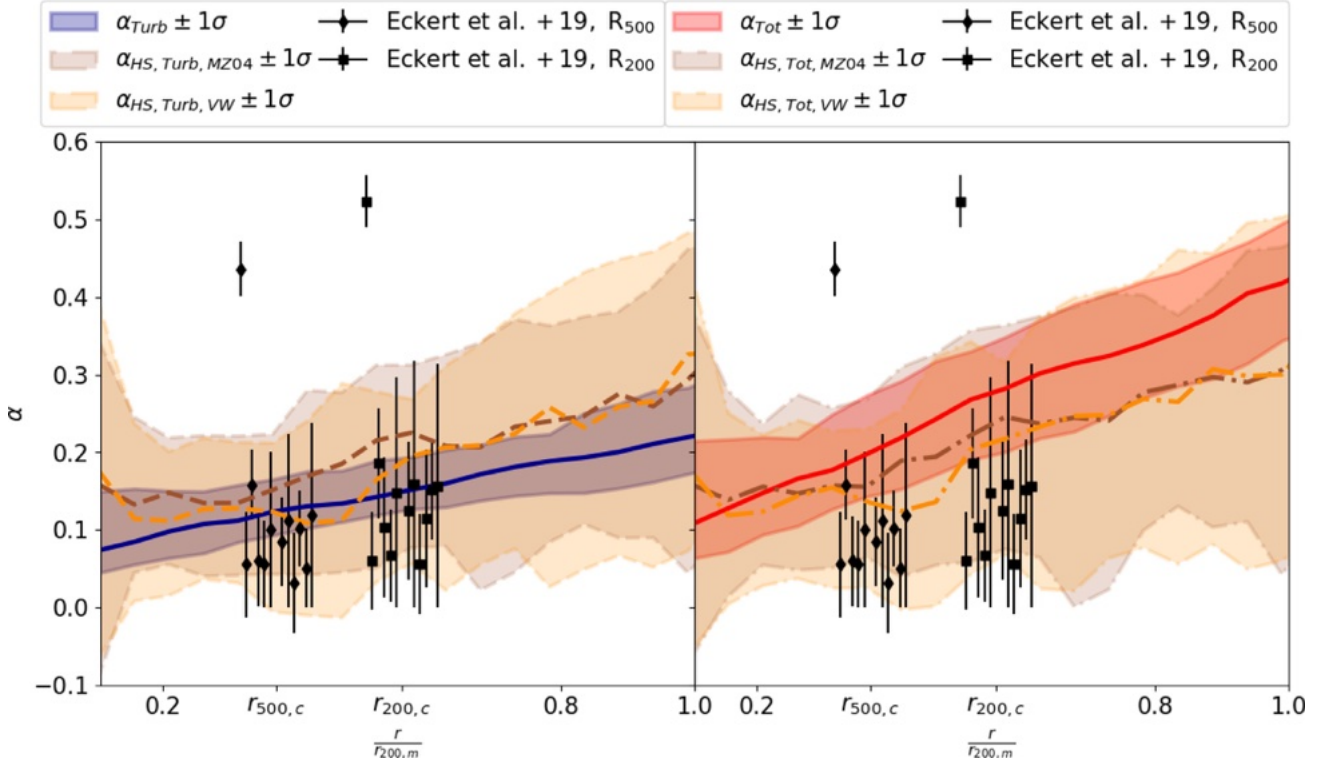


Figure 11. On the left-hand panel, we show the comparison between α_{Turb} (blue solid line) and $\alpha_{\text{HS,Turb}}$ computed with volume-weighted profile (orange dashed line) and with the spectroscopic-like temperature (brown dashed line). On the right-hand panel (with the same colour-coded legend of the left-hand panel), the result for α_{Tot} against $\alpha_{\text{HS,Tot}}$ is shown. The shadowed regions give the 1σ distribution of the sample for all the profiles. The black points represent the results of Eckert et al. (2019).

exception of A2319 (Ghirardini et al. 2018), which probably comes from the intrinsic difference in the two samples: the X-COP sample contains by selection mostly relaxed clusters, while our sample contains a larger variety of objects. We will further comment on this issue in Section 5. Despite this promising average agreement between these two samples, in the next section we investigate the caveats that may lead to a mismatch between observational estimates of α_{HS} and the underlying presence of turbulent motions in single objects.

It shall be noticed that all approaches are in better agreement in the centre of clusters, although the scatter is large for the distribution of α_{HS} . Interestingly, the central median values of α_{Turb} and α_{Tot} for the sample are in the 5–8 per cent range, which is reasonably close to the most recent estimates from the centre of the Perseus cluster, i.e. ~ 2 –6 per cent (Hitomi Collaboration et al. 2018). This trend is well explained by Lau et al. (2017) and Bourne & Sijacki (2017).

3.2 On the relation between turbulence and hydrostatic bias

To investigate the relation between turbulence and hydrostatic bias in a more systematic way, we compare the radial dependence of α and α_{HS} . We consider the median values of entire sample of α and α_{HS} in each radial shell. The results are shown in left-hand panel of Fig. 12.

If turbulence and hydrostatic bias were perfectly correlated, the data would closely follow the bisector of the plot. Instead, we find that their relation is well described by a function $\alpha_{\text{HS}} = a_0 \times (\alpha/0.2)^{a_1} + a_2$ (see Fig. 12). This suggests that in general both our definition of turbulence and the N14 model do not trace in a 1-to-1 relation the hydrostatic bias. From Fig. 12, it also appears

that the N14 definition of turbulence is much closer to the 1-to-1 relation between turbulence and hydrostatic bias. Considering that the N14 model includes not only turbulent motions but also the kinetic pressure associated to bulk motions, we conclude that the latter one represents an important ingredient for the mass bias, especially when large values of α_{HS} are considered (which happens most often at larger radii).

We divide further our sample in two mass, redshift or sparsity subsamples (see right-hand panel of Fig. 12). We observe that, as opposed to the analysis of the complete sample, α_{Tot} is able to reproduce the 1-to-1 relation with $\alpha_{\text{HS,Tot}}$ in some subsamples. This confirms that α_{Tot} is a more accurate tracer of hydrostatic bias compared to our definition of α_{Turb} . This is supported by the plot in Fig. 13 where we show the ratio between α_{Turb} and α_{Tot} against α_{HS} (here we used $\alpha_{\text{HS,Turb}}$ but the results are almost the same for the $\alpha_{\text{HS,Tot}}$ case). Combining the information from Figs 12 and 13, we notice that our definition of turbulent motions gives a value of α that is always a fraction of the value obtained from the N14 filtering technique, ~ 50 –70 per cent from case to case. From Fig. 13, we also notice that the less the hydrostatic bias, greater is the support from purely turbulent motions to non-thermal pressure. Indeed, the higher the α_{HS} , the lower is the ratio α_{Turb} against α_{Tot} . This ratio has also a dependence with distance from the cluster’s core. Indeed, greater is the radius and lower is the ratio. Therefore, the role of the turbulent motions in the non-thermal pressure support is less important in cluster outskirts than in the innermost regions. We made also a subsample analysis of these relations and the results are shown in the right-hand panel of Fig. 13. We notice that for all the subsamples the above conclusions still hold. In case of low-mass or high-redshift clusters, we also notice

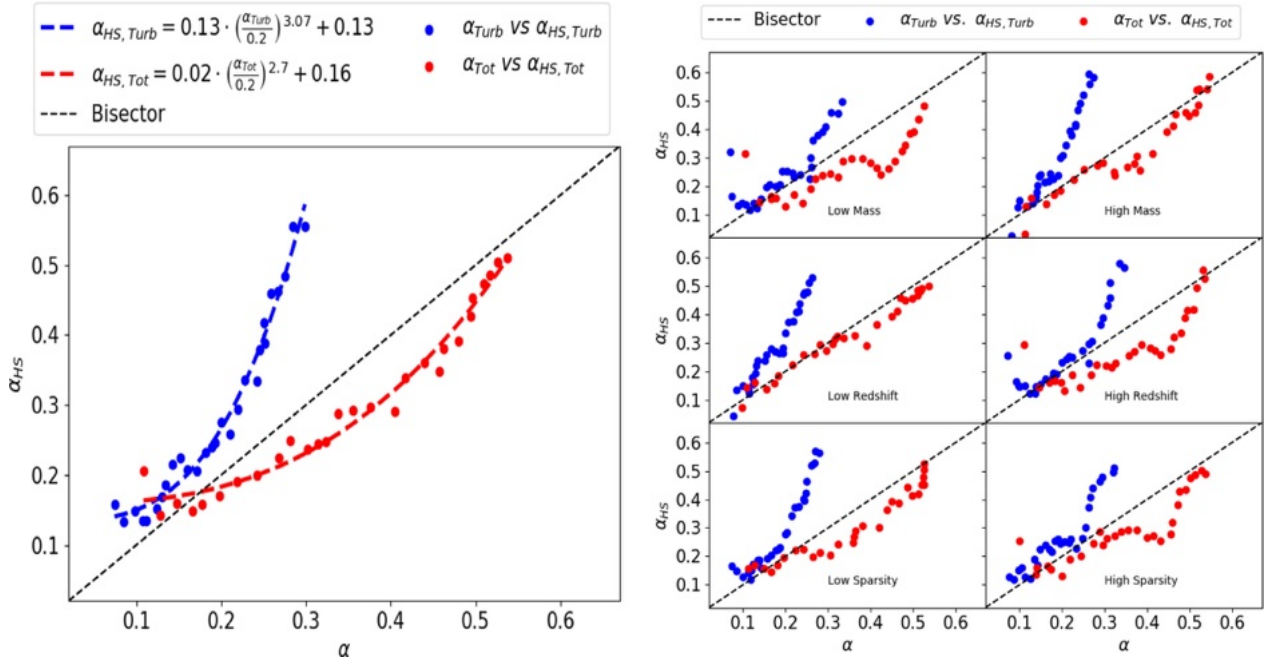


Figure 12. Relation between α and α_{HS} computed as described in Section 3.2. In the left side, the whole sample, while in the right side the blue points are obtained from α_{Turb} and $\alpha_{\text{HS,Turb}}$, and the red ones are obtained from α_{Tot} and $\alpha_{\text{HS,Tot}}$. The dashed lines are the fits made as described in Section 3.2, where the coefficients are given in the legend. The black dashed line is the bisector. In the right-hand panel there are six subsamples, as described in Section 3.2. Top panels: low mass on the left, high mass on the right; central panels: low redshift on the left, high redshift on the right; bottom panels: low sparsity on the left, high sparsity on the right. Also in these plots the blue points represent the ‘Turb’ quantities, while the red dots represent the ‘Tot’ ones. The dashed lines are the plots’ bisectors.

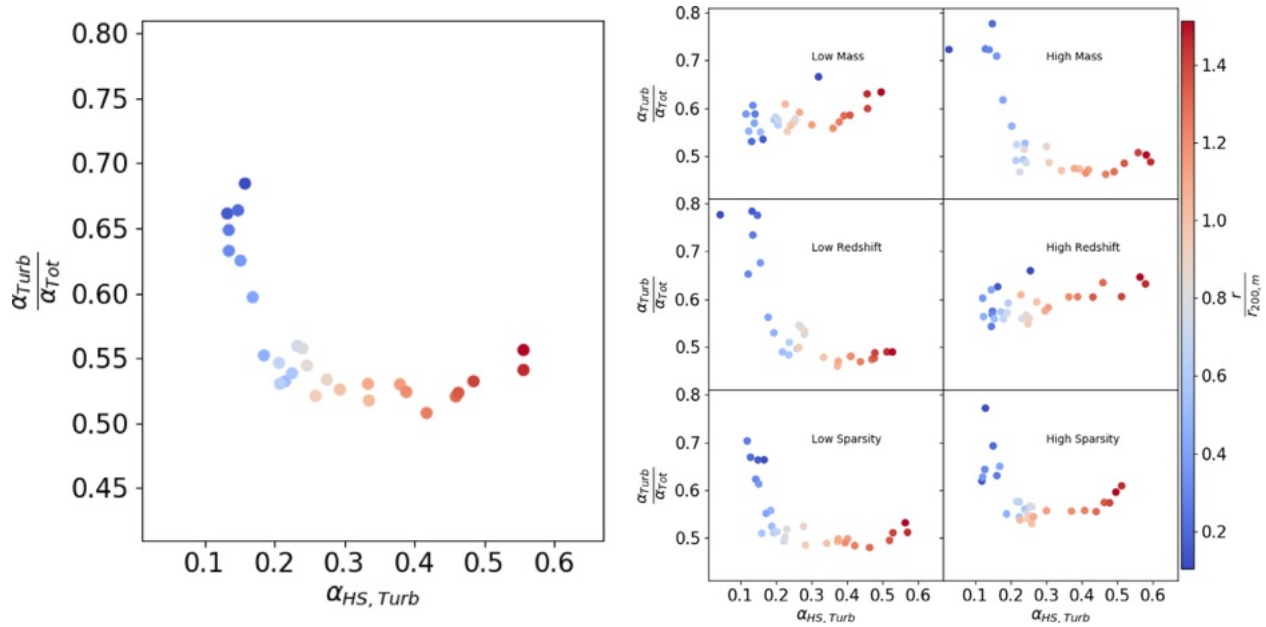


Figure 13. Relation between the ratio $\alpha_{\text{Turb}}/\alpha_{\text{Tot}}$ and $\alpha_{\text{HS,Turb}}$. In the left side, the whole sample, while in the right side there are six subsamples, as described in Section 3.2. Top panels: low mass on the left, high mass on the right; central panels: low redshift on the left, high redshift on the right; bottom panels: low sparsity on the left, high sparsity on the right. The colours represent the distance from the cluster’s centre.

that the ratio α_{Turb} against α_{Tot} is almost constant with the hydrostatic bias.

We conclude that the relation between turbulence and hydrostatic bias can be statistically detected only with a typical number of ≥ 20

objects, at least in the mass range probed by our sample. On the other hand, when applied to single objects the analysis presented above appears not suitable to give accurate correction factors for the hydrostatic bias, as we will show in the next section.

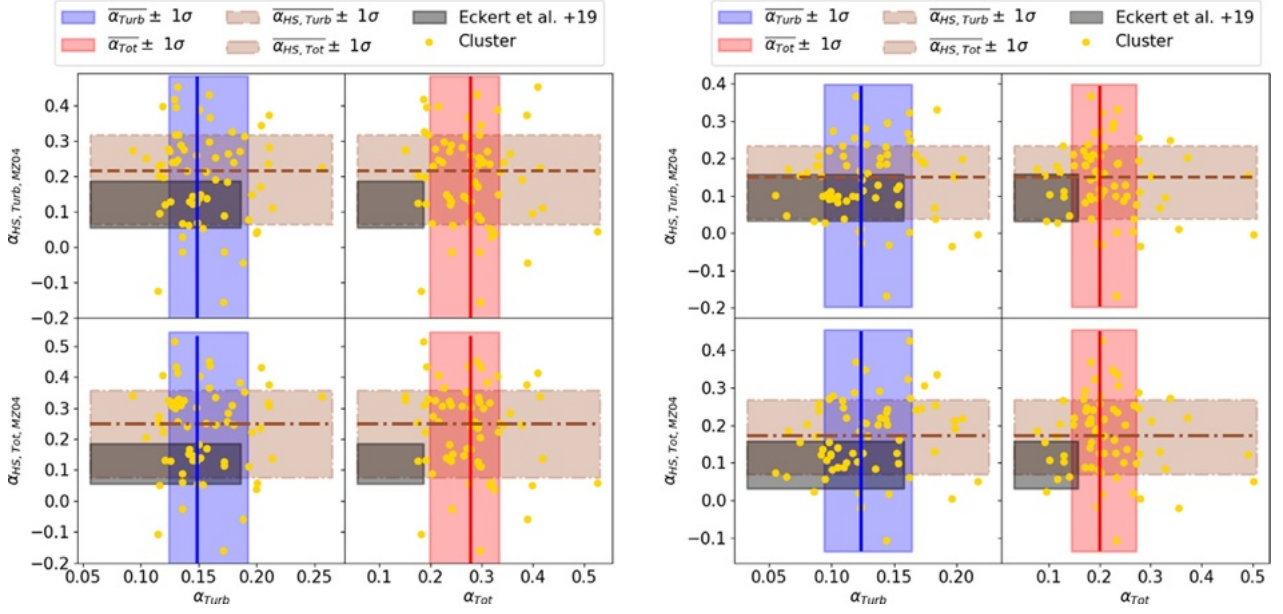


Figure 14. Comparison between median α_{Turb} (blue solid line) or α_{Tot} (red solid line) and $\alpha_{\text{HS,Turb}}$ (brown dashed line) or $\alpha_{\text{HS,Tot}}$ (brown dash-dotted lines) at $r_{200,c}$ (left-hand panels) and $r_{500,c}$ (right-hand panels). The shadowed regions represented 1σ variance. The black shadowed regions represented the range values presented by Eckert et al. (2019), while the yellow dots refer to singles clusters (we notice that one cluster of the sample is found to be well outside the plot limits and is discarded given its very peculiar shape).

4 DISCUSSION

We can finally study the relation between the non-thermal pressure, the turbulence we identify in our data, and the X-ray derived proxy (e.g. Eckert et al. 2019). To address this, we compute the values of α_{HS} and α at the radii $r_{200,c}$ and $r_{500,c}$ in each object. The results are shown in Fig. 14.

At first glance, there are almost no correlations between the two proxies (α and α_{HS}) for the non-thermal pressure support, even if the two distributions span a similar range of values, and also they are in the same ballpark of the X-COP results discussed in Eckert et al. (2019). We also notice that while α is defined as a positive quantity by construction, α_{HS} can be measured with negative values (in ~ 10 per cent of the sample) due to local fluctuations in the reconstructed thermodynamical profiles that are responsible for the scatter in the distribution of the estimated α_{HS} at a given radius. This introduces crucial problems for the α_{HS} estimate. First, the spherical symmetry and the coincidence between the centre of the gas pressure and of the gravitational mass (and between gas and dark matter densities) are often violated for systems that had only a little time to relax. Gas substructures are also more prominent, as they are often found in their first crossing of the ICM. This also leads to an ICM with a multiphase structure, also correlated with the crossing of shocks. In summary, most of the assumptions on which the hydrostatic equilibrium analysis is based are violated at high- z , while on the other hand the above factors affect little our estimate of α , because through our filtering procedure the measure of turbulence is local and does not rely in assumptions of symmetry or isothermality. Interestingly, the above problems should also play an important role for the mass modelling of high- z galaxy clusters in radial observations (e.g. Maughan et al. 2006; Jee et al. 2011; Schrabback et al. 2018).

To further investigate the physical origin of the deviations from hydrostatic equilibrium, we added a few important dynamical prox-

ies to characterize the dynamics of our systems. More specifically, we computed the radial profile of gas acceleration, and derived the residual acceleration from gas motions that are out of equilibrium in the presence of mergers, following Biffi et al. (2016). While Biffi et al. (2016) could directly access the acceleration values of single SPH particles from the hydrodynamical solver, we rely on the post-processing of Eulerian data, taking the derivative of two close time-steps. We defined the gravitational acceleration in each radial shell as

$$g(r) = -\frac{GM_T}{r^2}, \quad (22)$$

while the residual gas acceleration is computed by first taking the radial velocity in each cell, and then reconstructing the radial profile of this quantity for every selected snapshot. To define the residual gas acceleration in the radial direction, we take the difference in each radial shell, between two snapshots, $\delta(r)$ as

$$\delta(r) = \frac{Vr(t_2) - Vr(t_1)}{(t_2 - t_1)}. \quad (23)$$

In order to follow a convention consistent with Biffi et al. (2016), we defined an acceleration term consistent with the one extracted from their SPH simulations

$$H(r) = g(r) + \delta(r). \quad (24)$$

From the above we can thus introduce a factor, δ_{HE} , which compensates for the residual gas radial acceleration by motions that are not in equilibrium with the gravitational pull of the cluster

$$\delta_{\text{HE}}(r) = \frac{g(r)}{H(r)} - 1. \quad (25)$$

From this definition we notice that when the gas is in hydrostatic equilibrium δ_{HE} is equal to 0. Finally, as in Biffi et al. (2016), we define ξ_r

$$\xi_r = |\alpha_{\text{HS}}(r) - \delta_{\text{HE}}(r)|, \quad (26)$$

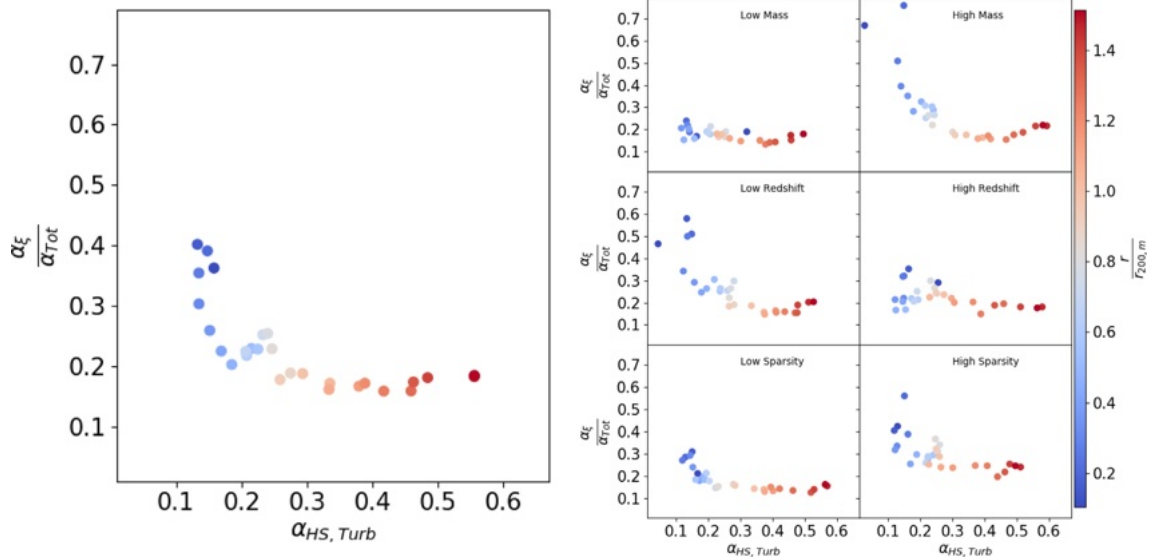


Figure 15. Relation between the ratio α_ξ against α_{Tot} and $\alpha_{\text{HS, Turb}}$. In the left side, the whole sample, while in the right side there are six subsamples, as described in Section 3.2. Top panels: low mass on the left, high mass on the right; central panels: low redshift on the left, high redshift on the right; bottom panels: low sparsity on the left, high sparsity on the right. The colours represent the distance from the cluster's centre.

which allows us to consider at the same time the contributions given at the hydrostatic bias from the acceleration terms and the term obtained from α_{HS} . In Appendix C, we show in more detail how this procedure can well highlight the presence of out-of-equilibrium conditions in the ICM; in particular we can relate large residual acceleration terms to the local gas conditions in the proximity of powerful shock waves crossing the cluster (see Figs C1 and C2). We can thus conclude that these terms are likely to be crucial for an accurate estimate of hydrostatic mass, but also that they are hard to model for a perfect correction of the hydrostatic mass bias, in most realistic cases.

We attempted to incorporate residual gas accelerations in the previous modelling of the hydrostatic bias, by defining α_ξ as the fraction of the total pressure due to purely radial accelerations

$$\alpha_\xi(r) = |\overline{\delta_{\text{HE}}(< r)}|, \quad (27)$$

where $\overline{\delta_{\text{HE}}}$ is defined starting from equation (25) and it represents the median value of the contributions of residual radial accelerations within the radius r . In Fig. 15 we show the behaviour of the ratio $\alpha_\xi/\alpha_{\text{Tot}}$ against α_{HS} .

From the left-hand panel of Fig. 15, we notice that the contribution of radial accelerations to the non-thermal pressure support spans from ~ 40 per cent in the innermost regions of the cluster to ~ 15 per cent in the outskirts. Two effects are likely at play here. First, strong acceleration terms originate from expanding shocks, which are typically launched during mergers starting from the core cluster region (or close to it). Therefore, when a cluster is disturbed by ongoing merger activity, such terms can be more significant in the core regions than in more external ones, due to their larger volume-filling fraction there. Additionally, we expect an irreducible level of spurious radial acceleration at the scale of cluster cores, due the fact that in perturbed systems (i.e. with many substructures in the core etc.) it is not always trivial to exactly track the position of the centre as a function of time, which may introduce noise in our procedure to measure $\delta_{\text{HE}}(< r)$ above.

As for the turbulent contributions, which are discussed in Section 3.2, also for the radial accelerations one, the higher the hydrostatic bias the lower is the contribution. The subsample analysis revealed that for high masses and low-redshift samples, in the innermost regions of the clusters where the hydrostatic bias is lower, the contribution of radial accelerations seems to be higher than for low masses and high redshifts.

Combining the contribution from turbulence and radial accelerations, we obtained the results shown in Fig. 16. In the cluster outskirts, where the hydrostatic bias is higher, turbulence and radial accelerations are not able to completely trace the hydrostatic bias. Due to the filtering techniques, the residual 30 per cent of the hydrostatic bias is generated by the bulk motions, which are filtered out from our filtering technique, but they are considered in the filter proposed by N14. However, in the innermost regions the hydrostatic bias is completely described by the combination of turbulence and the contribution of radial accelerations.

We performed the same subsample analysis used above. For low masses and high-redshift clusters, the combination of turbulence and radial accelerations is still not enough to account for the hydrostatic bias. On the other hand, for high masses, low-redshift, or low-sparsity objects, where the hydrostatic bias is lower, turbulence and radial accelerations trace the hydrostatic bias. However, even then, turbulence and radial accelerations are still not sufficient to explain the hydrostatic bias.

5 CONCLUSIONS

The hydrostatic bias plays an important role in limiting the use of galaxy clusters as cosmological probes (e.g. Pratt et al. 2019; Salvati et al. 2019, and references therein for recent reviews). Using a recent sample of 68 galaxy clusters simulated at high resolution with the cosmological code ENZO (Vazza et al. 2017, 2018; Wittor et al. 2017), we have shown that cosmological simulations combined with a sophisticated filtering of turbulent motions can in principle predict the same value of the hydrostatic mass bias inferred from the

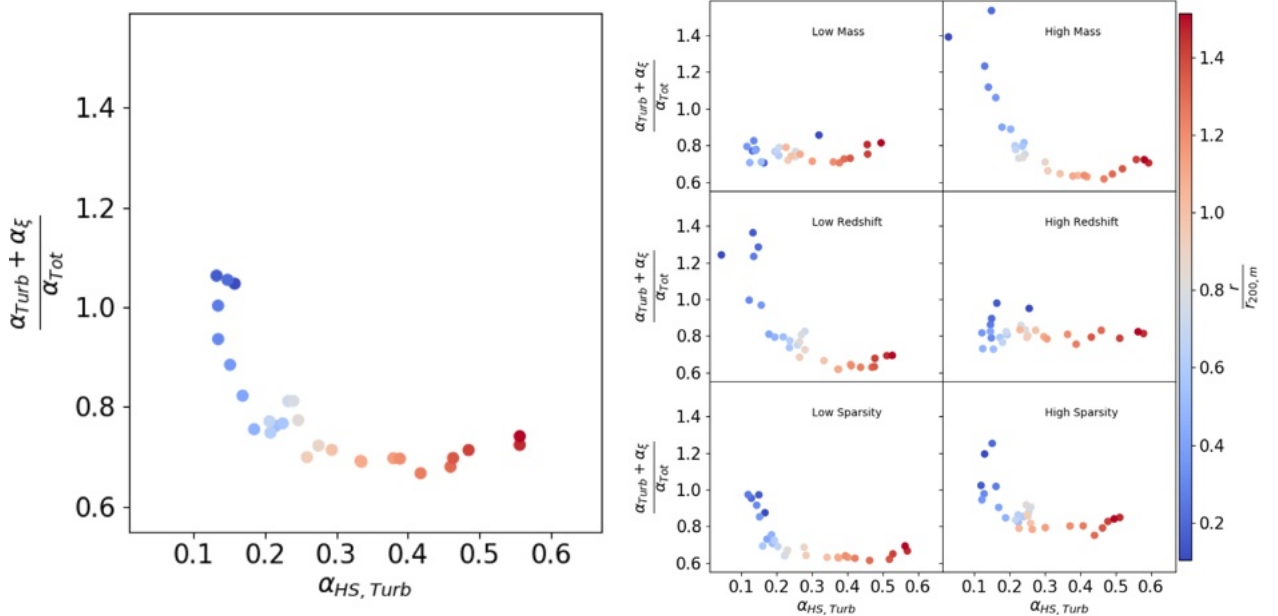


Figure 16. Relation between the ratio $\alpha_{\text{Turb}} + \alpha_{\xi}$ against α_{Tot} and $\alpha_{\text{HS, Turb}}$. In the left side, the whole sample, while in the right side there are six subsamples, as described in Section 3.2. Top panels: low mass on the left, high mass on the right; central panels: low redshift on the left, high redshift on the right; bottom panels: low sparsity on the left, high sparsity on the right. The colours represent the distance from the cluster’s centre.

combination of X-ray and SZ observations (e.g. Eckert et al. 2019), relying on the simplistic hydrodynamical view of the inviscid ICM.

This work improves on our previous works on the subject in several respects. First, we designed a procedure to extract a larger sample of objects and conduct larger statistical studies, by extracting multiple snapshots of the same objects with a sufficiently large time separation to consider them as dynamically independent clusters (see Section 2.2). This resulted in a total sample of 68 clusters. Second, we improved the iterative small-scale filtering techniques used in Vazza et al. (2018), by linking the tolerance parameter in our multiscale iterative analysis of turbulence to the expected increase of velocity with scale, following Kolmogorov theory (Section 2.3.1).

We thus extracted the 3D distribution of turbulent velocities from which we computed the non-thermal contribution of pressure, α_{Turb} , as a function of cluster-centric distance. We also compared this definition of turbulence using different filtering technique, specifically to the one proposed in Nelson et al. (2014a), we defined as α_{Tot} .

To compare to observations, we also computed the hydrostatic mass bias, defined via the parameter α_{HS} , and we studied the possible factors leading to a mismatch with the corresponding α_{Turb} or α_{Tot} measured for the same systems.

Our main results can be summarized as follows:

(i) We derived fitting formula for the radial profiles of α_{Turb} and of α_{Tot} (equation 11). Such fitting formulae reproduce the data of our simulations, both for the complete sample and for the different subsamples that we studied. We found that the three free parameters of our fitting model can be easily related to the physics of the ICM (see Section 3.1 for a detailed explanation and the necessary bibliographic references).

(ii) The average non-thermal pressure support in our sample is in agreement with the recent X-ray observational campaign by Eckert et al. (2019), both at $r_{500,c}$ and $r_{200,c}$, albeit with a large scatter that is probably due to a larger variety of simulated dynamical

states, compared to the X-COP sample used by Eckert et al. (2019) (Fig. 11). Different choices in filtering generate very different non-thermal pressure support (see Vazza et al. 2018), and we show that the other filtering technique for turbulence yields values of non-thermal pressure support that are ~ 2 – 3 times larger. Our analysis of subsamples in mass, redshift, and sparsity subsamples, do not evidence particular trends. Despite having a different selection bias for clusters, the comparison between the non-thermal pressure support obtained by Eckert et al. (2019) yields rather similar results.

(iii) The two approaches do not differ much in the centre of clusters, and when applied to our cluster sample the median central value of the non-thermal pressure support is well in line with the most recent estimates from the centre of the Perseus cluster, i.e. ~ 2 – 6 per cent (Hitomi Collaboration et al. 2018). This result is in agreement with recent results by Lau et al. (2017) and Bourne & Sijacki (2017), who also highlighted the plausible impact of ‘cosmic weather’ driven by cluster dynamics, such as mergers and/or gas sloshing, in contributing to the budget of turbulent motions on the small scales of cluster cores.

(iv) Following on Eckert et al. (2019), we computed α_{HS} for our objects, defined as in equation (17). When averaged over the sample, the median α_{HS} is not far from the values obtained by X-ray observations, i.e. $\alpha_{\text{HS}} \sim 10$ – 20 per cent at $r_{500,c}$ and $r_{200,c}$, albeit with a large scatter. The hydrostatic mass bias does not show strong dependences on the cluster mass or the cluster dynamical status (see Section 3.1 and Section 4 for details).

(v) We compared the values of α_{Turb} , α_{Tot} , and α_{HS} at different radii both for the median of our sample (see Fig. 12) and for single objects (Fig. 14). In general, we found no strong correlation between these parameters in the latter case, whereas we find a strong correlation when the median values of the sample are considered.

(vi) We studied the ratio between α_{Turb} and α_{Tot} against α_{HS} , finding that (i) there is a minimal contribution from α_{Turb} to α_{Tot} of about 50 per cent at every radius; (ii) when $\alpha_{\text{HS}} \geq 0.2$, at large radii,

half of the hydrostatic mass bias is due to kinetic energy components that are not purely turbulent, with an increasing contribution by bulk or large-scale flows. These results do not depend on the mass, redshift, and sparsity of the halo (see Section 3.2).

(vii) Finally, we assess the contribution of radial accelerations studying the ratio between α_ξ and α_{Tot} against α_{HS} (see Section 4 and the bibliographic references therein). This contribution spans from 40 per cent to 15 per cent, from cluster's core to the outskirts. We conclude that the sum of the contributions given by turbulence and radial accelerations could completely explain the observed hydrostatic bias in the innermost regions of the clusters, but far from the centre, the combination of turbulence and radial accelerations' terms reaches ~ 70 per cent (see Fig. 16).

In summary, we find that a well-defined correlation between turbulence and hydrostatic bias emerges from the average properties of a sample of clusters. On the other hand, if we focus on single objects, the internal dynamics of each cluster makes it impossible to find a simple relation between the level of turbulence and its hydrostatic bias.

This irreducible bias stems from episodic radial acceleration terms, related to merger activity (Appendix C), confirming earlier results (Nelson et al. 2014a; Biffi et al. 2016). Shocks and, more generally, non-thermal phenomena observed in the radio band are expected to trace important out-of-equilibrium conditions in the ICM (Brunetti & Jones 2014; van Weeren et al. 2019).

In this respect, future observations, e.g. with LOFAR and SKA, may be able to provide important clues to the presence of significant non-thermal pressure in dynamically disturbed systems. Thanks to numerical simulations, such out-of-equilibrium conditions may be linked to the presence of turbulent motions, as observations have also begun to establish the quantitative link between observed radio power in radio haloes to the turbulent energy budget of the ICM, inferred from the amount of fluctuations in X-ray surface brightness (e.g. Eckert et al. 2017b). This will be key for the cosmological use of galaxy clusters in future X-ray surveys (e.g. with eRosita, see Zandanel et al. 2018). Furthermore, future pointed exposures of the ICM in X-rays will enable the calibration of $\alpha_{\text{HS}}-\alpha$ by measuring the level of gas turbulence with the next generation of instruments having high spectral resolution capabilities (e.g. XRISM/Resolve - see Ishisaki et al. 2018 and scientific applications in Kitayama et al. 2014- and Athena/X-IFU - see description in Barret et al. 2018, and discussion of some scientific cases related to the one presented here in Roncarelli et al. 2018, Vazza et al. 2019, Clerc et al. 2019, Cucchetti et al. 2019).

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APPENDIX A: TESTING THE RELATION BETWEEN FILTERING SCALE AND NON-THERMAL PRESSURE

As detailed in the main text (Section 2.3.1), our iterative scheme to measure the local turbulent velocity field requires to predict the

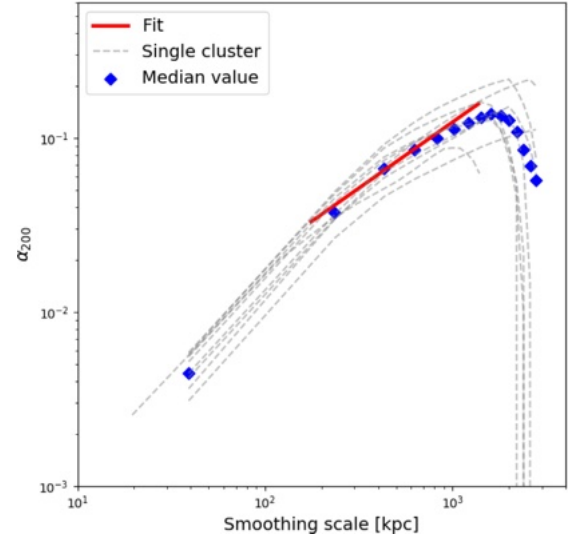


Figure A1. Relation between smoothing scales and α_{200} for the sample of clusters at $z = 0$. The blue points represent the median values of α_{200} at different smoothing scales for the used sample of clusters. The solid red line gives the power-law fit obtained explained in Section 2.3.1.

increase of the local rms velocity as a function of the smoothing scale, w , i.e. $\delta v^2 \propto w^f$. In Kolmogorov theory such exponent should be $f = 2/3$, yet we tested to what extent the standard Kolmogorov theory of turbulence applies to our data, and studied the relation between the value of α measured at the reference radius of $r_{200,c}$ (α_{200}) as a function of different fixed smoothing scale. If we apply the standard relation between rms velocity and turbulent scale (e.g. $\sigma^2 \propto L^{\frac{2}{3}}$) in the stationary subsonic turbulent regime described by Kolmogorov theory, we expect that the relation should approximately follow

$$\alpha_{200} = a \times w^f, \quad (\text{A1})$$

where w is the value of smoothing scale in physical quantities and a and f are the parameters obtained from Kolmogorov's theory (Kolmogorov 1941). The expected value for f is close to $\frac{2}{3}$ for stationary and subsonic turbulence. However, the ICM is not such an idealized environment because of density stratification, self-gravity, and non-stationary flow patterns, which can lead to deviations from $2/3$. Fig. A1 shows the pressure ratio, α_{200} , versus the smoothing scale computed of our set of clusters at $z = 0$, after computing the local turbulent velocity field for increasing smoothing scales, w . The trend is measured to be very similar across our sample, and can be fitted by a unique power law.

We fit the data to equation (A1) and obtain $a \simeq 6 \times 10^{-3}$ and $f \simeq 0.77$, which is the fiducial value we adopted to stop the iterations in our method in the main paper, as in equation (4). The value for f is reasonably close to $2/3$ and is consistent with the fact that the power spectra of the velocity field in simulated galaxy clusters are typically steeper than Kolmogorov's slope because of the stratified cluster atmosphere (Vazza et al. 2011). Only the scales below ~ 100 kpc show hints of a steepening, which may partially be ascribed to numerical dissipation in the PPM scheme, which is expected to dampen the velocities on scales close to a few times the spatial resolution (e.g. Porter & Woodward 1994). For scales larger than ~ 8 times the numerical resolution (≥ 200 kpc), these effects do not occur and the relation between α and the smoothing scale is well fitted by Kolmogorov's spectrum. Since a number of physical

and numerical effects may affect the dynamics of the turbulent flow on $<100\text{--}200$ kpc, with these simulations it is hard to tell the different effects apart. In the following, we focus mostly on the dynamics of turbulence on scales >100 kpc, which are also the ones that dominate the non-thermal pressure support. On scales greater than ~ 1 Mpc, the spectra show a drop where the peak of Kolmogorov spectrum is reached. The exponent f in equation (A1) is calculated in the inertial range of Kolmogorov spectrum, from ~ 200 to ~ 800 kpc, so we can use this value for the multiscale adaptive filtering.

APPENDIX B: SUBSAMPLES ANALYSIS OF α RADIAL PROFILES

As described in Section 3.1, we adopt our model as the best-fitting function both for α_{Turb} and α_{Tot} . In Fig. B1, we have shown the

radial profiles of α and α_{HS} . Here, the profiles of α_{HS} are computed using a spectroscopic-like definition of the temperature profile. As already discussed in Section 3.1, the differences between a spectroscopic-like profile and a volume-weighted one are as small that they allow us to use either of the two profiles. The subsamples used in this appendix are built to have the same number of objects in all the bins. The values that allow us this selection are shown in Table B1.

Both from Fig. B1 and Table B1, we conclude that our fitting formula well reproduces the radial behaviour of α_{Turb} and α_{Tot} at any subsamples. For α_{Turb} , we observe a slight decrease at any radii with an increase of mass or a decrease of redshift. However, no other strong dependencies are observed between the radial profiles and the quantities used for the selection. We notice also that α_{Turb} shows the lowest scatter at any radii, while both $\alpha_{\text{HS,Turb}}$ and $\alpha_{\text{HS,Tot}}$ are affected by high scatters.

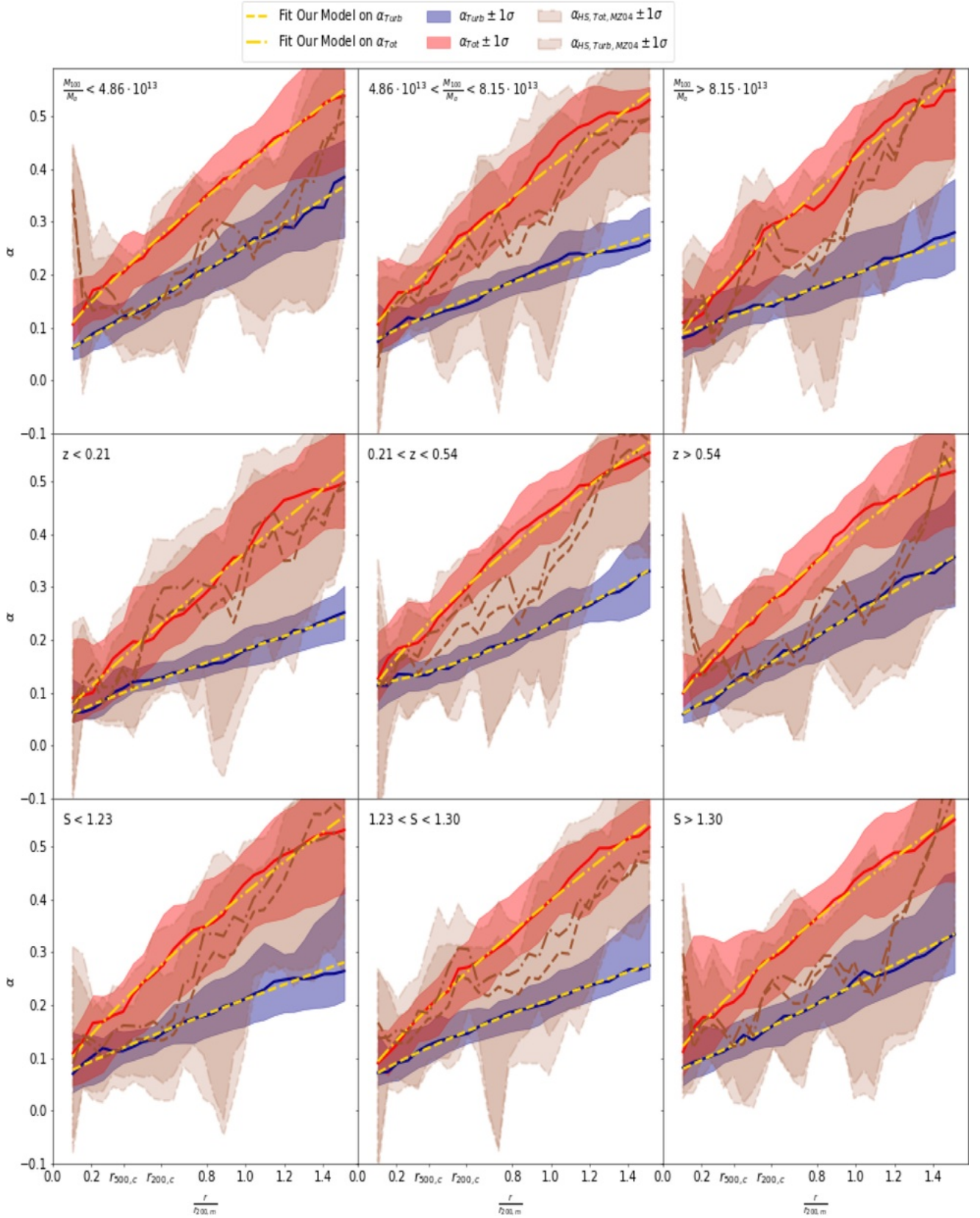


Figure B1. Radial profile of median value of α_{Turb} (blue solid line) and α_{Tot} (red solid line) for different bins of mass (top panels), redshift (central panels), and sparsity (bottom panels). The yellow dashed lines are the fits of our model on α_{Turb} profile, while the dash-dotted ones are the fits of the model on the α_{Tot} profile. The brown dashed and dash-dotted lines are the profile of median $\alpha_{\text{HS,Turb}}$ and $\alpha_{\text{HS,Tot}}$ computed as described in Section 3.1. The shadowed regions represent the 1σ distribution of the subsample.

Table B1. Parameters and values of χ^2 statistical test for our model applied to mass, redshift, and mass sparsity subsamples of our data. The errors on the parameters are the values at 3σ confidence.

Sample			a_0	a_1	a_2	χ^2
Mass	$M_{100}/M_\odot < 4.86 * 10^{13}$	α_{Turb}	$(2.100 \pm 0.005) * 10^{-1}$	1.041 ± 0.003	$(0.430 \pm 0.003) * 10^{-1}$	0.010
		α_{Tot}	0.351 ± 0.001	0.825 ± 0.004	0.054 ± 0.001	0.008
		α_{Turb}	$(1.582 \pm 0.001) * 10^{-1}$	0.815 ± 0.002	$(0.532 \pm 0.001) * 10^{-1}$	0.034
	$4.86 * 10^{13} < M_{100}/M_\odot < 8.15 * 10^{13}$	α_{Tot}	$(3.467 \pm 0.003) * 10^{-1}$	0.821 ± 0.001	$(0.589 \pm 0.001) * 10^{-1}$	0.035
		α_{Turb}	$(1.261 \pm 0.004) * 10^{-1}$	1.003 ± 0.007	$(0.755 \pm 0.005) * 10^{-1}$	0.014
		α_{Tot}	0.395 ± 0.001	0.786 ± 0.004	0.027 ± 0.001	0.036
Redshift	$M_{100}/M_\odot > 8.15 * 10^{13}$	α_{Turb}	$(1.398 \pm 0.001) * 10^{-1}$	0.884 ± 0.001	$(0.424 \pm 0.001) * 10^{-1}$	0.024
		α_{Tot}	$(3.271 \pm 0.005) * 10^{-1}$	0.929 ± 0.004	$(0.386 \pm 0.003) * 10^{-1}$	0.030
		α_{Turb}	$(1.186 \pm 0.001) * 10^{-1}$	1.488 ± 0.002	$(1.130 \pm 0.001) * 10^{-1}$	0.023
	$0.21 < z < 0.54$	α_{Tot}	$(3.875 \pm 0.008) * 10^{-1}$	0.743 ± 0.002	$(0.474 \pm 0.008) * 10^{-1}$	0.040
		α_{Turb}	$(2.113 \pm 0.003) * 10^{-1}$	0.998 ± 0.004	$(0.380 \pm 0.004) * 10^{-1}$	0.012
		α_{Tot}	0.373 ± 0.001	0.769 ± 0.004	0.034 ± 0.001	0.027
Sparsity	$z < 0.21$	α_{Turb}	$(1.537 \pm 0.003) * 10^{-1}$	0.903 ± 0.004	$(0.573 \pm 0.003) * 10^{-1}$	0.023
		α_{Tot}	$(3.730 \pm 0.006) * 10^{-1}$	0.793 ± 0.002	$(0.392 \pm 0.001) * 10^{-1}$	0.019
		α_{Turb}	$(1.674 \pm 0.002) * 10^{-1}$	0.791 ± 0.002	$(0.435 \pm 0.003) * 10^{-1}$	0.012
	$1.23 < s < 1.30$	α_{Tot}	$(3.587 \pm 0.003) * 10^{-1}$	0.836 ± 0.001	$(0.390 \pm 0.003) * 10^{-1}$	0.023
		α_{Turb}	$(1.761 \pm 0.003) * 10^{-1}$	1.046 ± 0.005	$(0.629 \pm 0.004) * 10^{-1}$	0.014
		α_{Tot}	$(0.361 \pm 0.002) * 10^{-1}$	0.785 ± 0.006	0.061 ± 0.002	0.014

APPENDIX C: ON THE RELATION BETWEEN HYDROSTATIC BIAS AND RADIAL ACCELERATION

The presence of shocks in the ICM is important for their dynamical equilibrium, since passage of a shock provides a thrust, usually in the outward direction. This effect generates a radial acceleration of the gas that could affect the computation of the hydrostatic mass, mimicking an excess of thermal pressure if the hydrostatic equilibrium is (wrongly) imposed on the structure (Nelson et al. 2014b).

As written in Section 4, we apply the same formalism presented in Biffi et al. (2016) on our clusters. We quantify the amount of departure from the hydrostatic equilibrium in each shell through the median value of ξ_r within the shell, ξ . As an example, in Fig. C1 we show the central slice of Mach number, which allows us to identify shocks sweeping the cluster volume at a given epoch. In left-hand panel, we can see a wide $\mathcal{M} \approx 3$ shock in the inner part of cluster IT90.0 at the epoch of $z \simeq 0.15$, while in right slight through cluster IT92.0 at $z \simeq 0.07$; there are no relevant shocks inside $r_{200,c}$. We can therefore expect in the first case a stronger departure from equilibrium, following the gasdynamical acceleration downstream of the shock wave. These trends are well captured in Fig. C2, which gives the radial behaviour of total mass (blue solid line), hydrostatic mass (red solid line), and $\mathcal{M}_w$ (green solid line). In the bottom panels of Fig. C2, we also show the radial profiles of α_{HS} and of the radial acceleration term.

From there, we can quantify how shocks in the inner parts of the cluster influence the hydrostatic mass. There is a strong correlation between the maximum values of the Mach number and a *negative* hydrostatic mass bias, meaning that the total mass that would be inferred through a standard hydrostatic equilibrium analysis would be larger than the total (true) mass, as shown by the radial trend of α_{HS} . These behaviours are also observed for the more relaxed cluster in the right-hand panel, but only in the regions close to $r_{200,c}$, where a shock front is visible in the right-hand panel of Fig. C1. Therefore, shocks introduce an additional term that one must consider when inferring non-thermal pressure from the hydrostatic mass bias. We remark that such behaviours in the radial profile would hardly be detected in realistic X-ray analysis of observed clusters, because observations are usually fitted through a (smooth) Navarro–Frank–White profile, which cannot produce such a sharp increase in the hydrostatic mass profile.

Thanks to the analysis of radial acceleration terms, we used ξ as correcting factor of hydrostatic bias. We compared the α terms with the sum of α_{HS} plus ξ . The goal of this comparison is to obtain a closer relation between the turbulent proxy α and the hydrostatic bias counterpart α_{HS} . The results are shown in Fig. C3.

From the comparison between Figs C3 and 14, we notice that the negative terms of hydrostatic bias are not present anymore. However, we do not find a strong correlation between turbulence and hydrostatic bias yet.

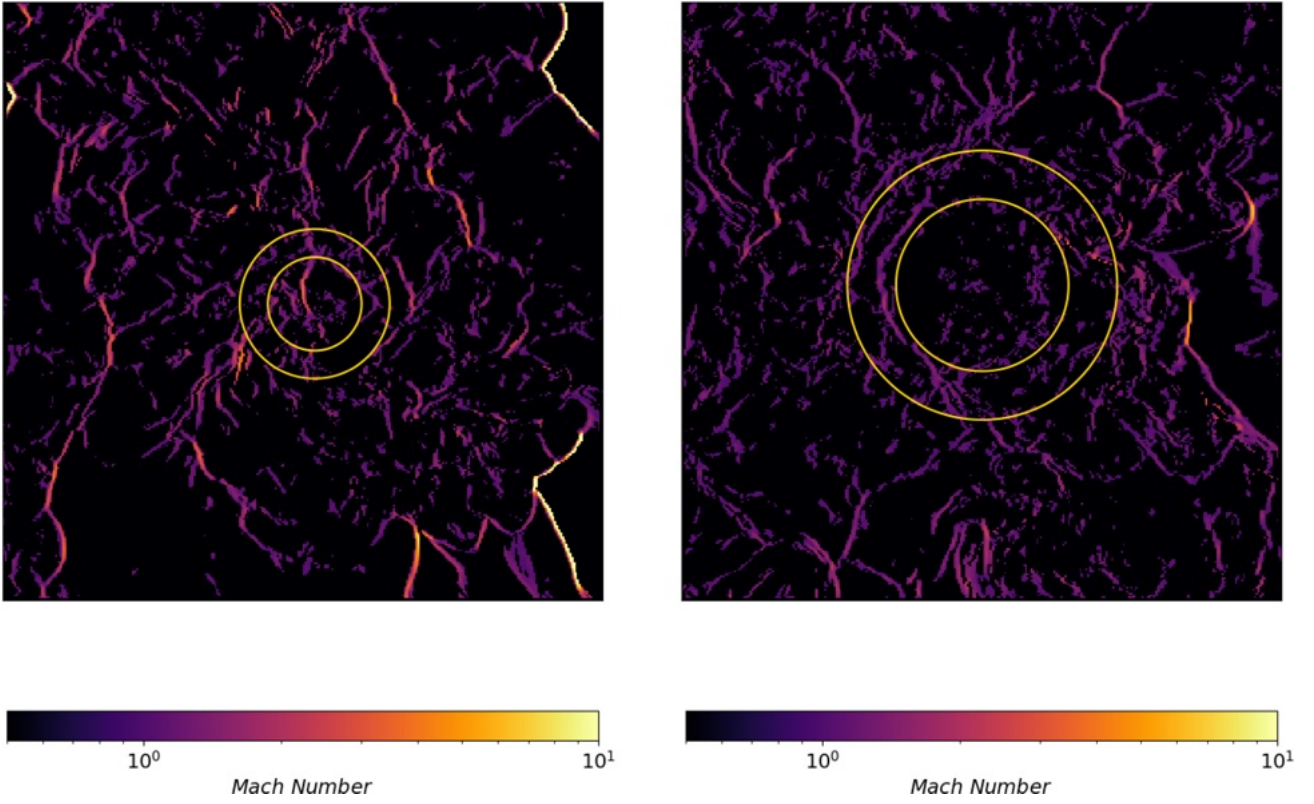


Figure C1. Maps of shock Mach number in a slice through the centre for cluster IT90_0 at $z \simeq 0.15$ (left-hand panel), and through the centre of IT92_0 at $z \simeq 0.07$ (right-hand panel). The inner circle shows the location of $r_{500,c}$, while the outer one shows $r_{200,c}$.

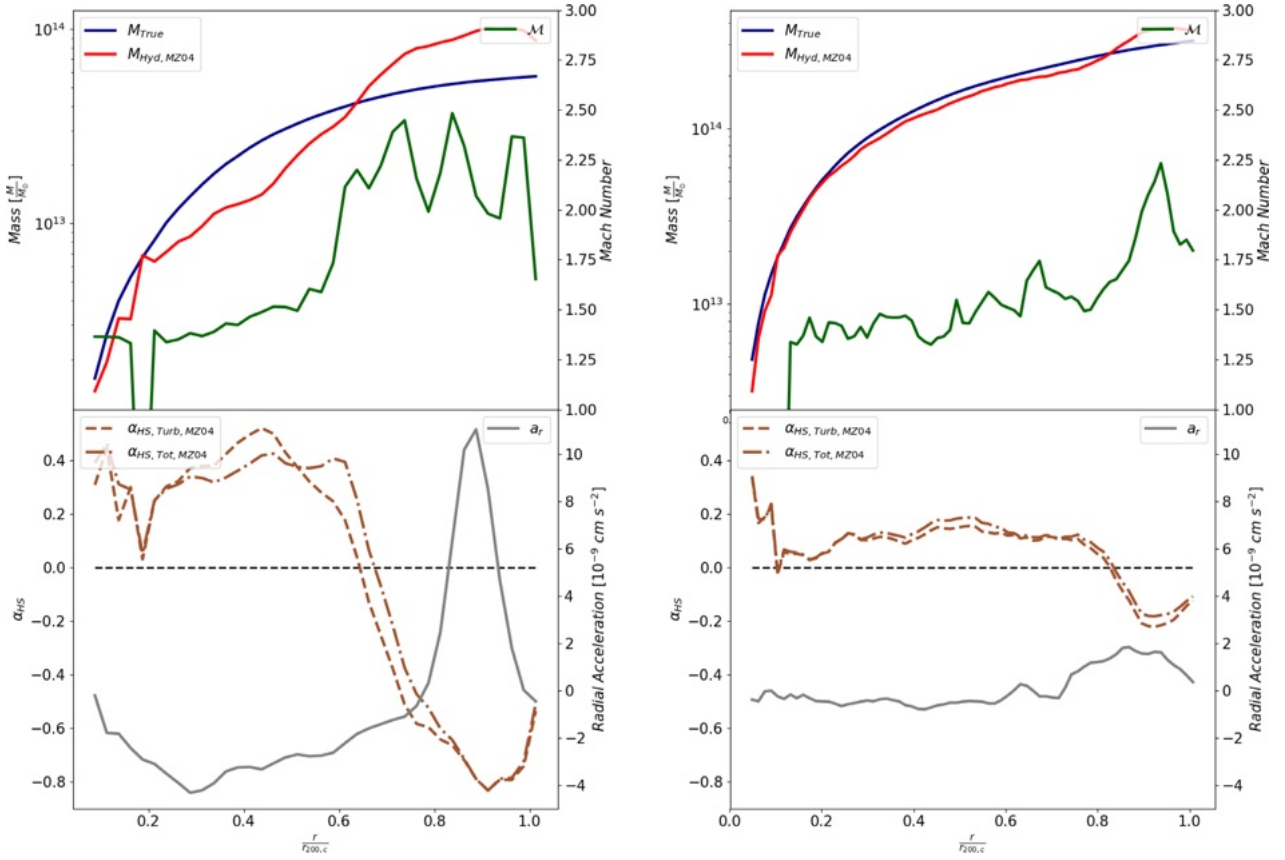


Figure C2. Total mass profile (blue solid line), hydrostatic mass profile (red solid line), and median Mach number profile (green solid line) in the top panel, and radial acceleration (blue solid line) and $\alpha_{HS, Turb}$ (brown dashed line) and $\alpha_{HS, Tot}$ profiles (brown dash-dotted line) in the bottom panel, for IT90.0 at $z \simeq 0.15$ (left-hand panel) and IT92.0 at $z \simeq 0.07$ (right-hand panel).

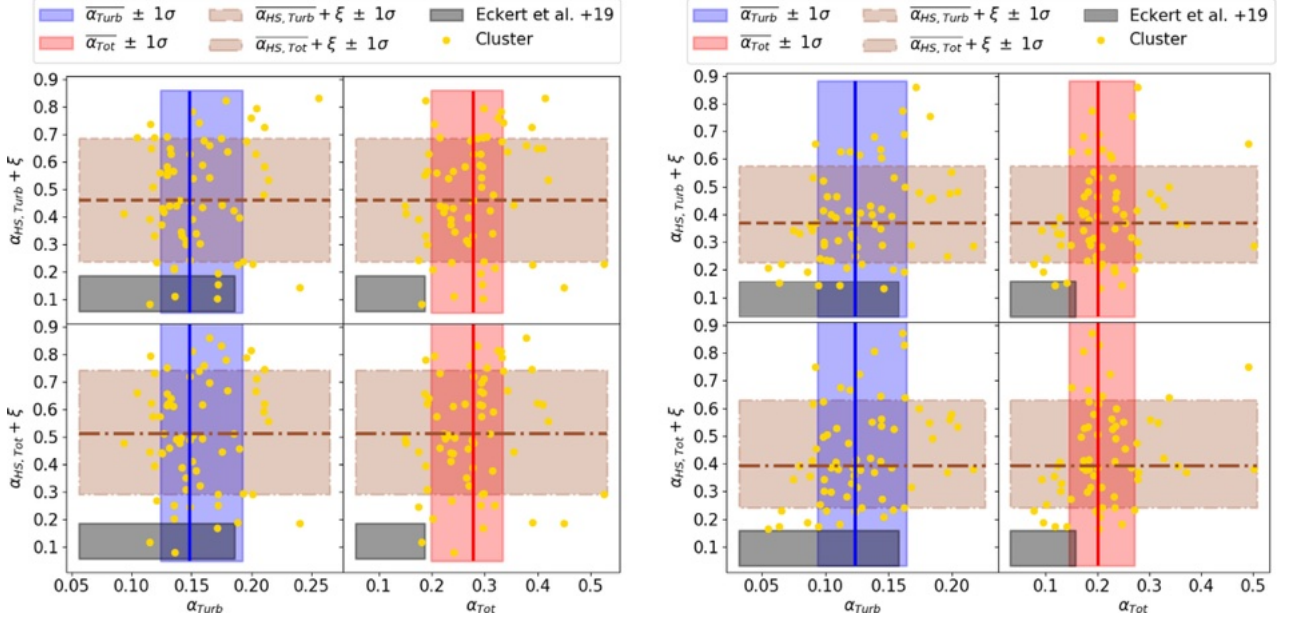


Figure C3. Comparison between median α_{Turb} (blue solid line) or α_{Tot} (red solid line) and $\alpha_{\text{HS,Turb}}$ (brown dashed line) or $\alpha_{\text{HS,Tot}}$ (brown dash-dotted lines) corrected for the radial acceleration term ξ , at $r_{200,c}$ (left-hand panels) and $r_{500,c}$ (right-hand panels). The shadowed regions represented 1σ variance. The black shadow regions represented the range values inferred with X-ray observations by Eckert et al. (2019), while the yellow dots refer to single clusters.

This paper has been typeset from a $\text{\LaTeX}$ file prepared by the author.